HYCON 紘康科技

HY11P42
Datasheet

8-Bit RISC-like Mixed Signal Microcontroller
Embedded 18-Bit ΣΔADC

Table of Contents

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1. Features

- 8-bit RISC, 66 instructions included.
- Operating voltage range: 2.2V to 3.6V, operation temperature range: -40℃~85℃.
- External Crystal Oscillator and Internal High Precision RC Oscillator, 6 CPU clock rates enable users to have the most power-saving plan.
  - Active Mode 300uA@2MHz
  - Standby Mode 3uA@28KHz
  - Sleep Mode 1uA
- 2K Word OTP (One Time Programmable) Type program memory, 128 Byte Data Memory.
- Brownout detector and Watch dog Timer, prevents CPU from Crash.
- 18-bit fully differential input Sigma-Delta Analog-to-Digital Converter (A/D)
  - Built-in PGA (Programmable Gain Amplifier) 1/4x、1/2x、1x. …128x，10 input signal gain selection.
  - Built-in Input zero point adjustment can increase measurement range according to different application.
  - Built-in high impedance input buffer (Not suitable for 4x or upwards input gain).
  - Built-in absolute temperature sensor
- 1.0V and 1.2V internal analog circuit common ground that equips with Push-Pull drive ability to provide sensor driving voltage.
- LVD low voltage detection function has 14 steps of voltage detection configuration and external input voltage detection function.
- VDDA can select 4 different output voltages that equip with 10mA low dropout regulator function.
- 8-bit Timer A
- 8-bit Timer C module can generate PWM/PFD waveform.
- EUART module.
- Built-In EPROM (BIE)
- Support 6 stack level

2. Pin Definition

2.1 SSOP28 Pin Diagram

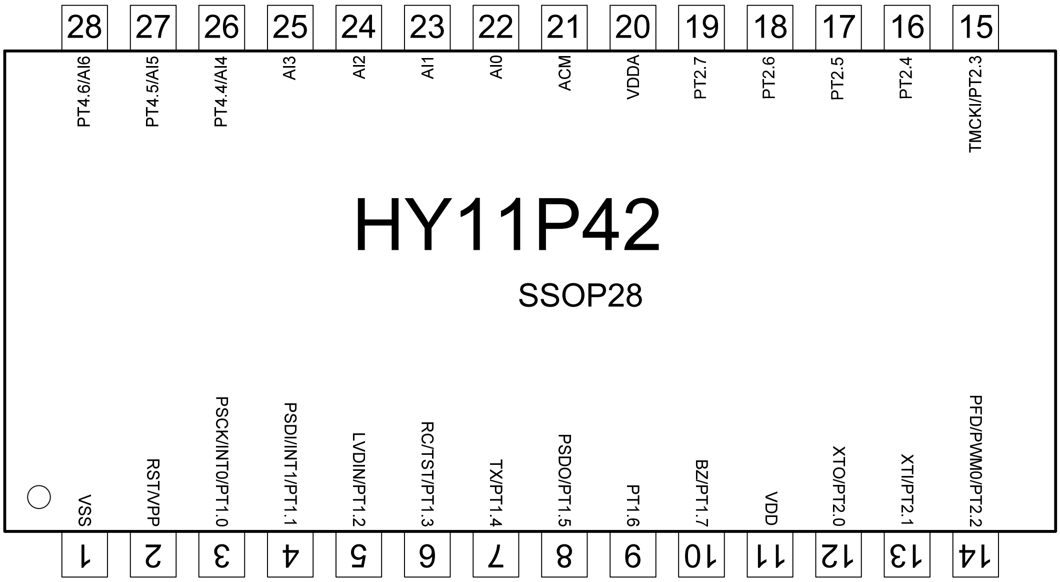

Figure 2-1 HY11P42 SSOP28 Pin Diagram

2.2 TSSOP28 Pin Diagram

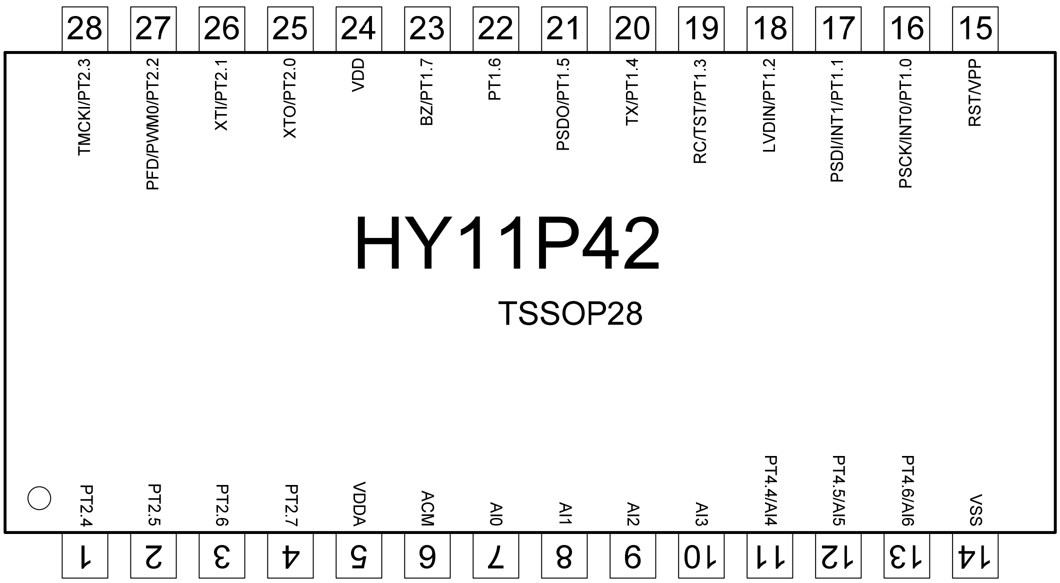

Figure 2-2 HY11P42 TSSOP28 Pin Diagram

Note 1：VPP and RST use the same pin. Input voltage cannot exceed 5.8V when not programming EPROM.

Note 2：TST and PT1.3 use the same pin. Input voltage cannot exceed Vdd+0.3V while operating.

Note 3：If PT1.3 is not configured as external button pin, the anti-interference ability will be enhanced.

2.3 QFN24 Pin Diagram

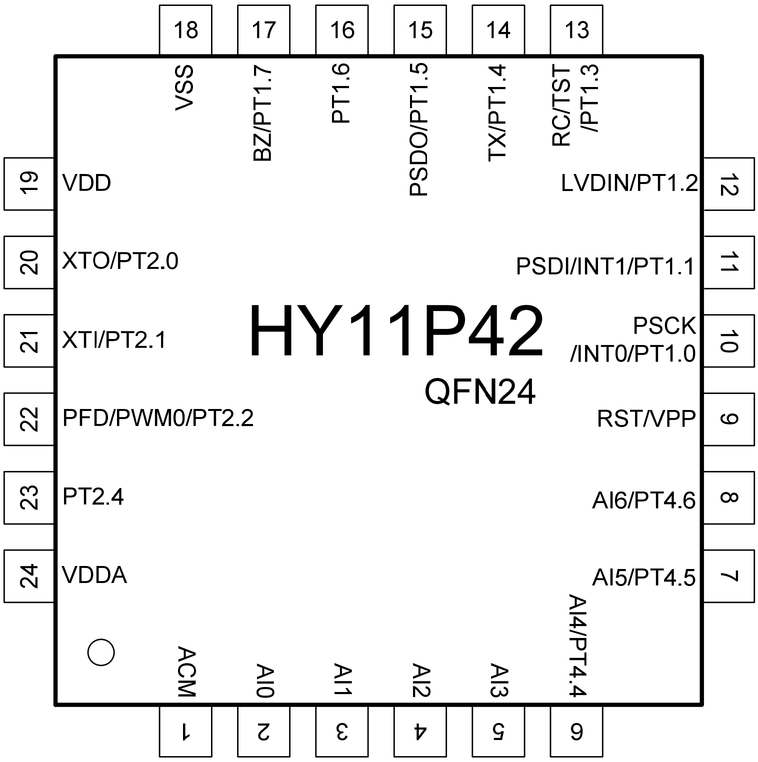

Figure 2-3 HY11P42 N-QFN24 Pin Diagram

Note 1：VPP and RST use the same pin. Input voltage cannot exceed 5.8V when not programming EPROM.

Note 2：TST and PT1.3 use the same pin. Input voltage cannot exceed Vdd+0.3V while operating.

Note 3：If PT1.3 is not configured as external button pin, the anti-interference ability will be enhanced.

2.4 SSOP28 Pinout I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name	Pin characteristic: Pin Type	Pin characteristic: Buffer Type	Description
1	VSS	P	P	Grounding pin for IC operation voltage
2	RST/VPP			
	RST	I	S	Reset IC
	VPP	P	P	EPROM programming voltage input
3	PT1.0/INT0/PSCK			
	PT1.0	I	S	Digital input
	INT0	I	S	Interrupt input INT0
	PSCK	I	S	OTP programming interface SCK
4	PT1.1/INT1/PSDI			
	PT1.1	I	S	Digital input
	INT1	I	S	Interrupt input INT1
	PSDI	I	S	OTP programming interface SDI
5	PT1.2/LVDIN			
	PT1.2	I	S	Digital input
	LVDIN	A	A	LVD external signal input port
6	PT1.3/TST/RC			
	PT1.3	I	S	Digital input
	RC	I/O	S	EUART communication interface RC
	TST	I	S	Test Mode input pin (invalid)
7	PT1.4/TX			
	PT1.4	I/O	S	Digital I/O
	TX	I/O	S	EUART communication interface TX
8	PT1.5/PSDO			
	PT1.5	I/O	S	Digital I/O
	PSDO	I/O	C	OTP programming interface SDO
9	PT1.6			
	PT1.6	I/O	S	Digital I/O
10	PT1.7/BZ			
	PT1.7	I/O	S	Digital I/O
	BZ	O	C	Buzzer output
11	VDD	P	P	Power source for IC operation
12	PT2.0/XTO			
	PT2.0	I/O	S	Digital I/O

	XTO	A	A	External oscillator output
13	PT2.1/XTI PT2.1 XTI	 I/O A	 S A	 Digital I/O External oscillator input
14	PT2.2/PWM0/PFD PT2.2 PWM0 PFD	 I/O O O	 C C C	 Digital I/O PWM output port PFD output port
15	PT2.3/TMCKI PT2.3 TMCKI	 I/O I	 S S	 Digital I/O TIMERC clock source input port
16	PT2.4	I/O	S	Digital I/O
17	PT2.5	I/O	S	Digital I/O
18	PT2.6	I/O	C	Digital I/O
19	PT2.7	I/O	C	Digital I/O
20	VDDA	P	P	Regulator output Analog circuit voltage source
21	ACM	P	P	Internal analog circuit grounding pin
22	AI0	A	A	Analog input channel
23	AI1	A	A	Analog input channel
24	AI2	A	A	Analog input channel
25	AI3	A	A	Analog input channel
26	PT4.4/AI4 PT4.4 AI4	 I A	 C A	 Digital input Analog input channel
27	PT4.5/AI5 PT4.5 AI5	 I A	 C A	 Digital input Analog input channel
28	PT4.6/AI6 PT4.6 AI6	 I A	 C A	 Digital input Analog input channel

Table 2-1 Pin Definition and Function Description

2.5 TSSOP28 Pin out I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name		Pin Characteristic		Description
			Pin Type	Buffer Type	
1	PT2.4		I/O	S	Digital I/O
2	PT2.5		I/O	S	Digital I/O
3	PT2.6		I/O	C	Digital I/O
4	PT2.7		I/O	C	Digital I/O
5	VDDA		P	P	Regulator output Analog circuit voltage source
6	ACM		P	P	Internal analog circuit grounding pin
7	AI0		A	A	Analog input channel
8	AI1		A	A	Analog input channel
9	AI2		A	A	Analog input channel
10	AI3		A	A	Analog input channel
11	PT4.4/AI4				
		PT4.4	I	C	Digital input
		AI4	A	A	Analog input channel
12	PT4.5/AI5				
		PT4.5	I	C	Digital input
		AI5	A	A	Analog input channel
13	PT4.6/AI6				
		PT4.6	I	C	Digital input
		AI6	A	A	Analog input channel
14	VSS		P	P	Grounding pin for IC operation voltage
15	RST/VPP				
		RST	I	S	Reset IC
		VPP	P	P	EPROM programming voltage input
16	PT1.0/INT0/PSCK				
		PT1.0	I	S	Digital input
		INT0	I	S	Interrupt input INT0
		PSCK	I	S	OTP programming interface SCK
17	PT1.1/INT1/PSDI				
		PT1.1	I	S	Digital input
		INT1	I	S	Interrupt input INT1
		PSDI	I	S	OTP programming interface SDI
18	PT1.2/LVDIN				

	PT1.2	I	S	Digital input
	LVDIN	A	A	LVD external signal input port
19	PT1.3/TST/RC			
	PT1.3	I	S	Digital input
	RC	I/O	S	EUART communication interface RC
	TST	I	S	Test Mode input pin (invalid)
20	PT1.4/TX			
	PT1.4	I/O	S	Digital I/O
	TX	I/O	S	EUART communication interface TX
21	PT1.5/PSDO			
	PT1.5	I/O	S	Digital I/O
	PSDO	I/O	C	OTP programming interface SDO
22	PT1.6			
	PT1.6	I/O	S	Digital I/O
23	PT1.7/BZ			
	PT1.7	I/O	S	Digital I/O
	BZ	O	C	Buzzer output
24	VDD	P	P	Power source for IC operation
25	PT2.0/XTO			
	PT2.0	I/O	S	Digital I/O
	XTO	A	A	External oscillator output
26	PT2.1/XTI			
	PT2.1	I/O	S	Digital I/O
	XTI	A	A	External oscillator input
27	PT2.2/PWM0/PFD			
	PT2.2	I/O	C	Digital I/O
	PWM0	O	C	PWM output port
	PFD	O	C	PFD output port
28	PT2.3/TMCKI			
	PT2.3	I/O	S	Digital I/O
	TMCKI	I	S	TIMERC clock source input port

Table 2-2 Pin Definition and Function Description

2.6 QFN24 Pin out I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name	Pin Characteristic		Description
		Pin Type	Buffer Type	
1	ACM	P	P	Internal analog circuit grounding pin
2	AI0	A	A	Analog input channel
3	AI1	A	A	Analog input channel
4	AI2	A	A	Analog input channel
5	AI3	A	A	Analog input channel
6	PT4.4/AI4			
	PT4.4	I	C	Digital input
	AI4	A	A	Analog input channel
7	PT4.5/AI5			
	PT4.5	I	C	Digital input
	AI5	A	A	Analog input channel
8	PT4.6/AI6			
	PT4.6	I	C	Digital input
	AI6	A	A	Analog input channel
9	RST/VPP			
	RST	I	S	Reset IC
	VPP	P	P	EPROM programming voltage input
10	PT1.0/INT0/PSCK			
	PT1.0	I	S	Digital input
	INT0	I	S	Interrupt input INT0
	PSCK	I	S	OTP programming interface SCK
11	PT1.1/INT1/PSDI			
	PT1.1	I	S	Digital input
	INT1	I	S	Interrupt input INT1
	PSDI	I	S	OTP programming interface SDI
12	PT1.2/LVDIN			
	PT1.2	I	S	Digital input
	LVDIN	A	A	LVDIN external signal input port
13	PT1.3/TST/RC			
	PT1.3	I	S	Digital input
	RC	I/O	S	EUART communication interface RC
	TST	I	S	Test Mode input pin (invalid)
14	PT1.4/TX			
	PT1.4	I/O	S	Digital I/O

	TX	I/O	S	EUART communication interface TX
15	PT1.5/PSDO PT1.5 PSDO	 I/O I/O	 S C	 Digital I/O OTP programming interface SDO
16	PT1.6 PT1.6	 I/O	 S	 Digital I/O
17	PT1.7/BZ PT1.7 BZ	 I/O O	 S C	 Digital I/O Buzzer output
18	VSS	P	P	Grounding pin for IC operation voltage
19	VDD	P	P	Power source for IC operation
20	PT2.0/XTO PT2.0 XTO	 I/O A	 S A	 Digital I/O External oscillator output
21	PT2.1/XTI PT2.1 XTI	 I/O A	 S A	 Digital I/O External oscillator input
22	PT2.2/PWM0/PFD PT2.2 PWM0 PFD	 I/O O O	 C C C	 Digital I/O PWM output port PFD output port
23	PT2.4	I/O	S	Digital I/O
24	VDDA	P	P	Regulator output Analog circuit voltage source

Table 2-3 Pin Definition and Function Description

3. Application Circuit

3.1 Bridge Sensor I

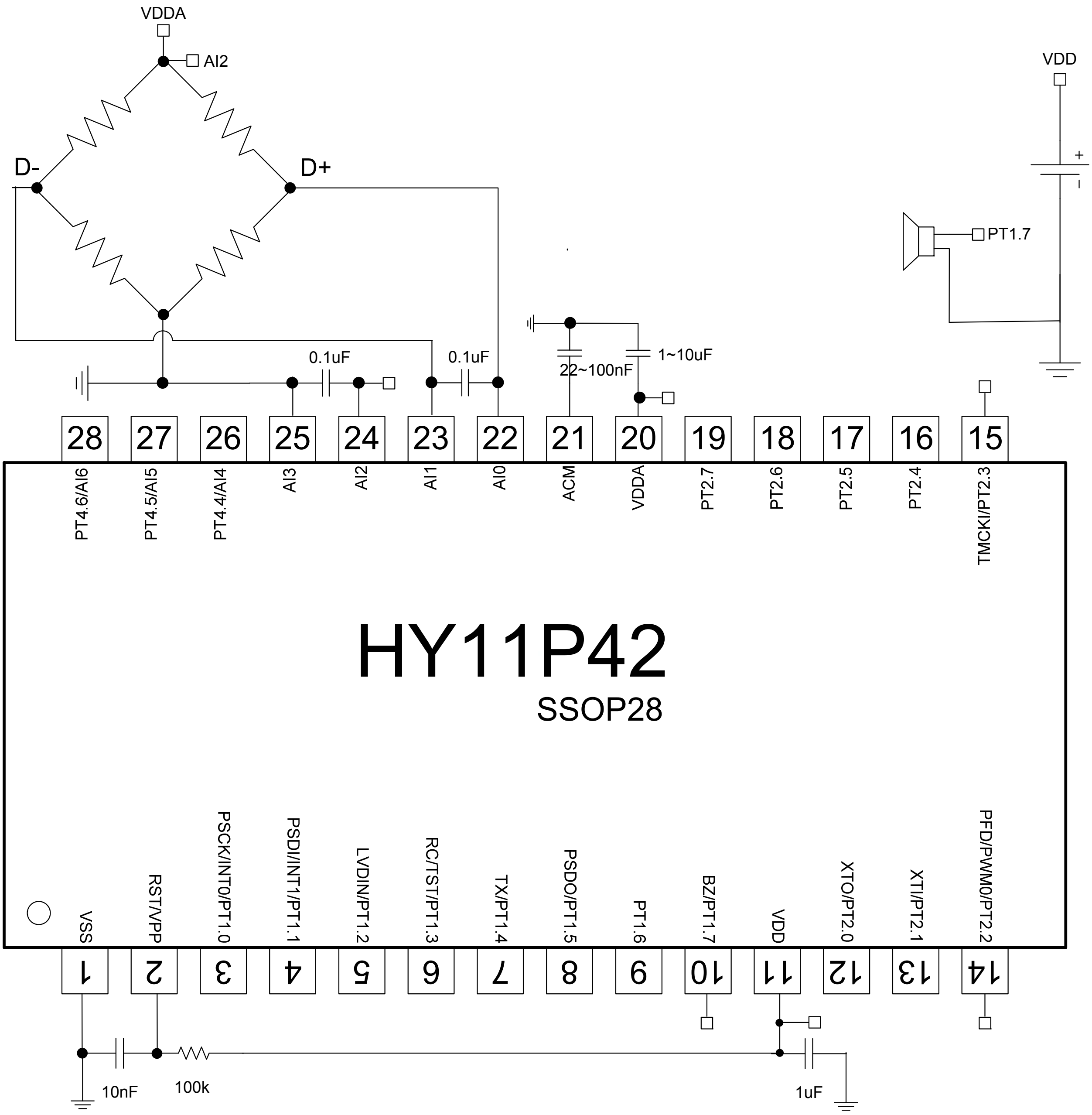

Figure 3-1 Application Circuit for Bridge Sensors

Note 1: DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

Note 2: BIE function can be used to save calibration parameters.

3.2 Bridge Sensor Ⅱ

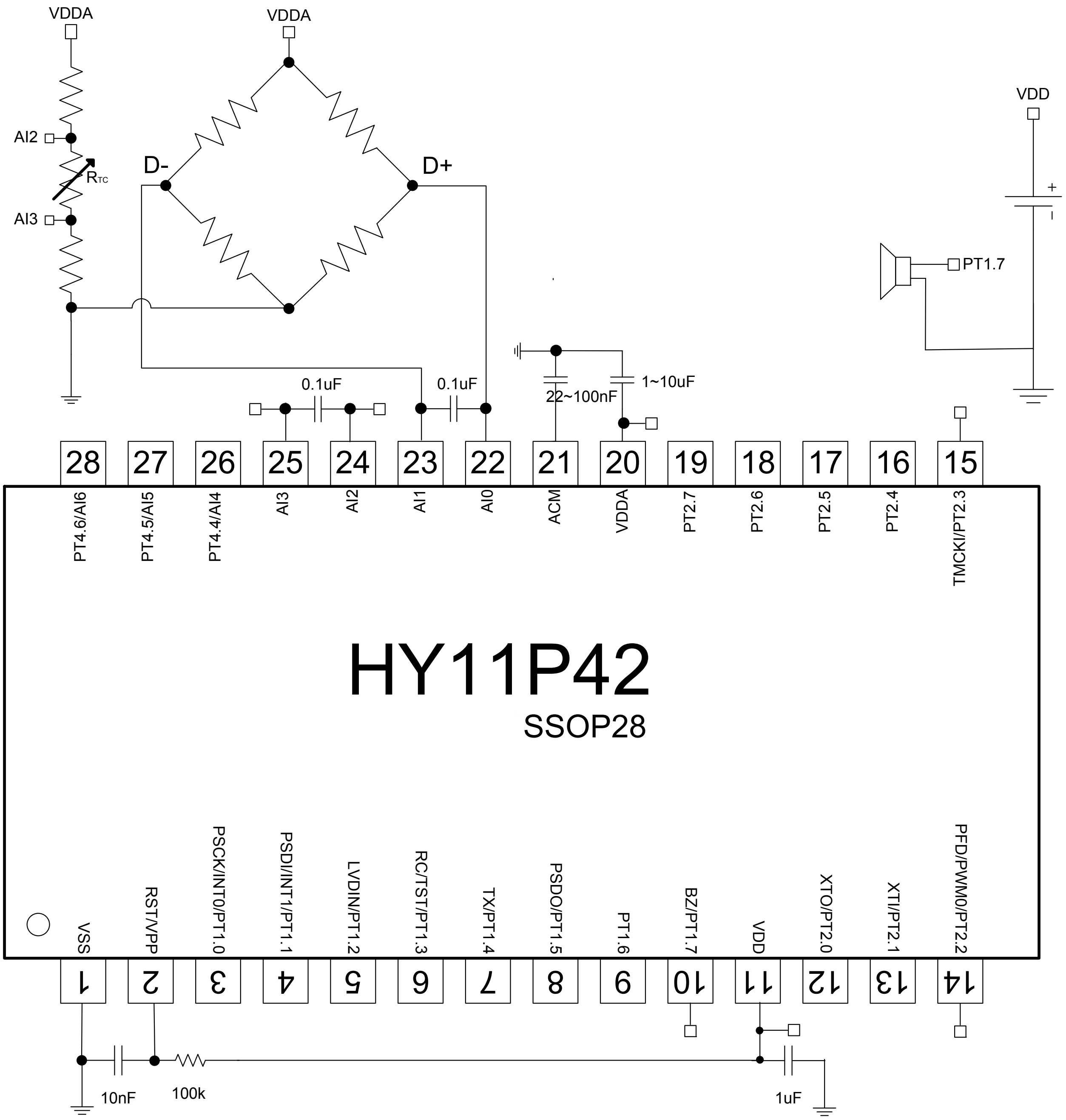

Figure 3-2 Application Circuit of Temperature Compensation Bridge Sensor

Note 1: Using external reference voltage to design temperature compensation resistor NTC basic circuit

Note 2: DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

Note 3: BIE function can be used to save calibration parameters.

3.3 4-20mA Two-Wire Current Panel Meter

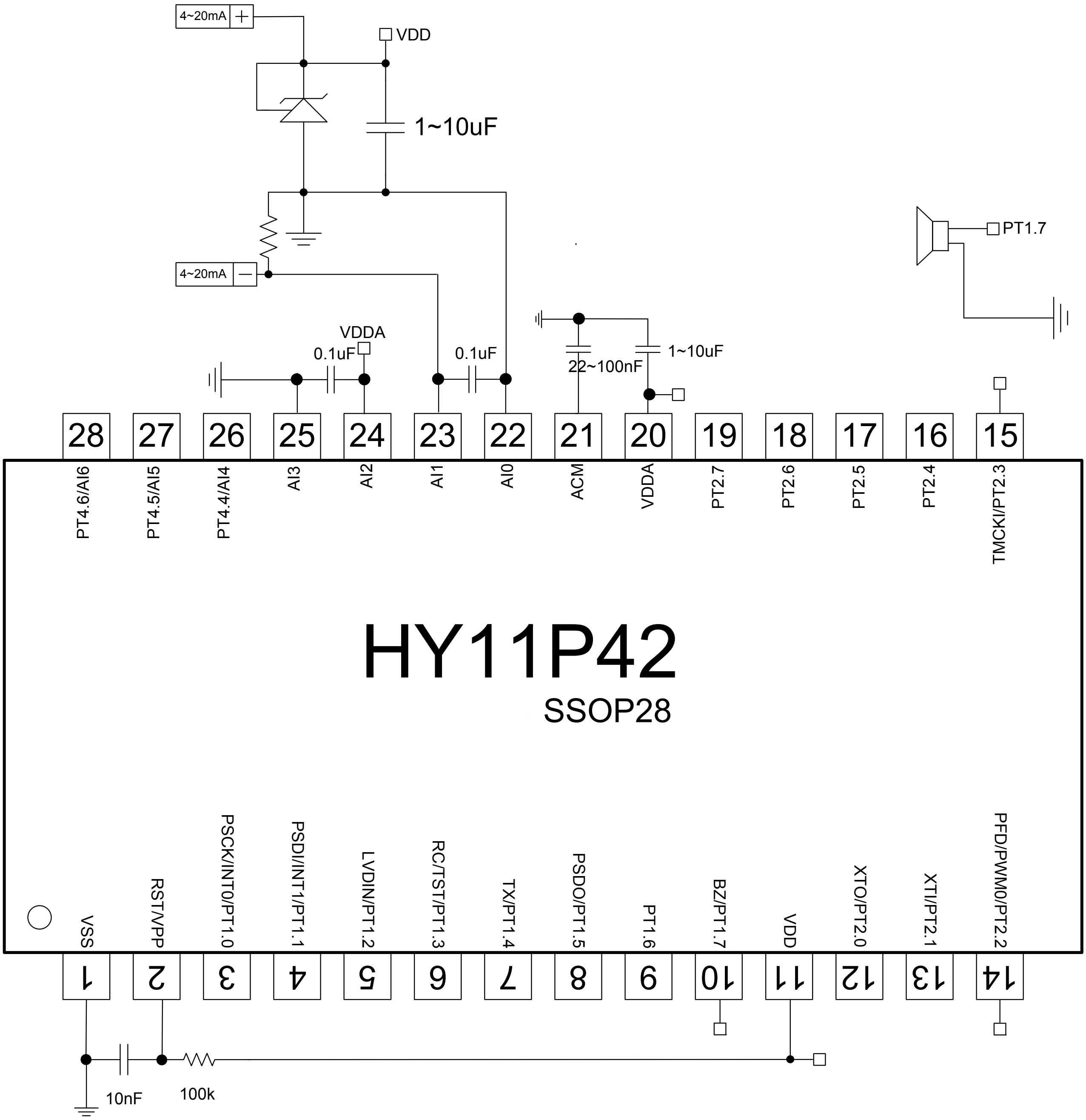

Figure 3-3 4-20mA Panel Meter that Unneeded to Connect External Power Supply

Note 1: DCSET[2:0] can carry out bias adjustment of Load Cell zero point voltage address

Note 2: BIE function can be used to save calibration parameters.

4. Function Outline

4.1 Internal Block Diagram

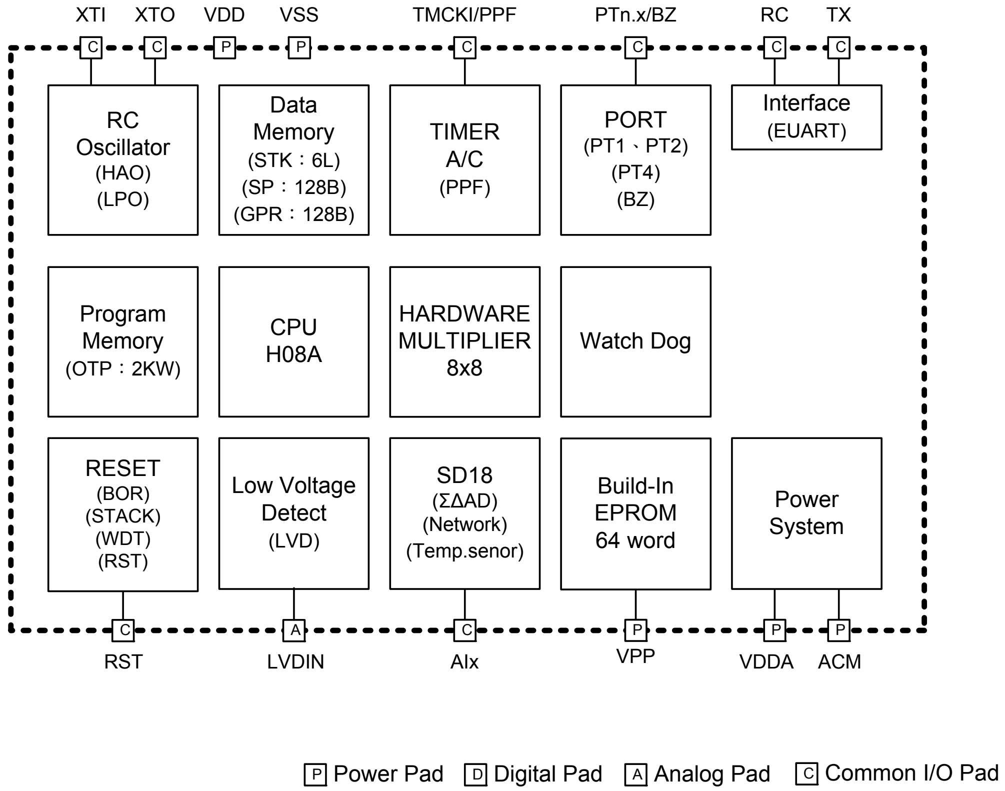

Figure 4-1 HY11P42 Internal Block Diagram

4.2 Related Description and Supporting Documents

IC Function Related Operating Instruction

DS-HY11P42-Vxx	HY11P42 Data Sheet
UG-HY11S14-Vxx	HY11P Series Users' Manual
APD-CORE002-Vxx	H08A Instruction Description

Development Tool Related Operating Instruction

APD-HYIDE006-Vxx	HY11xxx Series Development Tool Software Instruction Manual
APD-HYIDE005-Vxx	HY11xxx Series Development Tool Hardware Instruction Manual
APD-OTP001-Vxx	OTP Products Programming Pin Manual Product

Production Related Operating Instruction

APD-HYIDE004-Vxx	HY1xxxx Series Production Line Specialized Programmer Manual
BDI-HY11P42-Vxx	HY11P42 Individual Product Die Bonding Information

4.3 SD18 Network

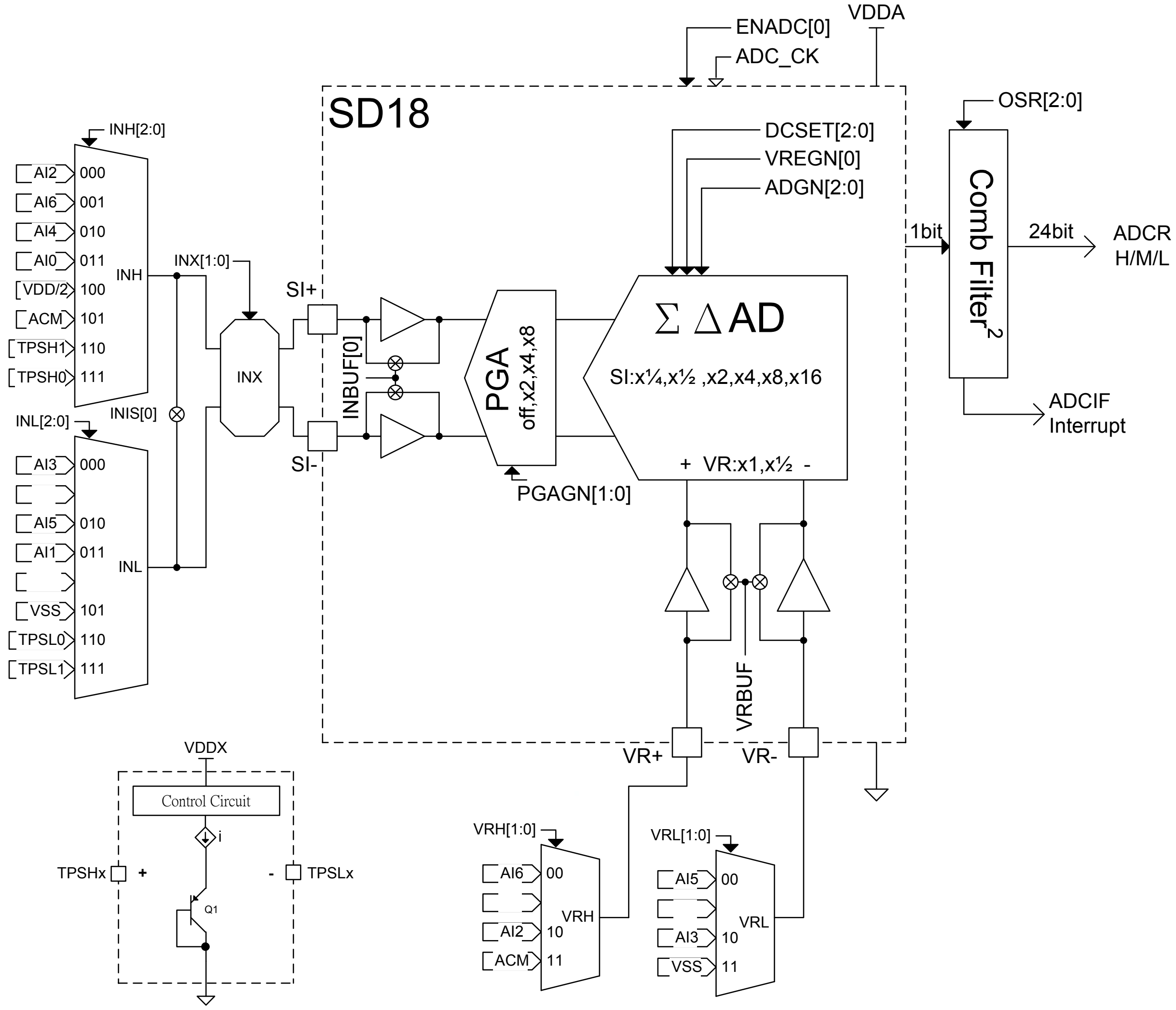

Figure 4-2 SD18 Network

5. Register List

"-"no use,"*"read/write,"w"write,"r"read,"r0"only read 0,"r1"only read 1,"w0"only write 0,"w1"omly write 1
"."unimplemented bit,"x"unknown,"u"unchanged,"d"depends on condition

Address	File Name	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	A-RESET	i-RESET	R/W
00H	INDF0	Contents of FSR0 to address data memory value of FSR0 not changed								N/A	N/A	*,*,*,* *,*,*,*
01H	POINC0	Contents of FSR0 to address data memory value of FSR0 post-incremented								N/A	N/A	*,*,*,* *,*,*,*
02H	PODEC0	Contents of FSR0 to address data memory value of FSR0 post-decremented								N/A	N/A	*,*,*,* *,*,*,*
03H	PRINC0	Contents of FSR0 to address data memory value of FSR0 pre-incremented								N/A	N/A	*,*,*,* *,*,*,*
04H	PLUSW0	Contents of FSR0 to address data memory value of FSR0 offset by W								N/A	N/A	*,*,*,* *,*,*,*
05H	INDF1	Contents of FSR1 to address data memory value of FSR0 not changed								N/A	N/A	*,*,*,* *,*,*,*
06H	POINC1	Contents of FSR1 to address data memory value of FSR0 post-incremented								N/A	N/A	*,*,*,* *,*,*,*
07H	PODEC1	Contents of FSR1 to address data memory value of FSR0 post-decremented								N/A	N/A	*,*,*,* *,*,*,*
08H	PRINC1	Contents of FSR1 to address data memory value of FSR0 pre-incremented								N/A	N/A	*,*,*,* *,*,*,*
09H	PLUSW1	Contents of FSR1 to address data memory value of FSR0 offset by W								N/A	N/A	*,*,*,* *,*,*,*
0FH	FSR0H								FSR0[8]	x	....u	-,-,-,- -,-,-,*
10H	FSR0L	Indirect Data Memory Address Pointer 0 Low Byte,FSR0[7:0]								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
11H	FSR1H								FSR1[8]	x	....u	-,-,-,- -,-,-,*
12H	FSR1L	Indirect Data Memory Address Pointer 1 Low Byte,FSR1[7:0]								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
16H	TOSH						TOS[10]	TOS[9]	TOS[8]	.... .000	.... .000	-,-,-,- -,*,*,*
17H	TOSL	Top-of-Stack Low Byte (TOS<7:0>)								0000 0000	0000 0000	*,*,*,* *,*,*,*
18H	STKPTR	STKFL	STKUN	STKOV			STKPRT[2:0]			000. .000	000. .000	r,rw0,rw0,- -,r,r,r
1AH	PCLATH						PC[10]	PC[9]	PC[8]	.... .000	.... .000	-,-,-,- -,*,*,*
1BH	PCLATL	PC Low Byte for PC<7:0>								0000 0000	0000 0000	*,*,*,* *,*,*,*
1DH	TBLPTRH						TBLPTR[10]	TBLPTR[9]	TBLPTR[8]	.... .000	.... .000	-,-,-,- -,*,*,*
1EH	TBLPTRL	Program Memory Table Pointer Low Byte (TBLPTR<7:0>)								0000 0000	0000 0000	*,*,*,* *,*,*,*
1FH	TBLDH	Program Memory Table Latch High Byte								0000 0000	0000 0000	*,*,*,* *,*,*,*
20H	TBLDL	Program Memory Table Latch Low Byte								0000 0000	0000 0000	*,*,*,* *,*,*,*
21H	PRODH	Product Register of Multiply High Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
22H	PRODL	Product Register of Multiply Low Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
23H	INTE1	GIE	ADCIE	TMCIE		TMAIE	WDTIE	E1IE	E0IE	000. 0000	000. 0000	*,*,*,- *,*,*,*
24H	INTE2	TXIE	RCIE							00..	00..	*,*,-,- -,-,-,-
26H	INTF1		ADCIF	TMCIF		TMAIF	WDTIF	E1IF	E0IF	.00. 0000	.00. 0000	-,*,*,- *,*,*,*
27H	INTF2	TXIF	RCIF							00..	00..	*,*,-,- -,-,-,-
29H	WREG	Working Register								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
2AH	BSRCN								BSR[0]	0	0	-,-,-,- -,-,-,*
2BH	STATUS				C	DC	N	OV	Z	...x xxxx	...u uuuu	-,-,-,* *,*,*,*
2CH	PSTATUS	PD	TO	IDLEB	BOR		SKERR			000d .0..	uduu .d..	rw0,rw0,rw0,rw0 -,rw0,-,-
2DH	LVDCN		LVDFG	LVD	LVDON	VLDX[3:0]				.000 0000	.000 uuuu	-,*,r,r *,*,*,*
30H	PWRCN	ENVDDA	VDDAX[1:0]		ENACM					0000	0000	*,*,*,* -,-,-,-
31H	MCKCN1	ADCS[2:0]			ADCCK	XTHSP	XTSP	ENXT	ENHAO	0000 0001	0000 0001	*,*,*,* *,*,*,*
32H	MCKCN2			LSCK	HSCK	HSS[1:0]		CPUCK[1:0]		..00 0000	..00 0000	-,-,*,* *,*,*,*
33H	MCKCN3					PERCK	BZS[2:0]			 0000	 0000	-,-,-,- *,*,*,*
39H	ADCRH	ADC conversion memory HighByte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
3AH	ADCRM	ADC conversion memory Middle Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
3BH	ADCRL	ADC conversion memory Low Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
3CH	ADCCN1	ENADC	ENHIGN	ENCHP	PGAGN[1:0]		ADGN[2:0]			0000 0000	0000 0000	*,*,*,* *,*,*,*
3DH	ADCCN2			INBUF	VRBUF	VREGN	DCSET[2:0]			..00 0000	..00 0000	-,-,*,* *,*,*,*
3EH	ADCCN3	OSR[2:0]								000.	000.	*,*,*,- -,-,-,-
3FH	AINET1	INH[2:0]			INL[2:0]			INIS		0000 000.	0000 000.	*,*,*,* *,*,*,-
40H	AINET2		VRH[1:0]		INX[1:0]		VRL[1:0]			.000 000.	.000 000.	-,*,*,* *,*,*,-
41H	TMACN	ENTMA	TMACK	TMAS[1:0]		ENWDT	WDTS[2:0]			0000 0000	0000 0000	*,*,*,* w1,*,*,*
42H	TMAR	TimerA data register								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
46H	TMCCN	ENTMC	TMCCK[1:0]		TMCS1[2:0]			TMCS0[1:0]		0000 0000	0000 0000	*,*,*,* *,*,*,*
47H	PRC	TimerC programmable register								1111 1111	1111 1111	*,*,*,* *,*,*,*
48H	TMCR	TimerC register								0000 0000	0000 0000	r,r,r,r r,r,r,r
4EH	PASC	PASF		PASCF[1:0]						0.00	0.00	*,-,*,* -,-,-,-
4FH	PWMCN	ENPWM	ENPFD	PWMRL[1:0]						0000	0000	*,*,*,* -,-,-,-
51H	PWMR	PWM MSB Byte register								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
63H	URCON	ENSP	ENTX	TX9	TX9D	PARITY			WUE	0000 0..0	0000 0..0	*,*,*,* *,-,-,*
64H	URSTA		RC9D	PERR	FERR	OERR	RCIDL	TRMT	ABDOVF	.000 0110	.000 0110	-,r,r,r r,r,r,rw0
65H	BAUDCON					ENCR	RC9	ENADD	ENABD	 0000	 0000	-,-,-,- *,*,*,*'
66H	BRGRH				Baud Rate Generator Register High Byte					...x xxxx	...u uuuu	-,-,-,* *,*,*,*
67H	BRGRL	Baud Rate Generator Register Low Byte								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
68H	TXREG	UART Transmit Register								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
69H	RCREG	UART Receive Register								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r
6AH	PT4		PT4.6	PT4.5	PT4.4					.xxx	.uuu	-,r,r,r -,-,-,-
6BH	PT4DA		DA4.6	DA4.5	DA4.4					.111	.111	-,*,*,* -,-,-,-
6CH	PT4PU		PU4.6	PU4.5	PU4.4					.000	.000	-,*,*,* -,-,-,-
6DH	PT1	PT1.7	PT1.6	PT1.5	PT1.4	PT1.3	PT1.2	PT1.1	PT1.0	xxxx xxxx	uuuu uuuu	*,*,*,* r,r,r,r
6EH	TRISC1	TC1.7	TC1.6	TC1.5	TC1.4					0000	0000	*,*,*,* -,-,-,-
6FH	PT1DA						DA1.2			.... .0..	.... .0..	-,-,-,- -,*,-,-
70H	PT1PU	PU1.7	PU1.6	PU1.5	PU1.4	PU1.3	PU1.2	PU1.1	PU1.0	0000 0000	0000 0000	*,*,*,* *,*,*,*
71H	PT1M1					INTEG1[1:0]		INTEG0[1:0]		 0000	 0000	-,-,-,- *,*,*,*
72H	PT1M2		PM1.7[0]		PM1.6[0]		PM1.5[0]		PM1.4[0]	.0.0 .0.0	.0.0 .0.0	-,*,-,* -,*,-,*
74H	PT2	PT2.7	PT2.6	PT2.5	PT2.4	PT2.3	PT2.2	PT2.1	PT2.0	xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
75H	TRISC2	TC2.7	TC2.6	TC2.5	TC2.4	TC2.3	TC2.2	TC2.1	TC2.0	0000 0000	0000 0000	*,*,*,* *,*,*,*
77H	PT2PU	PU2.7	PU2.6	PU2.5	PU2.4	PU2.3	PU2.2	PU2.1	PU2.0	0000 0000	0000 0000	*,*,*,* *,*,*,*
78H	PT2M1			PM2.2[1]	PM2.2[0]					..00	..00	-,-,*,* -,-,-,-
79H	PT2M2	PWMTR[1]	PWMTR[0]							00..	00..	*,*,-,- *,*,*,*
80H ~ FFH	GPR0	General Purpose Register as 128Byte								xxxx xxxx	uuuu uuuu	*,*,*,* *,*,*,*
195H	BIECTRL					VPP_HIGH		BIEWR	BIERD	1000 d000	1000 d000	-,-,-,- *,r0,*,*
196H	BIEPTRH									0000 0000	0000 0000	w0,w0,W0,W0 W0,W0,W0,W0
197H	BIEPTRL	0	0	BIE_ADDR[5:0]						0000 0000	0000 0000	w0,w0,*,* *,*,*,*
198H	BIEDH	BIE_DATA[15:8]								xxxx xxxx	xxxx xxxx	*,*,*,* *,*,*,*
199H	BIEDL	BIE_DATA[7:0]								xxxx xxxx	xxxx xxxx	*,*,*,* *,*,*,*

Table 5-1 HY11P42 Register List

6. Electrical Characteristics

Absolute maximum ratings over operating free-air temperature (unless otherwise noted)

Voltage applied at V_{DD} to V_{SS} . . . . −0.2 V to 4.0 V

Voltage applied to any pin . . . . −0.2 V to V_{DD} + 0.3 V

Voltage applied to RST/VPP pin . . . . −0.2 V to 6.9 V

Voltage applied to TST/PT1.3 pin . . . . −0.2 V to V_{DD} + 1 V

Diode current at any device terminal . . . . ±2 mA

Storage temperature, Tstg: (unprogrammed device) . . . . −55℃ to 150℃

(programmed device) . . . . −40℃ to 85℃

Total power dissipation. 0.5w

Maximum output current sink by any PORT1 to PORT3 I/O pin. 25mA

6.1 Recommended operating conditions

T_A = -40℃ ~ 85℃,unless otherwise noted

Sym.	Parameter		Test Conditions		Min.	Typ.	Max.	unit
V_{DD}	Supply Voltage		All digital peripherals and CPU		2.2		3.6	V
			Analog peripherals		2.4		3.6	
V_{SS}	Supply Voltage				0		0	
XT	External Oscillator Frequency	Watch crystal	V_{DD} = 2.2V, ENXT[0]=1	XTSP[0]=0, XTHSP[0]=0		32.768K		Hz
		Ceramic resonator		XTSP[0]=1, XTHSP[0]=0	450K		8M	
		Crystal		XTSP[0]=1, XTHSP[0]=0	1M		8M	

6.2 Internal RC Oscillator

T_A = 25℃, V_{DD} = 3.0V,unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
HAO	High Speed Oscillator frequency	ENHAO[0]=1	1.7	2.0	2.3	MHz
LPO	Low Power Oscillator frequency	V_{DD} supply voltage be enable LPO	22	28	35	KHz

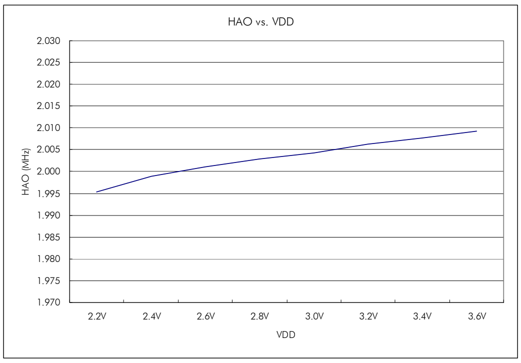

Figure 6.2-1 HAO vs. VDD

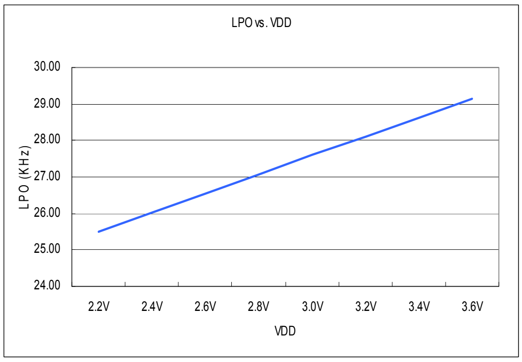

Figure 6.2-2 LPO vs. VDD

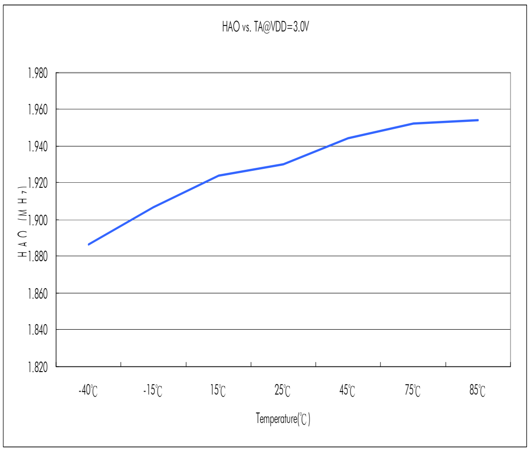

Figure 6.2-3 HAO vs. Temperature

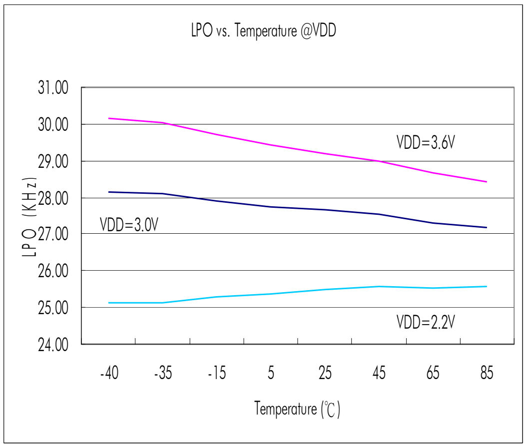

Figure 6.2-4 LPO vs. Temperature

6.3 Supply current into VDD excluding peripherals current

T_A = 25℃,V_{DD} = 3.0V,OSC_LPO = 28KHz,unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
I_{AM1}	Active mode 1	OSC_CY = 8MHz, OSC_HAO = off, CPU_CK = 8MHz		1.2	2	mA
I_{AM2}	Active mode 2	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 2MHz		0.32	0.55	mA
I_{AM3}	Active mode 3	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 1MHz		0.18	0.3	mA
I_{LP1}	Low Power 1	OSC_CY = 32768Hz, OSC_HAO = off, CPU_CK = 16384Hz		7	12	uA
I_{LP2}	Low Power 2	OSC_CY = off, OSC_HAO = off, CPU_CK = LPO, Idle state		1.65	3	uA
I_{LP3}	Low Power 3	OSC_CY = off, OSC_HAO = off, CPU_CK = off, Sleep state		0.65	1.2	uA

OSC_CY：External Oscillator frequency.

OSC_HAO：Internal High Accuracy Oscillator frequency.

CPU_CK：CPU core work frequency.

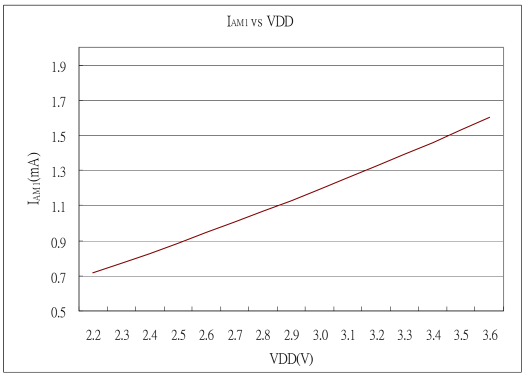

Figure 6.3-1 I_{AM1} vs. VDD

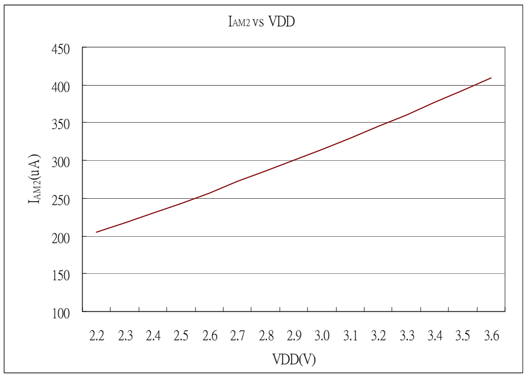

Figure 6.3-2 I_{AM2} vs. VDD

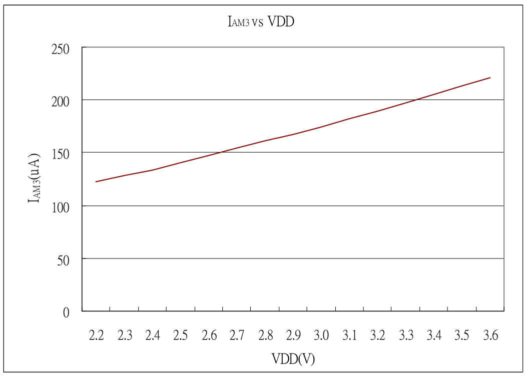

Figure 6.3-3 I_{AM3} vs. VDD

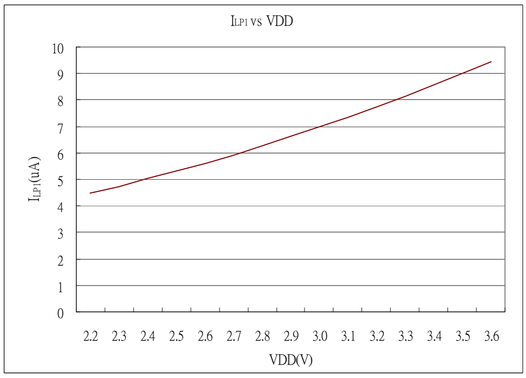

Figure 6.3-4 I_{LP1} vs. VDD

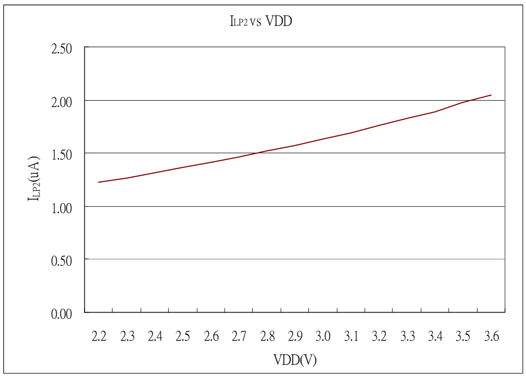

Figure 6.3-5 I_{LP2} vs. VDD

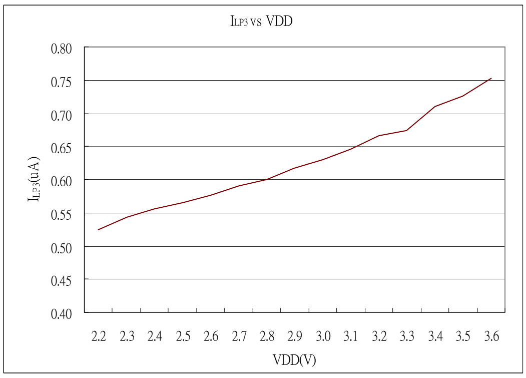

Figure 6.3-6 I_{LP3} vs. VDD

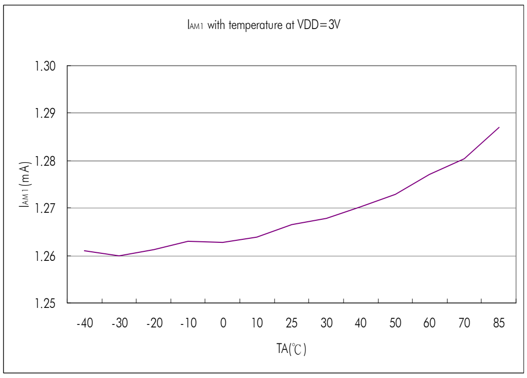

Figure 6.3-7 I_{AM1} vs. Temperature

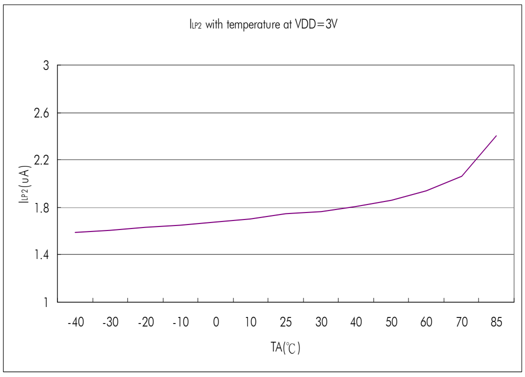

Figure 6.3-8 I_{LP2} vs. Temperature

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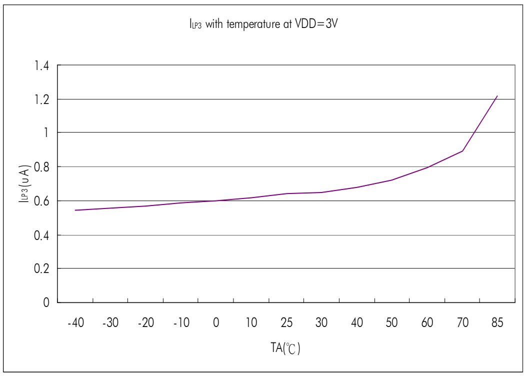


Figure 6.3-9 I_{LP3} vs. Temperature

6.4 Port1~5

T_A = 25℃, V_{DD} = 3.0V,unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
Input voltage and Schmitt trigger and leakage current and timing						
V_{IH}	High-Level input voltage				2.1	V
V_{IL}	Low-Level input voltage		0.9			V
V_{hys}	Input Voltage hysteresis(VIH - VIL)			0.8		V
I_{LKG}	Leakage Current				0.1	uA
R_{PU}	Port pull high resistance			180		kΩ
Output voltage and current and frequency						
V_{OH}	High-level output voltage	I_{OH}=10mA	V_{DD} -0.3			V
V_{OL}	Low-level output voltage	I_{OL}=-10mA			VSS +0.3	V

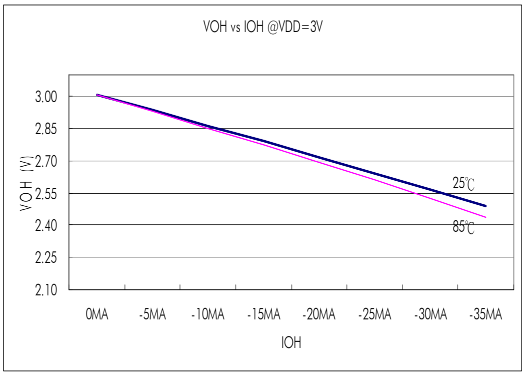


Figure 6.4-1 V_{OH} vs. I_{OH} @VDD=3.0V

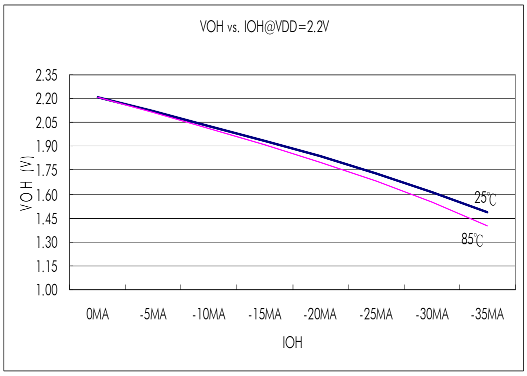


Figure 6.4-2 V_{OH} vs. I_{OH} @VDD=2.2V

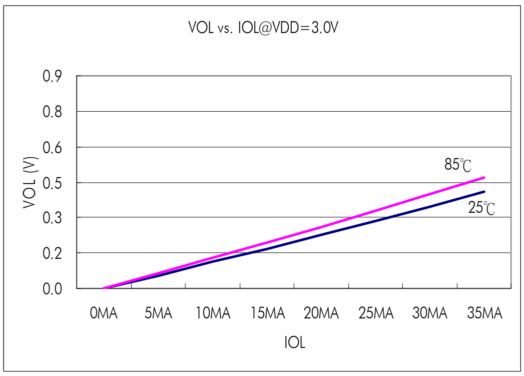


Figure 6.4-3 V_{OL} vs. I_{OL}@VDD=3.0V

Figure 6.4-4 V_{OL} vs. I_{OL}@VDD=2.2V

6.5 Reset (Brownout, External RST pin, Low Voltage Detect)

T_A = 25℃,V_{DD} = 3.0V,unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
BOR	Pulse length needed to accepted reset internally, $t_{d\text{-}LVR}$		2			us
	V_{DD} Start Voltage to accepted reset internally (L➔H),V_{LVR}		1.6	1.85	2.1	V
	Hysteresis, $V_{HYS\text{-}LVR}$			70		mV
RST	Pulse length needed as RST/VPP pin to accepted reset internally, $t_{d\text{-}RST}$		2			us
	Input Voltage to accepted reset internally		0.9			V
	Hysteresis, $V_{HYS\text{-}RST}$			0.8		V
LVD	Operation current, I_{LVD}			10	15	uA
	External input voltage to compare reference voltage			1.2		V
	Compare reference voltage temperature drift	T_A = -40℃ ~ 85 ℃		100		ppm/℃
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1110b			3.3		V
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1101b			3.2		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1100b			3.1		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1011b			3.0		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1010b			2.9		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1001b			2.8		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=1000b			2.7		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0111b			2.6		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0110b			2.5		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0101b			2.4		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0100b			2.3		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0011b			2.2		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0010b			2.1		
	Detect V_{DD} voltage rang by user option, V_{SVS} VLDx[3:0]=0001b			2.0		

BOR：Brownout Reset

LVR：Low Voltage Reset of BOR

LVD：Low Voltage Detect

RST：External Reset pin

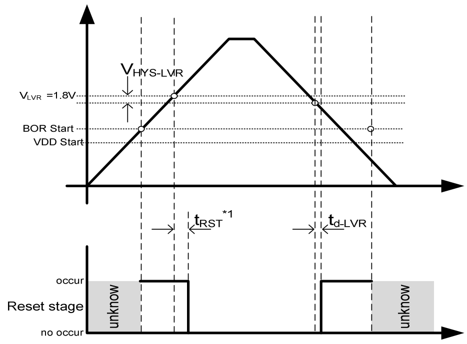


Figure 6.5-1 BOR Reset diagram

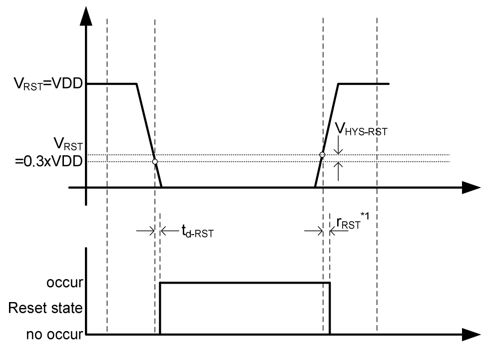


Figure 6.5-2 RST Reset diagram

[*1] r_{RST} ：Please see BOR Introduce of HY11Pxx series User's Guide (UG-HY11S14-Vxx).

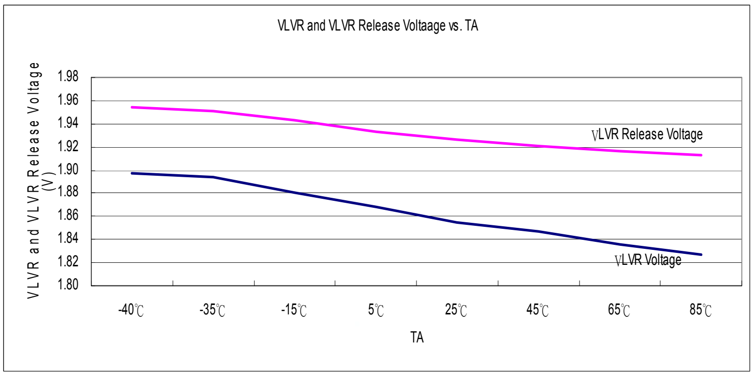


Figure 6.5-3 LVR vs. Temperature

6.6 Power System

T_A = 25℃,V_{DD} = 3.0V,unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
VDDA	VDDA operation current, I_{VDDA}	I_L = 0mA	VDDAX[1:0]=00b		22		uA
	Select VDDA output voltage	I_L = 0.1mA, VDD≧VDDA+0.2V	VDDAX[1:0]=00b		3.3		V
			VDDAX[1:0]=01b		2.9		V
			VDDAX[1:0]=10b		2.6		V
			VDDAX[1:0]=11b		2.4		V
	Dropout voltage	I_L = 10mA	VDDAX[1:0]=00b		135		mV
			VDDAX[1:0]=01b		150		mV
			VDDAX[1:0]=10b		165		mV
			VDDAX[1:0]=11b		180		mV
	Temperature drift	VDDAX[1:0]=11b	T_A=-40℃~85℃		50		ppm/℃
	V_{DD} Voltage drift	I_L = 0.1mA	V_{DD}=2.5V~3.6V		±0.2		%/V
ACM	ACM operation current, I_{ACM}	I_L = 0mA			20		uA
	Output voltage ,V_{ACM}	ENACM[0]=1, *1	I_L = 0uA		1.0		V
	Output voltage with Load		I_L = ±200uA	0.98		1.02	V_{ACM}
	Output voltage ,V_{ACM}	ENACM[0]=1, *2	I_L = 0uA		1.2		V
	Output voltage with Load		I_L = ±200uA	0.98		1.02	V_{ACM}
	Temperature drift	ENACM[0]=1, I_L = 10uA	T_A=-40℃~85℃		50		ppm/℃
	VDDA Voltage drift				100		uV/V

VDDA：Adjust Voltage Regulator

ACM：Analog Common Mode Voltage

*1: V_{ACM} = 1.0V is just for VDDAX[1:0]=1xb mode. (at A/D differential voltage reference < 1.4V)

*2: V_{ACM} = 1.2V is just for VDDAX[1:0]=0xb mode. (at A/D differential voltage reference > 1.4V)

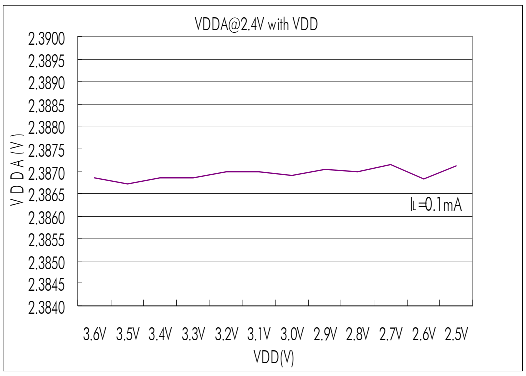


Figure 6.6-1 VDDA IL=0.1mA vs. VDD

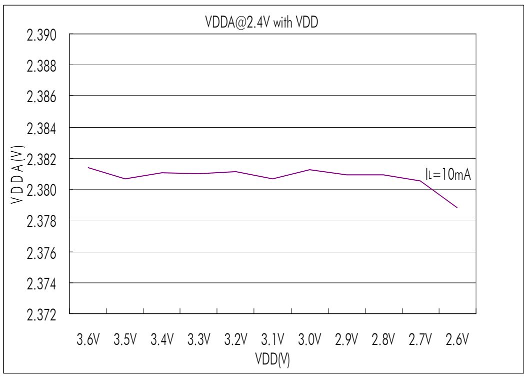


Figure 6.6-2 VDDA IL=10mA vs. VDD

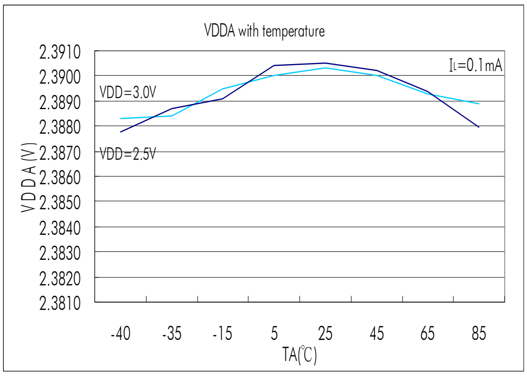


Figure 6.6-3 VDDA I_L=0.1mA vs. Temperature

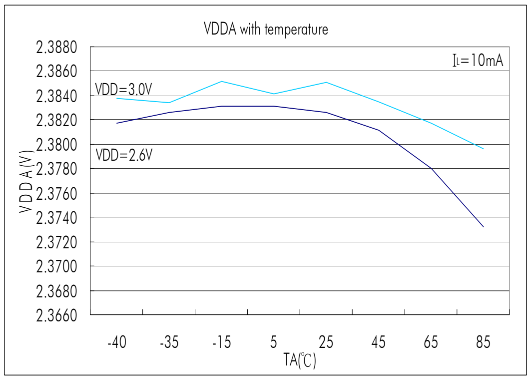


Figure 6.6-4 VDDA I_L=10mA vs. Temperature

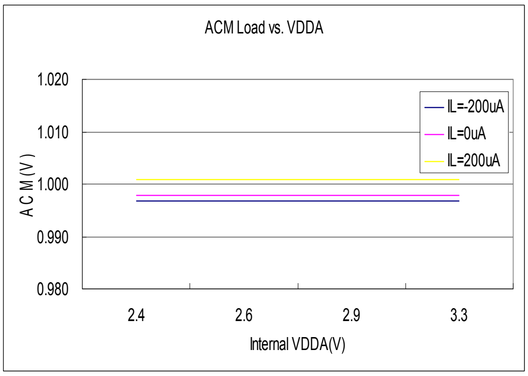


Figure 6.6-5 ACM Load vs. VDDA (a)

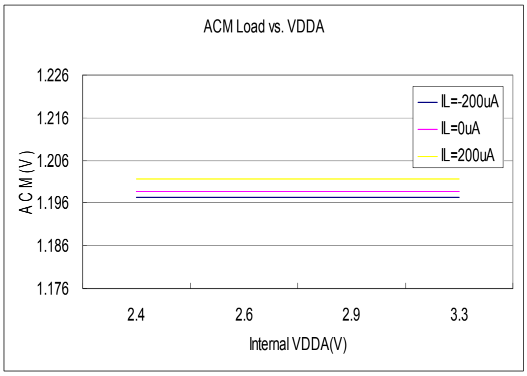


Figure 6.6-5 ACM Load vs. VDDA (b)

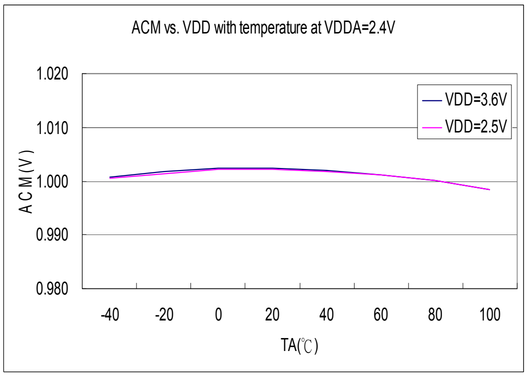


Figure 6.6-6 ACM vs. Temperature (a)

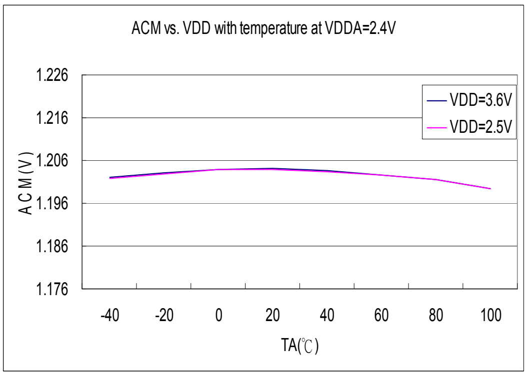


Figure 6.6-6 ACM vs. Temperature (b)

6.7 SD18, Power Supply and Recommended Operating Conditions

T_A = 25℃,V_{DD} = 3.0V, VDDA=2.4V,unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{SD18}	Supply Voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
f_{SD18}	Modulator sample frequency, ADC_CK			25	250	300	KHz
	Over Sample Ratio, OSR			256		32768	
I_{SD18}	Operation supply current without PGA	ENADC[0]=1 INBUF[0]=1,VRBUF[0]=0	GAIN =4, ADC_CK=250KHz		168		uA
		ENADC[0]=1 INBUF[0]=0,VRBUF[0]=1			150		
		ENADC[0]=1 INBUF[0]=0,VRBUF[0]=0			120		

6.7.1 PGA, Power Supply and Recommended Operating Conditions

T_A = 25℃,V_{DD} = 3.0V, VDDA=2.4V,unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{PGA}	Supply Voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
I_{PGA}	Operation supply current	PGAGN[1:0]=<01>or<1x>			320		uA
G_{PGA}	Gain temperature drift	T_A = -40℃~ 85℃	GAIN=128		5		ppm/℃

6.7.2 SD18, Performance II (fSD18=250KHz)

T_A = 25℃,V_{DD} = 3.0V, VDDA=2.9V,V_{VR}=1.0V,GAIN=1 without PGA, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
INL	Integral Nonlinearity(INL)	VDDA=2.4V,V_{VR}=1.0V,ΔSI=±200mV			±0.003	±0.01	%FSR
		VDDA=2.4V,V_{VR}=1.0V,ΔSI=±450mV					
	No Missing Codes[3]	ADC_CK=250KHz,OSR[2:0]=010b		23			Bits
G_{SD18}	Temperature drift **Gain 1~x16 (INBUF[0]=0b,)** **Gain 1~x4 (INBUF[0]=1b,)**	INBUF[0]=0b,VRBUF[0]=0b	T_A = -40℃~ 85℃		2		ppm/℃
		INBUF[0]=1b,VRBUF[0]=0b					
		INBUF[0]=0b,VRBUF[0]=1b					
		INBUF[0]=1b,VRBUF[0]=1b					
E_{OS}	Offset error of Full Scale Rang input voltage range with Chopper and Buffer(INBUF,VRBUF)	ΔAI=0V ΔVR=0.9V DCSET[2:0]=<000> *ΔAI is external short	Gain=2			1	%FSR
	Offset error of Full Scale Rang input voltage range with Chopper without Buffer(INBUF,VRBUF)		Gain=2			1	

	Offset temperature drift with chopper without Buffer (INBUF,VRBUF).		GAIN=1	2	uV/℃
			GAIN=2	1	
			GAIN=4	0.5	
			GAIN=16	0.15	
	Offset temperature drift with chopper and Buffer (INBUF,VRBUF)		GAIN=1	2	
			GAIN=2	1	
			GAIN=4	0.5	
	Offset temperature drift with chopper without Buffer (INBUF,VRBUF).		GAIN=128	0.02	
CM_{SD18}	Common-mode rejection	V_{CM}=0.7V to 1.7V, V_{VR}=1.0V,without PGA	V_{SI}=0V, GAIN=1	90	dB
		V_{CM}=0.7V to 1.7V, V_{VR}=1.0V,	V_{SI}=0V, GAIN=16	75	
PSRR	DC power supply rejection	VDDA=3.0V,ΔVDDA=±100m V,V_{VR}=1.0V, V_{SI}=1.2V,V_{SI-}=1.2V,	GAIN=1 PGA=off	75	dB
			GAIN=16		

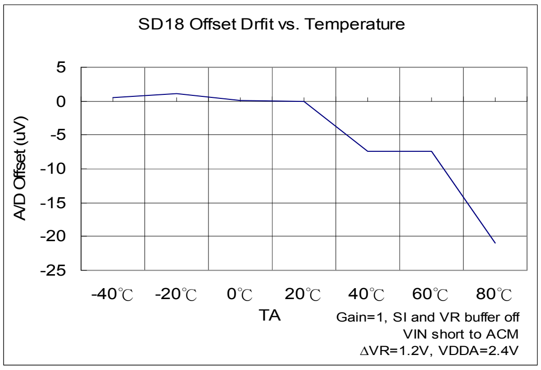


Figure 6.7-1(a) SD18 Offset Temperature Drift

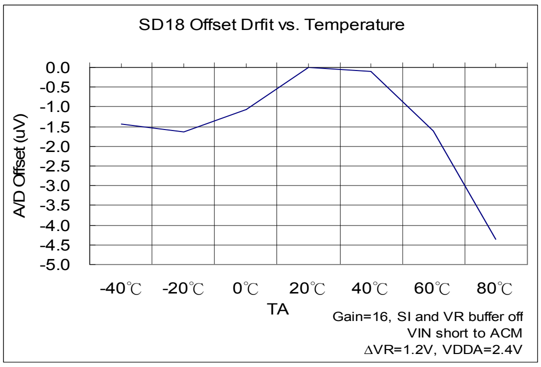


Figure 6.7-1(b) SD18 Offset Temperature Drift

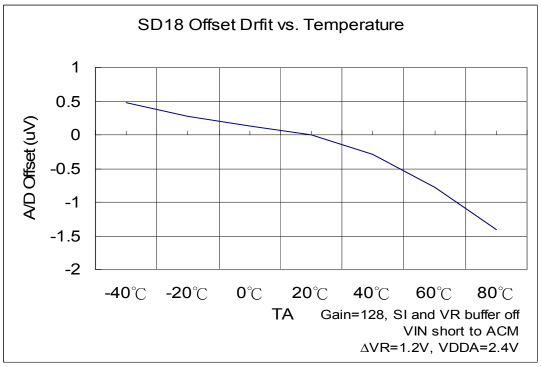


Figure 6.7-1(c) SD18 Offset Temperature Drift

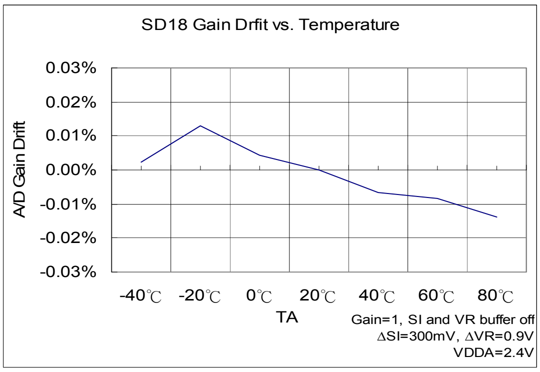


Figure 6.7-2(a) SD18 Gain Drift with Temperature

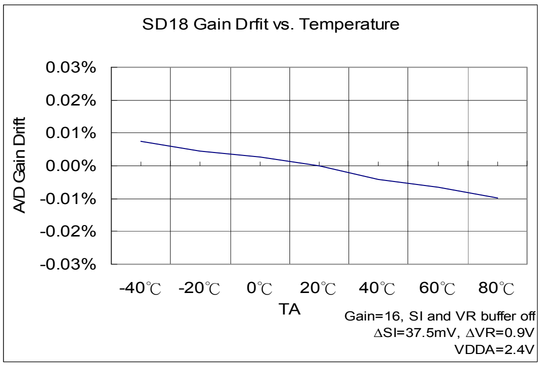


Figure 6.7-2(b) SD18 Gain Drift with Temperature

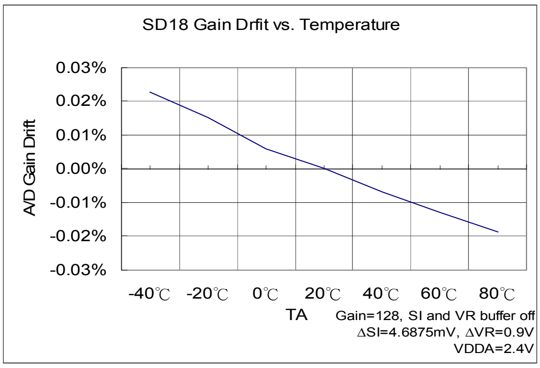


Figure 6.7-2(c) SD18 Gain Drift with Temperature

6.7.3 SD18, Temperature Sensor

T_A = 25℃,V_{DD} = 3.0V, VDDA=2.4V,unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
TC_S	Sensor temperature drift			178		uV/℃
KT	Absolute Temperature Scale 0°K	INBUF[0]=1		-289		℃
TC_{ERR}	One point calibrate error temperature	Calibration at 25℃ of -40℃~85℃		±2		℃

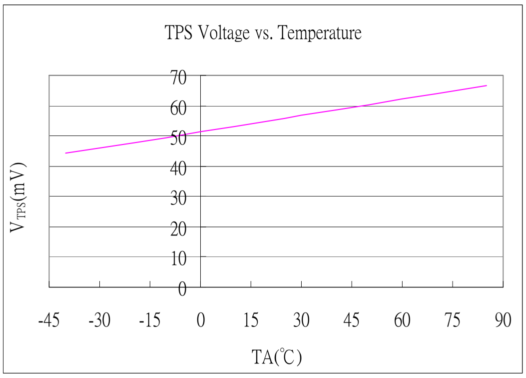


Figure 6.7-3 TPS Output Voltage vs. Temperature Drift

6.7.4 SD18 Noise Performance

T_A = 25℃, V_{DD} = 3.0V, VDDA=2.4V, unless otherwise noted

HY11P42 provides important input noise specification that aims at SD18. Table6.7-4(a) and Table6.7-4(b) lists out the relations of typical noise specification, Gain, Output rate, and maximum input voltage of single end. Test condition configuration and external input signal short, voltage reference: 1.2V and 1024 records were sampled.

ENOB(RMS) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V												
Max. Vin(mV) =0.9*VREF (1)	**OSR**				**256**	**512**	**1024**	**2048**	**4096**	**8192**	**16384**	**32768**
	Output rate(HZ)				**977**	**488**	**244**	**122**	**61**	**31**	**15**	**8**
	Gain	**=**	**PGA**	**× ADGN**								
±2400	**0.25**	**=**	**1**	**× 0.25**	16.3	17.4	17.9	18.5	19.0	19.5	20.0	20.4
±2160	**0.5**	**=**	**1**	**× 0.5**	16.3	17.3	17.9	18.4	18.9	19.4	19.8	20.2
±1080	**1**	**=**	**1**	**× 1**	16.2	17.2	17.8	18.3	18.8	19.3	19.7	20.1
±540	**2**	**=**	**1**	**× 2**	16.1	17.1	17.6	18.2	18.7	19.2	19.6	20.0
±270	**4**	**=**	**1**	**× 4**	16.0	16.9	17.5	18.0	18.5	18.9	19.4	19.8
±135	**8**	**=**	**1**	**× 8**	15.9	16.6	17.2	17.7	18.2	18.7	19.2	19.6
±68	**16**	**=**	**1**	**× 16**	15.6	16.3	16.8	17.3	17.7	18.3	18.8	19.3
±34	**32**	**=**	**2**	**× 16**	14.8	15.3	15.9	16.4	16.9	17.4	17.8	18.3
±17	**64**	**=**	**4**	**× 16**	14.5	15.0	15.5	16.0	16.5	17.0	17.5	18.0
±8	**128**	**=**	**8**	**× 16**	14.0	14.6	15.1	15.6	16.0	16.6	17.0	17.5

(1) Max.Vin (mV) is the max. input voltage of single end to ground (VSS).

Table6.7-4(a) SD18 ENOB Table

RMS Noise(uV) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V												
Max. Vin(mV) =0.9*VREF	**OSR**				**256**	**512**	**1024**	**2048**	**4096**	**8192**	**16384**	**32768**
	Output rate(HZ)				**977**	**488**	**244**	**122**	**61**	**31**	**15**	**8**
	Gain	**=**	**PGA**	**× ADGN**								
±2400	**0.25**	**=**	**1**	**× 0.25**	121.08	57.40	38.74	26.66	18.39	13.21	9.49	6.98
±2160	**0.5**	**=**	**1**	**× 0.5**	61.63	29.23	19.21	13.51	9.78	7.02	5.12	3.91
±1080	**1**	**=**	**1**	**× 1**	32.21	15.70	10.25	7.31	5.19	3.77	2.80	2.13
±540	**2**	**=**	**1**	**× 2**	16.59	8.54	5.91	4.06	2.86	2.06	1.48	1.12
±270	**4**	**=**	**1**	**× 4**	9.00	4.84	3.33	2.37	1.67	1.19	0.87	0.65
±135	**8**	**=**	**1**	**× 8**	5.04	2.97	2.02	1.44	1.01	0.73	0.51	0.39
±68	**16**	**=**	**1**	**× 16**	3.03	1.84	1.29	0.92	0.70	0.46	0.33	0.24
±34	**32**	**=**	**2**	**× 16**	2.61	1.81	1.27	0.89	0.62	0.45	0.32	0.23
±17	**64**	**=**	**4**	**× 16**	1.66	1.13	0.80	0.56	0.41	0.29	0.20	0.14
±8	**128**	**=**	**8**	**× 16**	1.13	0.77	0.55	0.38	0.28	0.19	0.14	0.10

Table6.7-4(b) SD18 RMS Noise Table

The RMS noise is referred to the input. The Effective Number of Bits (ENOB(RMS Bit)) is defined as:

$$\text{ENOB(RMS)} = \ln\left(\frac{\text{FSR}}{\text{RMS Noise}}\right) \Big/ \ln(2)$$

$$\text{RMS Noise} = \left(2 \times \text{VREF} \times \sqrt{\sum_{k=1}^{1024}\left(\text{ADO}[k] - \text{Average}\right)^2}\right) \Big/ 2^{23}$$

Where FSR (Full-Scale Range) $= 2 \times \text{VREF/Gain}$.

$$\text{Average} = \frac{\sum_{k=1}^{1024}(\text{ADO}[k])}{1024}$$

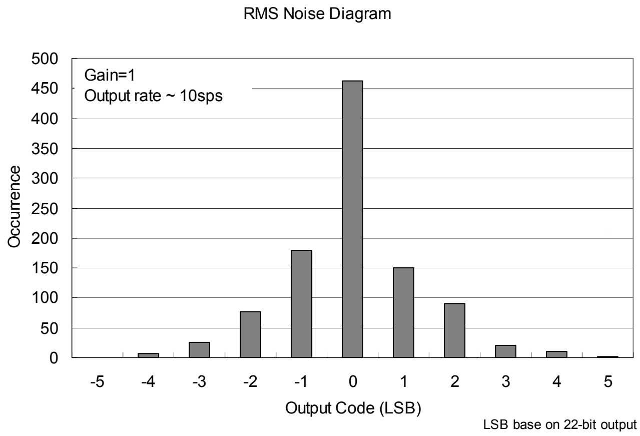


Figure 6.7-4(a) RMS Noise Diagram

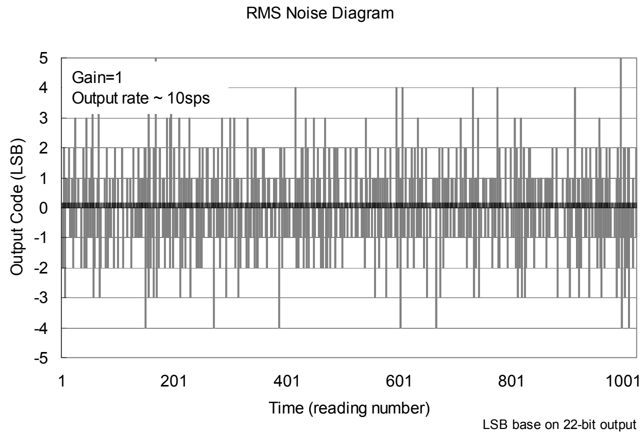


Figure 6.7-4(b) Output Code Diagram

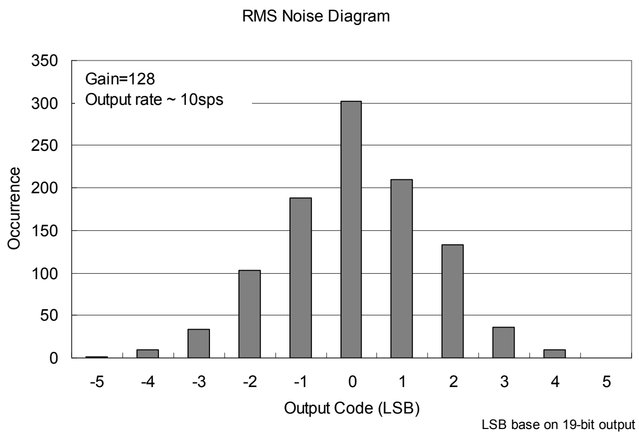


Figure 6.7-4(c) RMS Noise Diagram

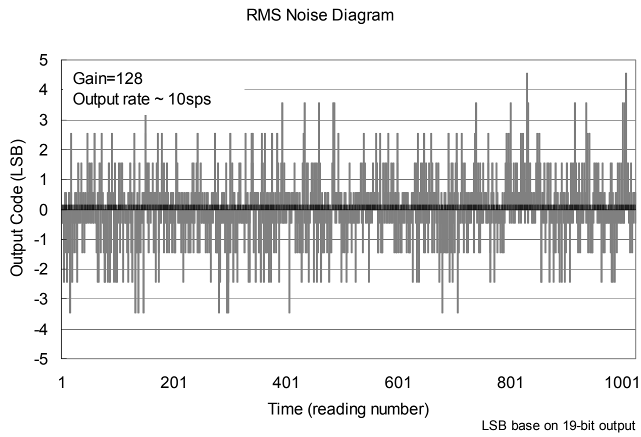


Figure 6.7-4(d) Output Code Diagram

6.8 Built-in EPROM (BIE)

T_A = 25℃, V_{DD} = 3.0V, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
V_{BIE}	Supply Voltage			6.0	6.5	V
I_{BIE}	Operation supply current			5		mA
V_{SS}	Supply Voltage			0		V

7. Ordering Information

Device No.[1]	Package Type	Pins	Package Drawing		Code[2]	Shipment Packing Type	Unit Q'ty	Material Composition	MSL[3]
HY11P42-D000	Die	-	D	000	000	-	200	Green[4]	-
HY11P42-E028	SSOP	28	E	028	000	Tube	48	Green[4]	MSL-3
HY11P42-E028	SSOP	28	E	028	000	Tape & Reel	2000	Green[4]	MSL-3
HY11P42-N024	QFN	24	N	024	000	Tray	490	Green[4]	MSL-3
HY11P42-T028	TSSOP	28	T	028	000	Tube	50	Green[4]	MSL-3
HY11P42-T028	TSSOP	28	T	028	000	Tape & Reel	3000	Green[4]	MSL-3

[1] **Device No.: Model No. – Package Type Description – Code** (Blank Code/ Standard/ Customized Programming Code)

Ex: Your customized programming code is 008 and you require die shipment.
The device No. will be HY11P42-D000-008

Ex: You request blank code in die package.
The device No. will be HY11P42-D000

Ex: You request blank code in SSOP28 package.
The device No. will be HY11P42-E028
And please clearly indicate the shipment packing type when placing orders.

Ex: Your customized programming code is 009 and you require products in TSSOP28 package.
The device No. will be HY11P42-T028-009.
And please clearly indicate the shipment packing type when placing orders.

[2] **Code**:
"001"~ "999" is standard or customized programming code. Blank code does not have these numbers.

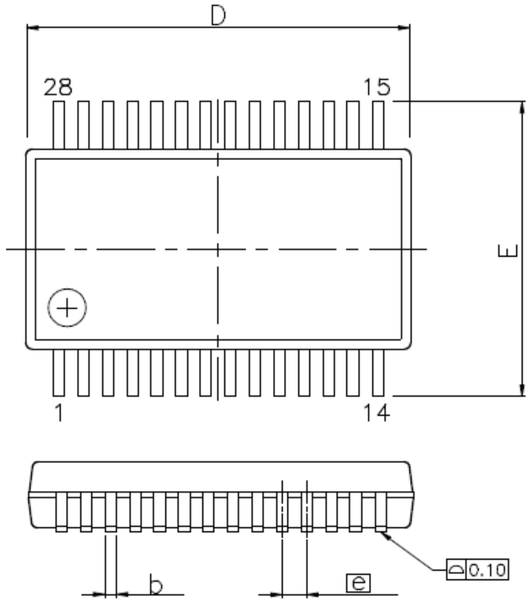
[3] **MSL**:
The Moisture Sensitivity Level ranking conforms to IPC/JEDEC J-STD-020 industry standard categorization. The products are processed, packed, transported and used with reference to IPC/JEDEC J-STD-033.

[4] **Green (RoHS & no Cl/Br)**:
HYCON products are Green products that compliant with RoHS directive and are Halogen free (Br/Cl<0.1%)

8. Package Information

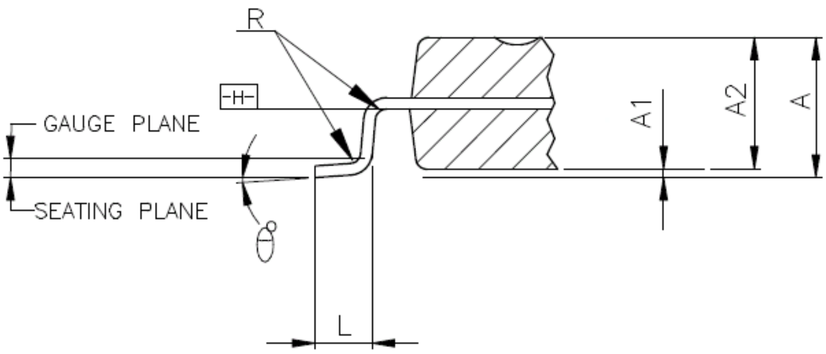
8.1 SSOP28 (E028)

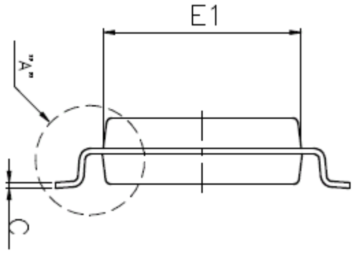
8.1.1 Package Dimensions



	SYMBOLS	MIN.	NOM.	MAX.
	A	–	–	2.0
	A1	0.05	–	–
2	A2	1.65	1.75	1.85
	b	0.22	–	0.38
	c	0.09	–	0.25
2	D	10.05	10.20	10.50
3	E	7.65	7.80	7.90
	E1	5.00	5.30	5.60
	e	0.65 BSC		
	L	0.55	0.75	0.95
	R	0.09	–	–
	θ°	0°	4°	8°

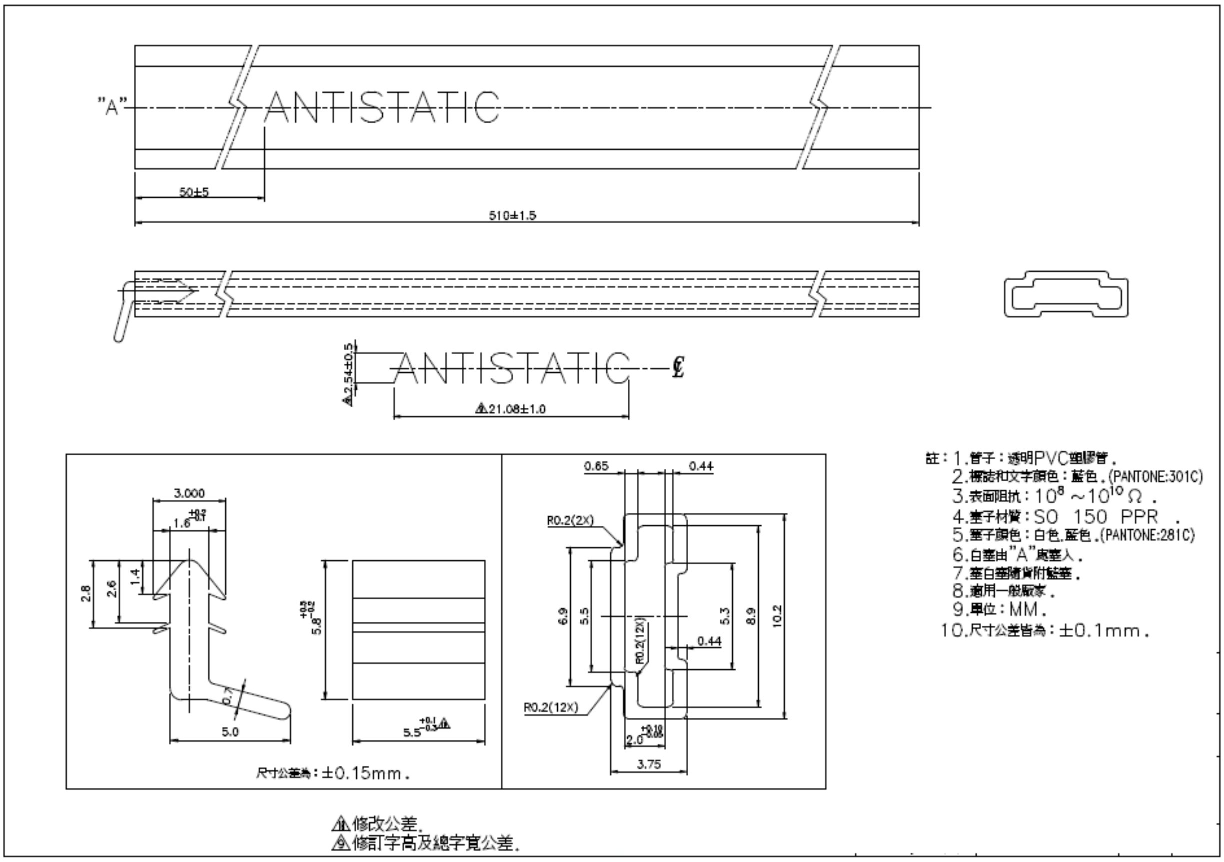
UNIT : MM





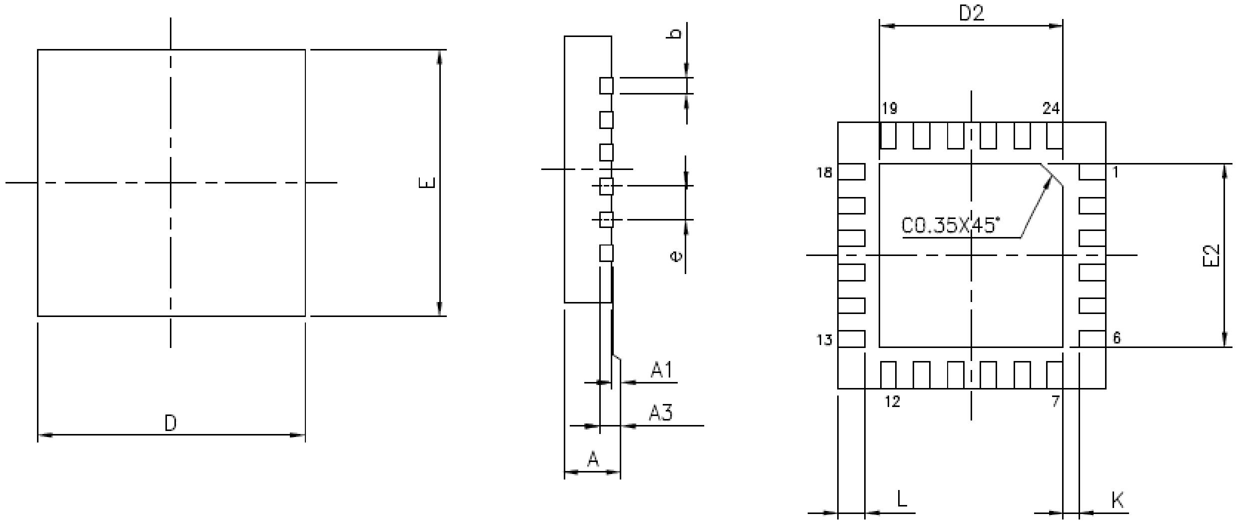
JEDEC MO-150 AH compliant

8.1.2 Tube Dimensions



8.2 QFN24(N024)

8.2.1 Package Dimensions



	D2			E2			JEDEC
EXPOSED PAD	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	
2.7X2.7	2.60	2.70	2.80	2.60	2.70	2.80	WGGD-6

UNIT : mm

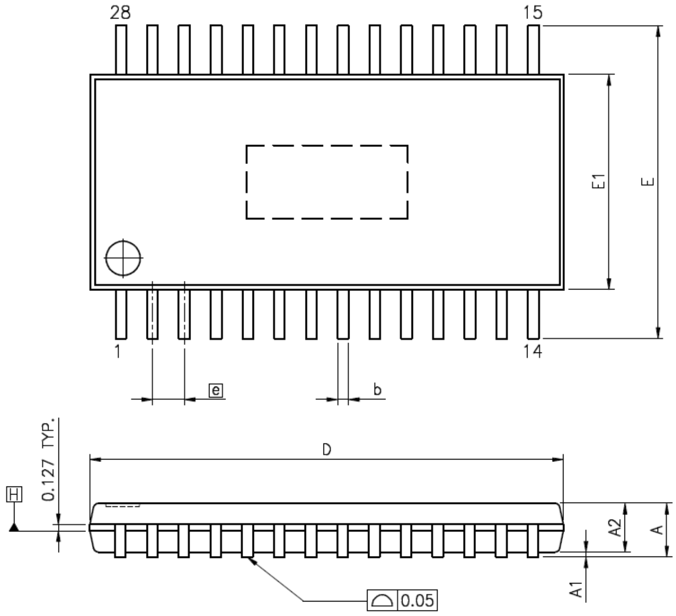
SYMBOLS	MIN.	NOM.	MAX.
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3	0.20 REF.		
b (w/o plating)	0.18	0.25	0.30
D	3.90	4.00	4.10
E	3.90	4.00	4.10
e	0.50 BSC.		
L	0.35	0.40	0.45
K	0.20	—	—

UNIT : mm

JEDEC MO-220 compliant

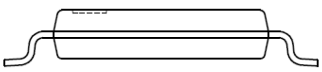
8.3 TSSOP28(T028)

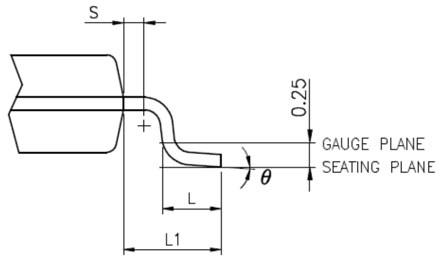
8.3.1 Package Dimensions



VARIATIONS (ALL DIMENSIONS SHOWN IN MM)

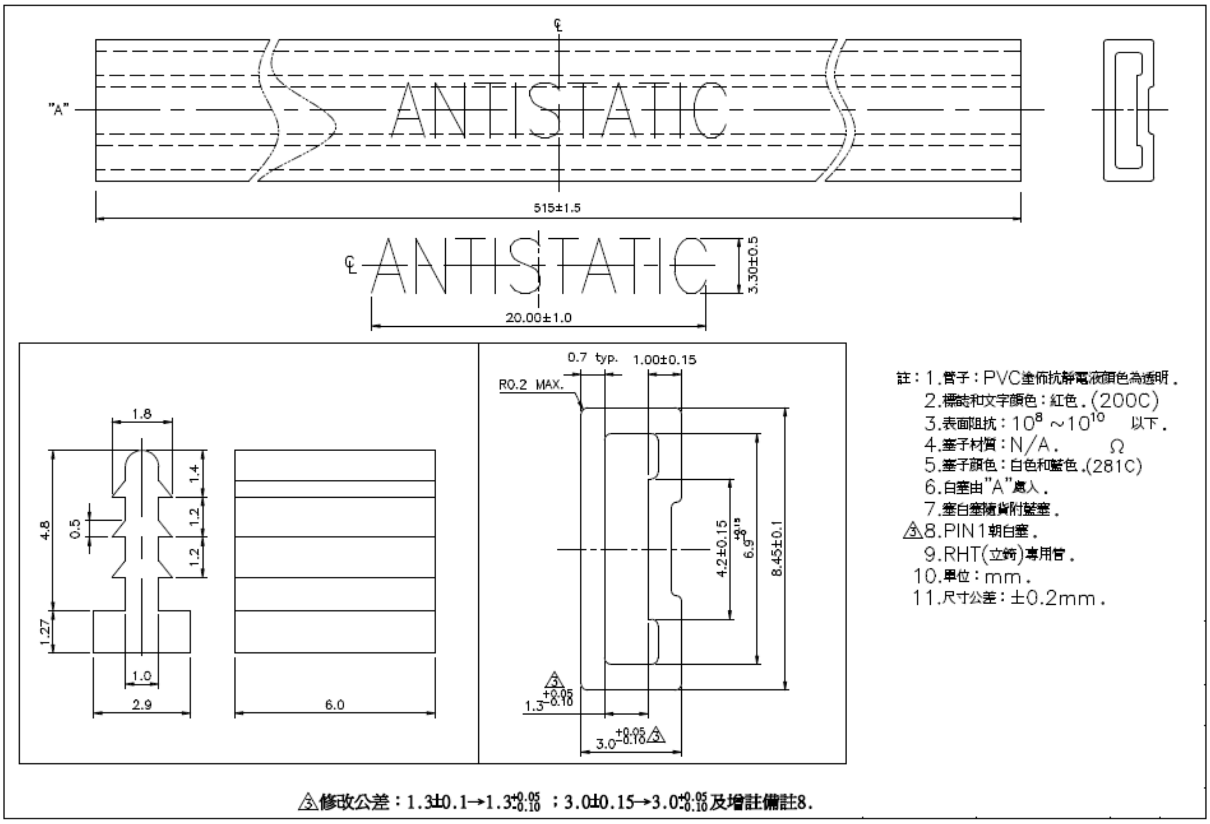
SYMBOLS	MIN.	NOM.	MAX.
A	–	–	1.20
A1	0.00	–	0.15
A2	0.80	1.00	1.05
b	0.19	–	0.30
D	9.60	9.70	9.80
E1	4.30	4.40	4.50
E	6.40 BSC		
e	0.65 BSC		
L1	1.00 REF		
L	0.45	0.60	0.75
S	0.20	–	–
θ	0°	–	8°

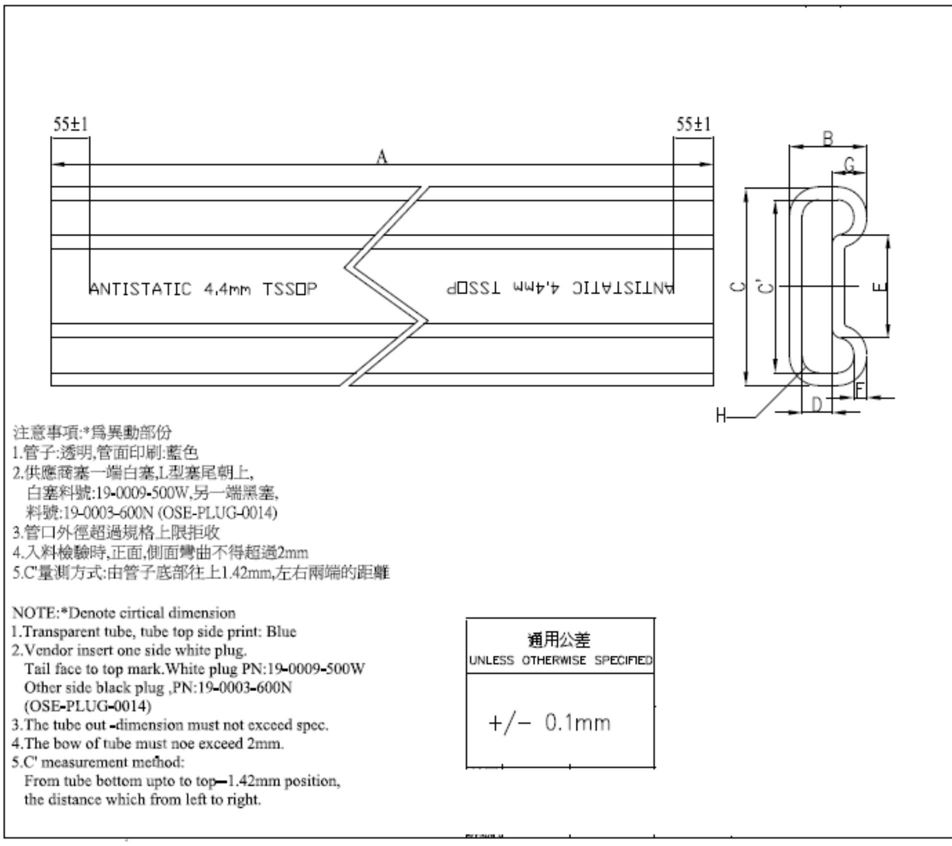




JEDEC MO-153 compliant

8.3.2 Tube Dimensions





Dimenson	SPEC
A	518±1
B	3.1
C	7.82
C'	6.85
D	1.25
E	4.0
F	0.5
G	1.35
H	0.5(TYP)

9. Revision Record

Major differences are stated thereinafter:

Version	Page	Revision Summary
V03	All	First Edition
V07	6	Add in 2.2 TSSOP28 Pin Diagram
	8~9	2.4 SSOP28 Pin out I/O Description order revision
	10~11	Chapter 3 Application Circuit revision
	13	4.1 Internal Block Diagram & 4.2 Related Description and Supporting Documents
	14	revision
	15	4.3 SD18 Network revision
	32	Chapter 5 Register List revision
	35	Chapter 7 Ordering Information revision
		Add in 8.3 TSSOP28(T028)
V08	5~9,14~17,19	Delete the related description and figures of Serial Communication SPI module.
	10~11	Add in 2.5 TSSOP28 Pin out I/O Description
	12~13	Add in 2.6 QFN24 Pin out I/O Description
V10	21	Update Internal RC Oscillator frequency spec