



HY11P54
Datasheet
8-Bit RISC-like Mixed Signal Microcontroller
Embedded 4x32 LCD Driver
Low Noise Amplifier
18-Bit $\Sigma\Delta$ ADC

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1. 特點

- 8 位元加強型精簡指令集，共有 66 個指令
包含硬體乘法指令及查表指令
- 2.2V to 3.6V 工作電壓範圍，-40~85°C 工作溫度範圍。
- 外部石英震盪器及內部高精度 RC 震盪器，6 種 CPU 工作時脈切換選擇，可讓使用者達到最佳省電規劃
 - 運行模式 300uA@2MHz
 - 待機模式 3uA@28KHz
 - 休眠模式 1uA
- 8KWord OTP (One Time Programmable) Type 程式記憶體，256Byte 資料記憶體
- Brownout detector 及 Watch dog Timer，可防止 CPU 進入死機模式。
- 18bit 全差動輸入 $\Sigma\Delta$ ADC 類比數位轉換器
 - 內置 PGA (Programmable Gain Amplifier) 及可有 1/4、1/2、1、.....128 倍多種輸入信號放大倍率選擇
 - 內置輸入零點調整，可針對不同應用增加其量測範圍
 - 可選擇不同的數據輸出速率，最高可達 1.95ksps
- 超低輸入雜訊(<1uVpp) 運算放大器，可提供高輸出阻抗小訊號的放大及小電流的電壓轉換
- 1.0V 的內部類比電路共地電壓源，具有 Push-Pull 驅動能力，可提供傳感器驅動電壓
- LVD 低電壓檢測功能具 14 段檢測電壓設置與外部輸入電壓檢測功能
- 類比電壓源 VDDA 2.4V, 具 10mA 穩壓電壓源輸出能力
- 4x32 LCD 液晶驅動器
 - 1/4 Duty、1/3 Bias
 - 內建 Charge Pump 穩壓線路，可提供 4 種 LCD 偏壓
- 8-bit Timer A
- 8-bit Timer C 模組具 PWM/PFD 波形產生功能
- Built-In EPROM (BIE)，內建 3.05V 低壓燒錄控制電路
- 串列通訊 EUART 模組
- Support 6 stack level.

Model No.	ADC	Program	Data	Build-IN				LCD		Serial		Pin
		Memory (word)	Memory (byte)	EPROM (word)	OPAMP	TPS	RTC	I/O	Segment	PWM	Interface	
HY11P54-L100	9-CH	8k	256	64,LV	1	-	Y	13xl + 12xIO	4x32	1-CH	EUART	LQFP 100
HY11P54-L064	7-CH	8k	256	64,LV	1	-	Y	10xl + 10xIO	4x30	1-CH	EUART	LQFP 64
HY11P54-NS48	8-CH	8k	256	64,LV	1	-	Y	11xl + 11xIO	-	1-CH	EUART	QFN 48

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8-Bit RISC-like Mixed Signal Microcontroller

2. 引腳定義

2.1 HY11P54 LQFP100 引腳圖

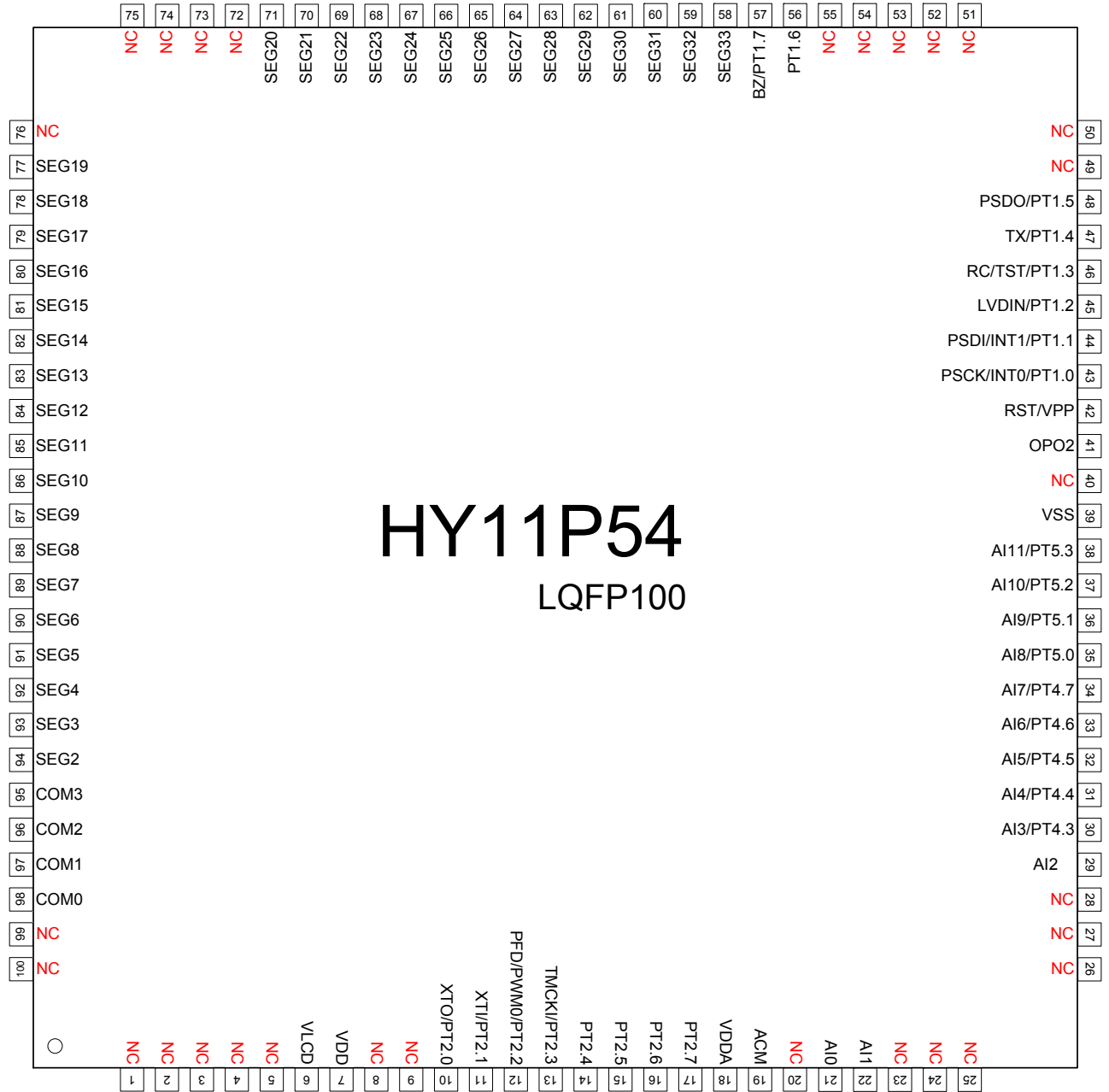


圖 2-1 HY11P54 LQFP100 引腳圖

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2.2 HY11P54 LQFP64 引腳圖

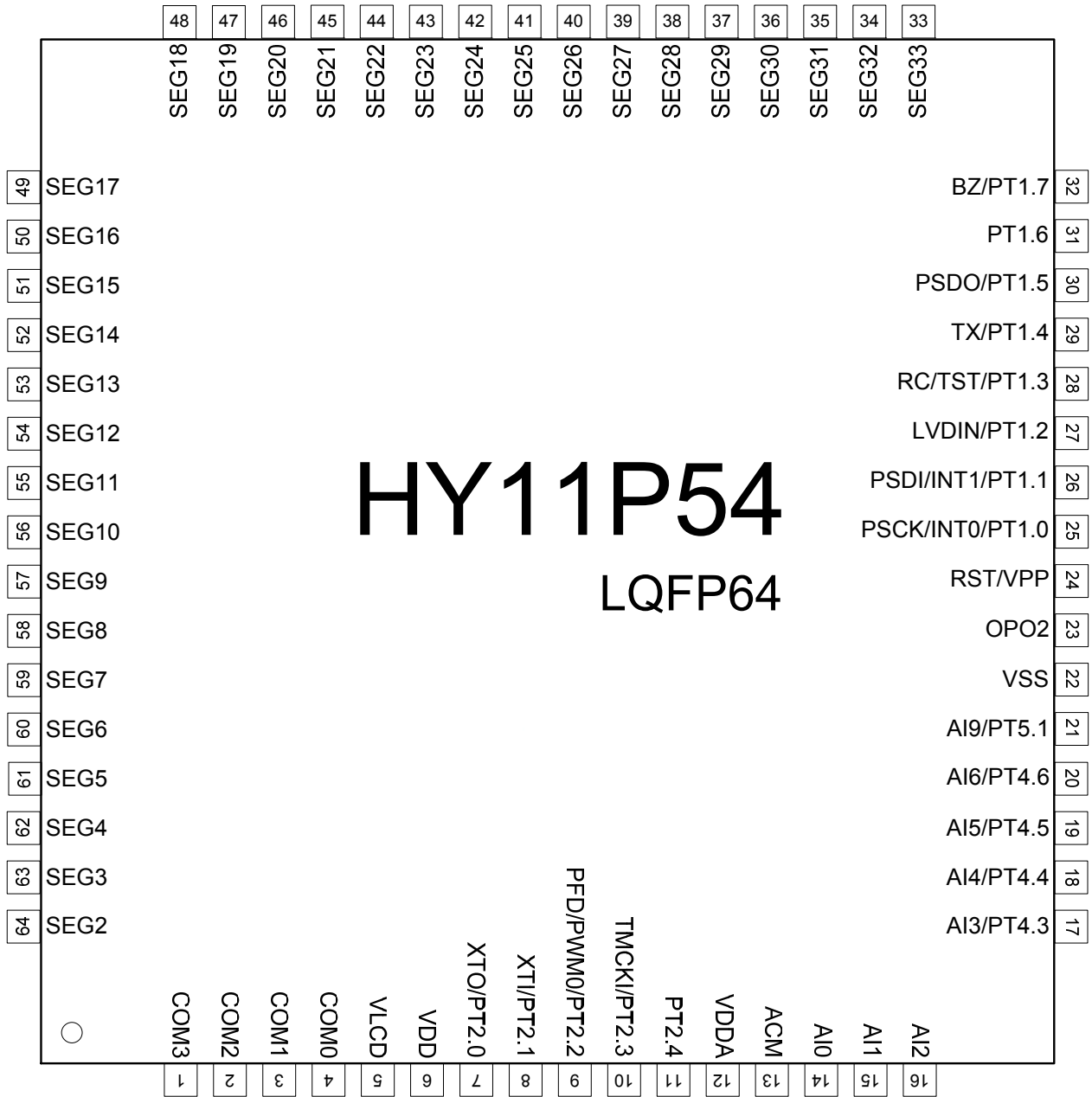


圖 2-2 HY11P54 LQFP64 引腳圖

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2.3 HY11P54 QFN48 引腳圖

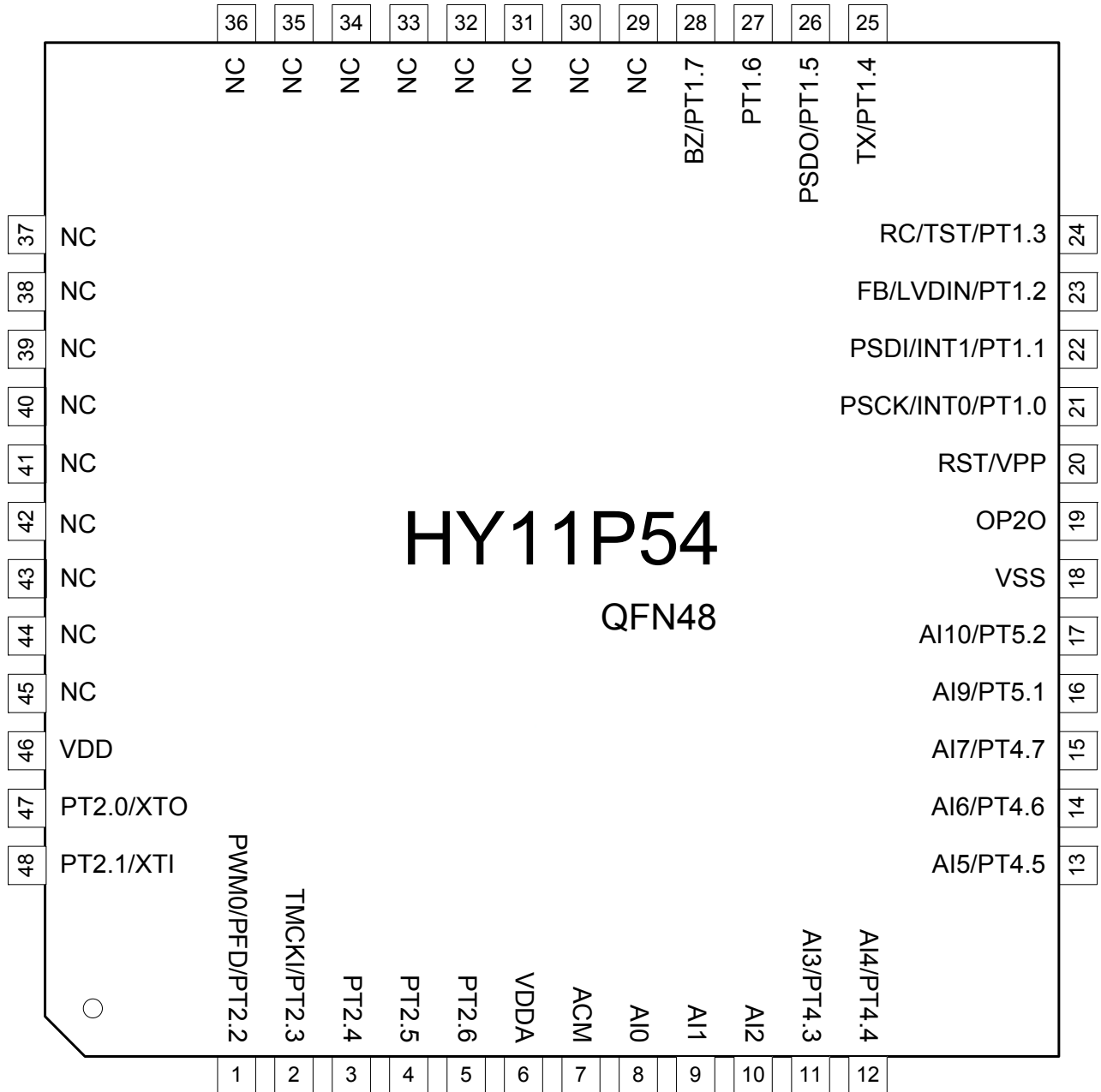


圖 2-3 HY11P54 QFN48 引腳圖

註 1：VPP 與 RST 復用同一接口，非燒錄 EPROM 時禁止輸入電壓超過 5.8V

註 2：TST 與 PT1.3 復用同一接口，操作時禁止輸入電壓超過 VDD+0.3V

註 3：若不將 PT1.3 設定成外部引腳按鍵，可以提升抗干擾能力

2.4 HY11P54 I/O 定義與說明

“I/O”輸入/輸出, “I”輸入, “O”輸出, “S”史密斯觸發, “C”CMOS 特性兼容輸出與輸入, “P”電壓源, “A”類比通道

QFN48 引腳編號	LQFP64 引腳編號	LQFP100 引腳編號	引腳名稱	引腳特性		功能說明
			HY11P54	緩衝	緩衝	
-	5	6	VLCD	P	P	LCD 的電壓源
46	6	7	VDD	P	P	晶片工作電壓源
47	7	10	PT2.0/XTO	I/O	S	數位輸入/輸出 外接振盪器輸出端
			PT2.0 XTO	A	A	
48	8	11	PT2.1/XTI	I/O	S	數位輸入/輸出 外接振盪器輸入端
			PT2.1 XTI	A	A	
1	9	12	PT2.2/PWM0/PFD	I/O	C	數位輸入/輸出 PWM 輸出接口 PFD 輸出接口
			PT2.2	O	C	
			PWM0 PFD	O	C	
2	10	13	PT2.3/TMCKI	I/O	S	數位輸入/輸出 TIMERC 時脈源輸入接口
			PT2.3 TMCKI	I	S	
3	11	14	PT2.4	I/O	S	數位輸入/輸出
4	-	15	PT2.5	I/O	S	數位輸入/輸出
5	-	16	PT2.6	I/O	S	數位輸入/輸出
-	-	17	PT2.7	I/O	S	數位輸入/輸出
6	12	18	VDDA	P	P	穩壓器輸出, 類比電路電壓源
7	13	19	ACM	P	P	內部類比電路共地引腳
8	14	21	AI0	A	A	類比輸入通道
9	15	22	AI1	A	A	類比輸入通道
10	16	29	AI2	A	A	類比輸入通道
11	17	30	PT4.3/AI3	I	S	數位輸入/輸出 類比輸入通道
			PT4.3 AI3	A	A	
12	18	31	PT4.4/AI4	I	S	數位輸入/輸出 類比輸入通道
			PT4.4 AI4	A	A	
13	19	32	PT4.5/AI5	I	S	數位輸入/輸出
			PT4.5	I	S	數位輸入/輸出

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			AI5	A	A	類比輸入通道	
14	20	33	PT4.6/AI6	PT4.6 AI6	I A	S A	數位輸入/輸出 類比輸入通道
15	-	34	PT4.7/AI7	PT4.7 AI7	I A	S A	數位輸入/輸出 類比輸入通道
-	-	35	PT5.0/AI8	PT5.0 AI8	I A	S A	數位輸入/輸出 類比輸入通道
16	21	36	PT5.1/AI9	PT5.1 AI9	I A	S A	數位輸入/輸出 類比輸入通道
17	-	37	PT5.2/AI10	PT5.2 AI10	I A	S A	數位輸入/輸出 類比輸入通道
-	-	38	PT5.3/AI11	PT5.3 AI11	I A	S A	數位輸入/輸出 類比輸入通道
18	22	39	VSS		P	P	晶片工作電壓源接地端
19	23	41	OPO2		A	A	運算放大器輸出
20	24	42	RST/VPP	RST VPP	I P	S P	復位晶片 EPROM 讀/寫時的電壓源
21	25	43	PT1.0/INT0/PSCK	PT1.0 INT0 PSCK	I I I	C S S	數位輸入 中斷源 INT0 OTP 讀/寫介面 SCK 接口
22	26	44	PT1.1/INT1/PSDI	PT1.1 INT1 PSDI	I I I	C S S	數位輸入 中斷源 INT1 OTP 讀/寫介面 SDI 接口
23	27	45	PT1.2/LVDIN	PT1.2 LVDIN	I A	C A	數位輸入 LVD 外部信號輸入接口
24	28	46	PT1.3/TST/RC	PT1.3 TST	I I	C S	數位輸入 測試模式致能輸入 (未開

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			RC	I	S	放) EUART 訊介面 RC 接口
25	29	47	PT1.4/TX PT1.4 TX	I/O I	C S	數位輸入/輸出 EUART 訊介面 TX 接口
26	30	48	PT1.5/PSDO PT1.5 PSDO	I/O O	S C	數位輸入/輸出 OTP 讀/寫介面 SDO 接口
27	31	56	PT1.6 PT1.6	I/O	S	數位輸入/輸出
28	32	57	PT1.7/BZ PT1.7 BZ	I/O O	S C	數位輸入/輸出 蜂鳴器輸出端
-	33	58	SEG33	O	A	LCD 的 Segment 輸出
-	34	59	SEG32	O	A	LCD 的 Segment 輸出
-	35	60	SEG31	O	A	LCD 的 Segment 輸出
-	36	61	SEG30	O	A	LCD 的 Segment 輸出
-	37	62	SEG29	O	A	LCD 的 Segment 輸出
-	38	63	SEG28	O	A	LCD 的 Segment 輸出
-	39	64	SEG27	O	A	LCD 的 Segment 輸出
-	40	65	SEG26	O	A	LCD 的 Segment 輸出
-	41	66	SEG25	O	A	LCD 的 Segment 輸出
-	42	67	SEG24	O	A	LCD 的 Segment 輸出
-	43	68	SEG23	O	A	LCD 的 Segment 輸出
-	44	69	SEG22	O	A	LCD 的 Segment 輸出
-	45	70	SEG21	O	A	LCD 的 Segment 輸出
-	46	71	SEG20	O	A	LCD 的 Segment 輸出
-	47	77	SEG19	O	A	LCD 的 Segment 輸出
-	48	78	SEG18	O	A	LCD 的 Segment 輸出
-	49	79	SEG17	O	A	LCD 的 Segment 輸出
-	50	80	SEG16	O	A	LCD 的 Segment 輸出
-	51	81	SEG15	O	A	LCD 的 Segment 輸出
-	52	82	SEG14	O	A	LCD 的 Segment 輸出
-	53	83	SEG13	O	A	LCD 的 Segment 輸出
-	54	84	SEG12	O	A	LCD 的 Segment 輸出
-	55	85	SEG11	O	A	LCD 的 Segment 輸出
-	56	86	SEG10	O	A	LCD 的 Segment 輸出

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-	57	87	SEG9	O	A	LCD 的 Segment 輸出
-	58	88	SEG8	O	A	LCD 的 Segment 輸出
-	59	89	SEG7	O	A	LCD 的 Segment 輸出
-	60	90	SEG6	O	A	LCD 的 Segment 輸出
-	61	91	SEG5	O	A	LCD 的 Segment 輸出
-	62	92	SEG4	O	A	LCD 的 Segment 輸出
-	63	93	SEG3	O	A	LCD 的 Segment 輸出
-	64	94	SEG2	O	A	LCD 的 Segment 輸出
-	1	95	COM3	O	A	LCD 的 Common 輸出
-	2	96	COM2	O	A	LCD 的 Common 輸出
-	3	97	COM1	O	A	LCD 的 Common 輸出
-	4	98	COM0	O	A	LCD 的 Common 輸出
-	-	Others	NC	-	-	Not connect

3. 應用電路

3.1 橋式感測器

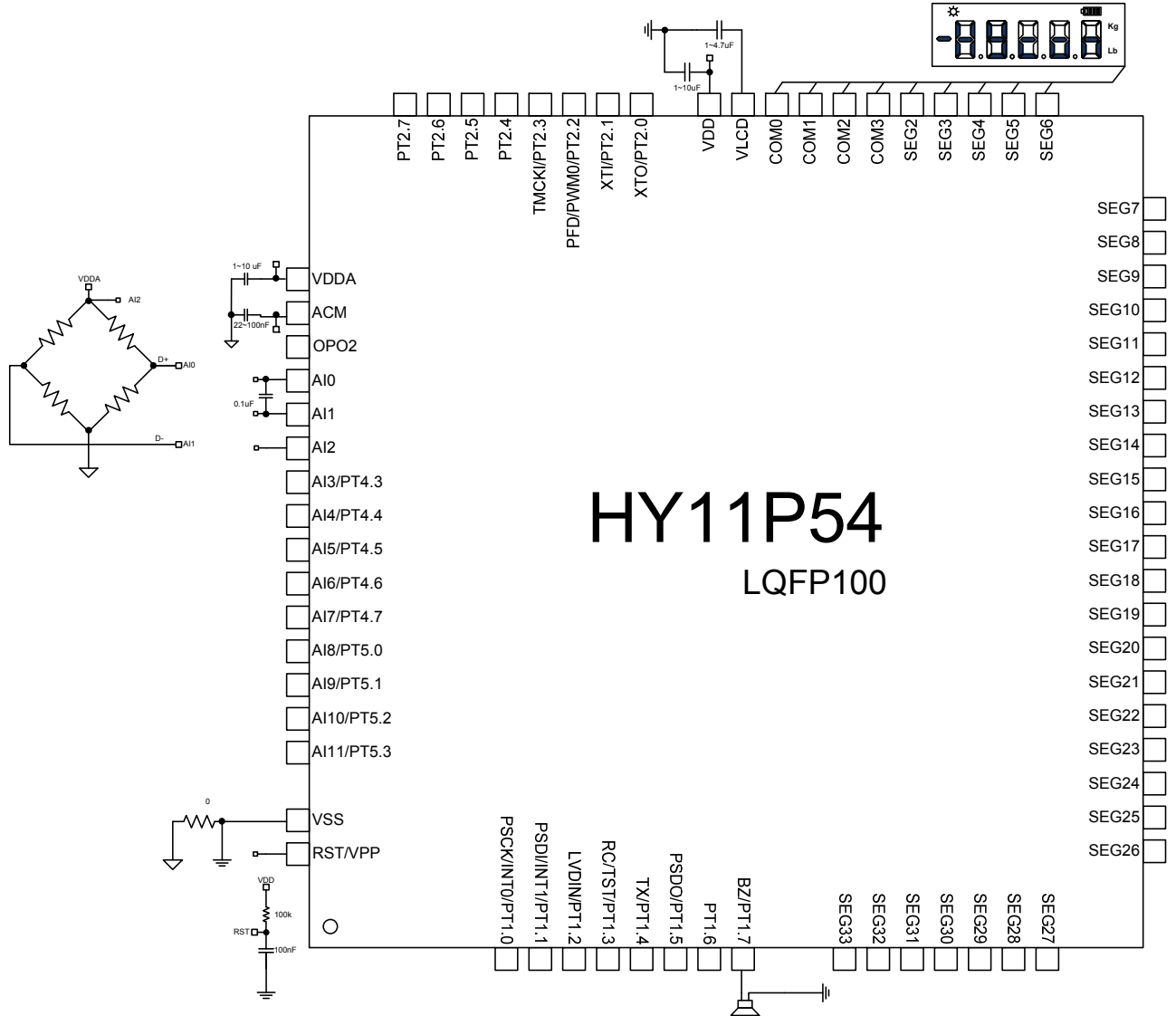


圖 3-1 橋式感測器應用電路

註：Load Cell 零點電壓位置可透過 DCSET[2:0] 進行偏壓調整。

4. 功能概述

4.1 内部方块圖

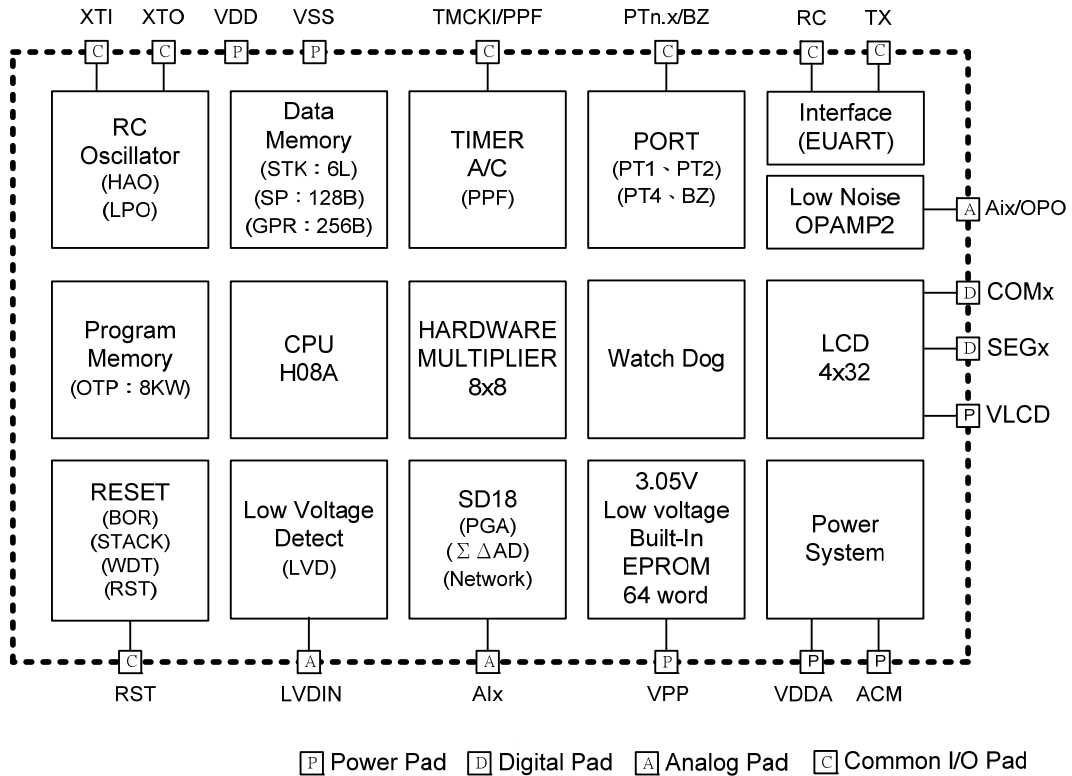


圖 4-1 HY11P54 内部方块圖

4.2 相關說明與支援文件

晶片功能相關使用說明書

DS-HY11P54-Vxx	HY11P54 說明書
UG-HY11S14-Vxx	HY11Pxx 系列使用說明書
APD-CORE002-Vxx	H08A 指令說明書

開發工具相關使用說明書

APD-HYIDE006-Vxx	HY11xxx 系列開發工具軟體使用說明書
APD-HYIDE005-Vxx	HY11xxx 系列開發工具硬體使用說明書
APD-OTP001-Vxx	OTP 產品燒錄引腳說明書

產品生產相關使用說明書

APD-HYIDE004-Vxx	HY1xxxx 系列生產線專用燒錄器說明書
BDI-HY11P54-Vxx	HY11P54 個別產品的裸片打線資訊

4.3 SD18 Network

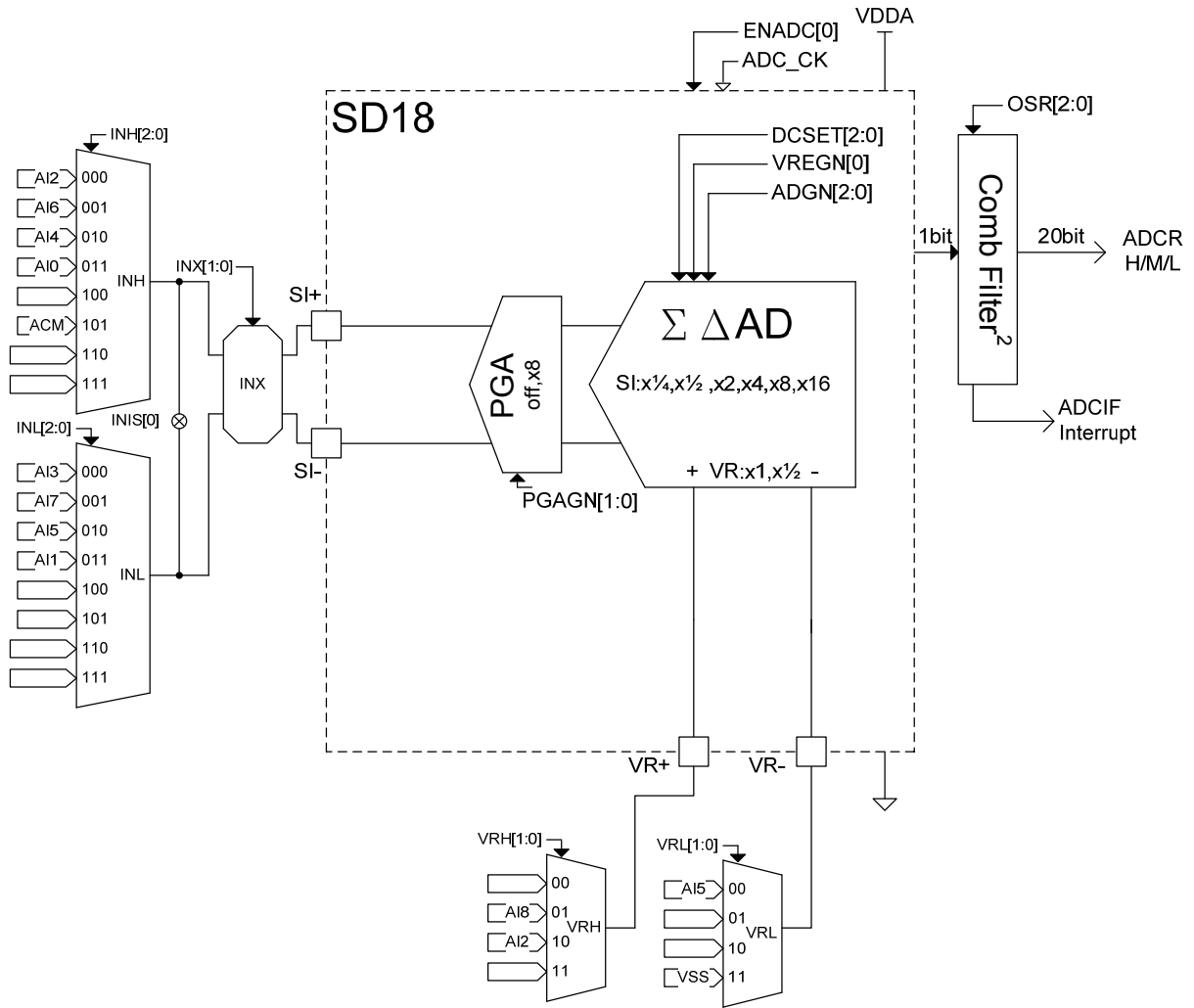
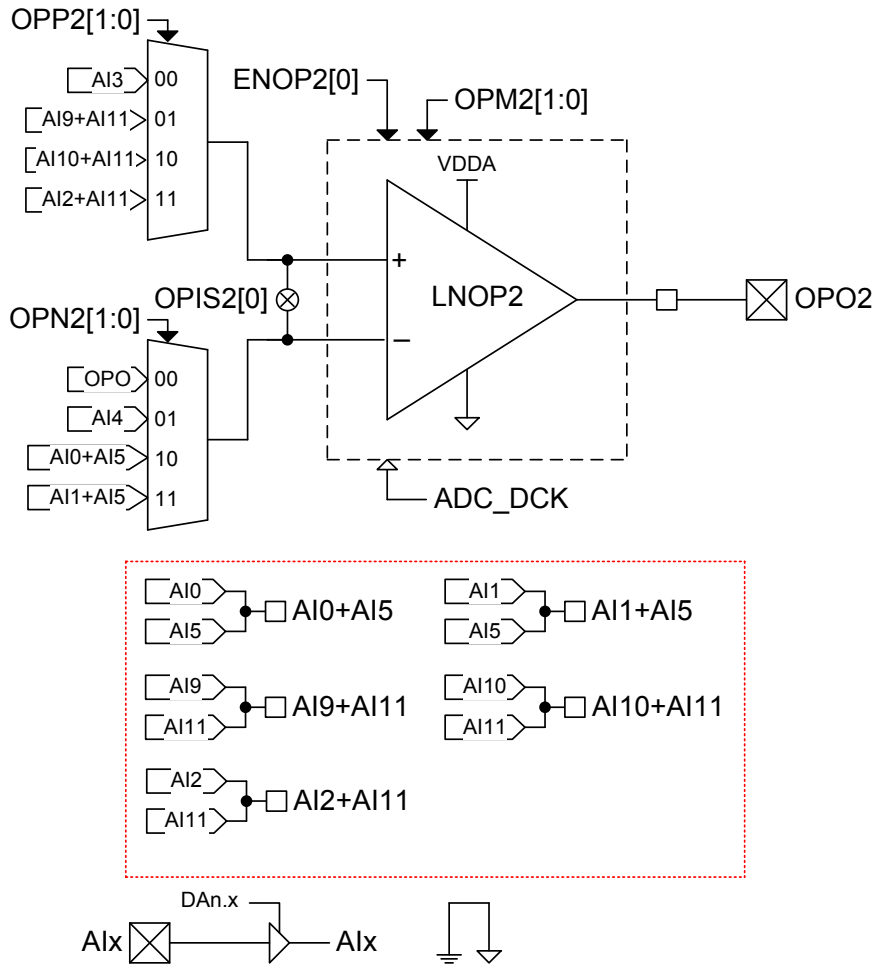


图 4-2 SD18 Network

4.4 LNOP2 Network



4-3 Low Noise OPAMP2 Network

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5. 暫存器列表

"0" no use, "1" read/write, "w" write, "r" read, "r0" only read 0, "r1" only read 1, "w0" only write 0, "w1" only write 1													
"x" unimplemented bit, "u" unknown, "u" unchanged, "d" depends on condition													
Address	File Name	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	A-RESET	I-RESET	R/W	
00H	INDF0	Contents of FSR0 to address data memory value of FSR0 not changed								N/A	N/A	*****	
01H	POINC0	Contents of FSR0 to address data memory value of FSR0 post-incremented								N/A	N/A	*****	
02H	PODEC0	Contents of FSR0 to address data memory value of FSR0 post-decremented								N/A	N/A	*****	
03H	PRINC0	Contents of FSR0 to address data memory value of FSR0 pre-incremented								N/A	N/A	*****	
04H	PLUSW0	Contents of FSR0 to address data memory value of FSR0 offset by W								N/A	N/A	*****	
05H	INDF1	Contents of FSR1 to address data memory value of FSR0 not changed								N/A	N/A	*****	
06H	POINC1	Contents of FSR1 to address data memory value of FSR0 post-incremented								N/A	N/A	*****	
07H	PODEC1	Contents of FSR1 to address data memory value of FSR0 post-decremented								N/A	N/A	*****	
08H	PRINC1	Contents of FSR1 to address data memory value of FSR0 pre-incremented								N/A	N/A	*****	
09H	PLUSW1	Contents of FSR1 to address data memory value of FSR0 offset by W								N/A	N/A	*****	
0FH	FSR0H									FSR0[8]xu	*****
10H	FSR0L	Indirect Data Memory Address Pointer 0 Low Byte, FSR0[7:0]								xxxx xxxx	uuuu uuuu	*****	
11H	FSR1H									FSR1[8]xu	*****
12H	FSR1L	Indirect Data Memory Address Pointer 1 Low Byte, FSR1[7:0]								xxxx xxxx	uuuu uuuu	*****	
16H	TOSH					TOS[11]	TOS[10]	TOS[9]	TOS[8]00000000	*****	
17H	TOSL	Top-of-Stack Low Byte (TOS<7:0>)								0000 0000	0000 0000	*****	
18H	STKPTR	STKFL	STKUN	STKOV					STKPR[2:0]	000 .000	000 .000	r,rw 0,rw 0,-,r,r,r	
1AH	PCLATH					PC[11]	PC[10]	PC[9]	PC[8]00000000	*****	
1BH	PCLATL	PC Low Byte for PC<7:0>								0000 0000	0000 0000	*****	
1DH	TBLPTRH					TBLPTR[11]	TBLPTR[10]	TBLPTR[9]	TBLPTR[8]00000000	*****	
1EH	TBLPTRL	Program Memory Table Pointer Low Byte (TBLPTR<7:0>)								0000 0000	0000 0000	*****	
1FH	TBLDH	Program Memory Table Latch High Byte								0000 0000	0000 0000	*****	
20H	TBLDL	Program Memory Table Latch Low Byte								0000 0000	0000 0000	*****	
21H	PRODH	Product Register of Multiply High Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
22H	PRODL	Product Register of Multiply Low Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
23H	INTE1	GIE	ADCFE	TMCFE	TMAIE		WDTIE	E1IE	E0IE	000 .0000	000 .0000	*****	
24H	INTE2	TXIE	RCIE	TMCFE	TMAIF		WDTIF	E1IF	E0IF	00 .0000	00 .0000	*****	
26H	INTF1	ADCF		TMCF	TMAIF		WDTIF	E1IF	E0IF	.00 .0000	.00 .0000	*****	
27H	INTF2	TXIF	RCIF							00 .0000	00 .0000	*****	
29H	WREG	Working Register								xxxx xxxx	uuuu uuuu	*****	
2AH	BSRCON									BSR[0]00	*****
2BH	STATUS					C	DC	N	OV	Zxu	*****
2CH	PSTATUS	PD	TO	IDLEB	BOR	SKERR				000d .0	uuuu .d	rw 0,rw 0,rw 0,rw 0,-,rw 0,-,-	
2DH	LVDON	LVDFG		LVD	LVDON	VLDX[3:0]				.000 0000	.000 0000	*****	
30H	PWRON	ENVDDA	VDDAX[1:0]=11		ENACM	ENLEDP		ENHAO		0x0 .0	0x0 .0	*****	
31H	MCKCN1	ADCS[2:0]		ADCOCK	XTHSP	XTSP	ENXT	ENHAO		0000 0001	0000 0001	*****	
32H	MCKCN2			LSCK	HSCK	HSS[1:0]	CPUCK[1:0]		.00 0000		.00 0000	*****	
33H	MCKCN3	LCS[2:0]				PERCK	BZS[2:0]		000 .0000		000 .0000	*****	
39H	ADCRH	ADC conversion memory High Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
3AH	ADCRM	ADC conversion memory Middle Byte								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
3BH	ADCL	ADC conversion memory Low Byte								xxxx 0000	uuuu 0000	r,r,r,r r0,r0,r0,r0	
3CH	ADCCN1	ENADC	ENCHP		PGAGN[1:0]	ADGN[2:0]				0 .00 0000	0 .00 0000	*****	
3DH	ADCCN2	INBUF=0		VRBUF=0	VREGN	DCSET[2:0]				.xx 0000	.xx 0000	*****	
3EH	ADCCN3	OSR[2:0]				OSR[3]				000 .0	000 .0	*****	
3FH	AINET1	INH[2:0]		INL[2:0]		INS				0000 000x	0000 000x	*****	
40H	AINET2	VRH[1:0]		INX[1:0]		VRL[1:0]				xx00 xx0x	xx00 xx0x	*****	
41H	TMACN	ENTMA	TMACK	TMA[1:0]	ENWDT	WDT[2:0]				0000 0000	0000 0000	***** w 1,1,1	
42H	TMAR	TimerA data register								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
46H	TMCCN	ENTMC	TMOCK[1:0]	TMCS1[2:0]		TMCS0[1:0]				0000 0000	0000 0000	*****	
47H	PRC	TimerC programmable register								1111 1111	1111 1111	*****	
48H	TMCR	TimerC register								0000 0000	0000 0000	r,r,r,r r,r,r,r	
4FH	PWMCN	ENPWM	ENFPD	PWMRL[1:0]						0000	0000	*****	
51H	PWMR	PWM MSB Byte register								xxxx xxxx	uuuu uuuu	*****	
52H	LDCCN1	ENLCD	LCDFR	VLCDX[1:0]	LCDBF	LCDBI[1:0]=10				0000 0xxx	0000 0xxx	*****	
53H	LDCCN2	LCDBL	LCDMX[1:0]=11						0xxx xxxx		0xxx xxxx	*****	
54H	LCD0	Segment SEG2@[3:0] and SEG3@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
55H	LCD1	Segment SEG4@[3:0] and SEG5@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
56H	LCD2	Segment SEG6@[3:0] and SEG7@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
57H	LCD3	Segment SEG8@[3:0] and SEG9@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
58H	LCD4	Segment SEG10@[3:0] and SEG11@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
59H	LCD5	Segment SEG12@[3:0] and SEG13@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
5AH	LCD6	Segment SEG14@[3:0] and SEG15@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
5BH	LCD7	Segment SEG16@[3:0] and SEG17@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
5CH	LCD8	Segment SEG18@[3:0] and SEG19@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
5DH	LCD9	Segment SEG20@[3:0] and SEG21@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu	*****	
63H	URCON	ENSP	ENTX	TX9	TX9D	PARITY	WUE		0000 0 .0		0000 0 .0	*****	
64H	URSTA	RC9D		FERR	FERR	OERR	RCIDL	TRMT	ABDOVF	.000 0110	.000 0110	r,r,r,r r,r,r,rw 0	
65H	BAUDCON					ENCR	RC9	ENADD	ENABD 0000	 0000	*****
66H	BRGRH	Baud Rate Generator Register High Byte								...x xxxx	...u uuuu	*****	
67H	BRGRL	Baud Rate Generator Register Low Byte								xxxx xxxx	uuuu uuuu	*****	
68H	TXREG	UART Transmit Register								xxxx xxxx	uuuu uuuu	*****	
69H	RCREG	UART Receive Register								xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
6AH	PT4	PT4.7	PT4.6	PT4.5	PT4.4	PT4.3			xxxx x...		uuuu u...	r,r,r,r r,r,r,r	
6BH	PT4DA	DA4.7	DA4.6	DA4.5	DA4.4	DA4.3	DA4.2	DA4.1	DA4.0	1111 1111	1111 1111	*****	
6CH	PT4FU	PU4.7	PU4.6	PU4.5	PU4.4	PU4.3			0000 0...		0000 0...	*****	
6DH	PT1	PT1.7	PT1.6	PT1.5	PT1.4	PT1.3	PT1.2	PT1.1	PT1.0	xxxx xxxx	uuuu uuuu	r,r,r,r r,r,r,r	
6EH	TRISC1	TC1.7	TC1.6	TC1.5	TC1.4					0000	0000	*****	
70H	PT1FU	FU1.7	FU1.6	FU1.5	FU1.4	FU1.3	FU1.2	FU1.1	FU1.0	0000 0000	0000 0000	*****	

圖 5-1a HY11P54 暫存器列表

HY11P54

Embedded 18-Bit Σ ADC

8-Bit RISC-like Mixed Signal Microcontroller

"-"no use,"*"read/write,"w"write,"r"read,"r0"only read 0,"r1"only read 1,"w0"only write 0,"w1"only write 1												
"u"unimplemented bit,"x"unknown,"u"unchanged,"d"depends on condition												
Address	File Name	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	A-RESET	I-RESET	R/W
71H	PT1M1					INTEG1[1:0]		INTEG0[1:0]	 0000 0000*
72H	PT1M2		PM1.7[0]						PM1.4[0]	.0. ...0	.0. ...0*
74H	PT2	PT2.7	PT2.6	PT2.5	PT2.4	PT2.3	PT2.2	PT2.1	PT2.0	xxxx xxxx	uuuu uuuu*
75H	TRISC2	TC2.7	TC2.6	TC2.5	TC2.4	TC2.3	TC2.2	TC2.1	TC2.0	0000 0000	0000 0000*
77H	PT2PU	PU2.7	PU2.6	PU2.5	PU2.4	PU2.3	PU2.2	PU2.1	PU2.0	0000 0000	0000 0000*
78H	PT2M1			PM2.2[1]	PM2.2[0]					...00*
80H ~ FFH	GPR0	General Purpose Register as 128Byte								xxxx xxxx	uuuu uuuu*
100H~17FH	GPR1	General Purpose Register as 128Byte								xxxx xxxx	uuuu uuuu*
180H	LCD10	Segment SEG22@[3:0] and SEG23@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
181H	LCD11	Segment SEG24@[3:0] and SEG25@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
182H	LCD12	Segment SEG26@[3:0] and SEG27@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
183H	LCD13	Segment SEG28@[3:0] and SEG29@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
184H	LCD14	Segment SEG30@[3:0] and SEG31@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
185H	LCD15	Segment SEG32@[3:0] and SEG33@[7:4] data register of LCD								xxxx xxxx	uuuu uuuu*
192H	PT5					PT5.3	PT5.2	PT5.1	PT5.0 xxxx uuuu	r,r,r,r r,r,r,r
193H	PT5DA					DA5.3	DA5.2	DA5.1	DA5.0 1111 1111*
194H	PT5PU					PU5.3	PU5.2	PU5.1	PU5.0 0000 0000*
195H	BIECTRLA					VFP_HIGH		BIEWR	BIERD	1000 d000	1000 d000*r0**
196H	BIEPTRHA	SBMSEL						BIE_ADDR[10:8]		1000 0000	1000 0000	w0,w0,W0,W0,W0,W0,W0
197H	BIEPTRLA	0	0			BIE_ADDR[5:0]				0000 0000	0000 0000	w 0,w 0,.....*
198H	BIEDHA	BIE_DATA[15:8]								xxxx xxxx	xxxx xxxx*
199H	BIEDLA	BIE_DATA[7:0]								xxxx xxxx	xxxx xxxx*
19BH	OPCN2	ENOP2	OPM2[1:0]		OPS2[0]	OPF2[1:0]		OPN2[1:0]		0000 0000	0000 0000*

圖 5-1b HY11P54 暫存器列表

HY11P54

Embedded 18-Bit $\Sigma\Delta$ ADC
8-Bit RISC-like Mixed Signal Microcontroller



6. 電氣特性

Absolute maximum ratings over operating free-air temperature (unless otherwise noted)

- Voltage applied at V_{DD} to V_{SS} -0.2 V to 4.0 V
- Voltage applied to any pin -0.2 V to $V_{DD} + 0.3$ V
- Voltage applied to RST/VPP pin -0.2 V to 6.9 V
- Voltage applied to TST/PT1.3 pin -0.2 V to $V_{DD} + 1$ V
- Diode current at any device terminal ± 2 mA
- Storage temperature, Tstg: (unprogrammed device) -55°C to 150°C
(programmed device) -40°C to 85°C
- Total power dissipation..... 0.5w
- Maximum output current sink by any PORT1 to PORT2 I/O pin..... 25mA

6.1 Recommended operating conditions

$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$, unless otherwise noted

Sym.	Parameter		Test Conditions	Min.	Typ.	Max.	unit
V_{DD}	Supply Voltage		All digital peripherals and CPU	2.2		3.6	V
			Analog peripherals	2.4		3.6	
V_{SS}	Supply Voltage			0		0	
XT	External	Watch crystal	$V_{DD} = 2.2\text{V}$, ENXT[0]=1			32.768K	Hz
	Oscillator	Ceramic resonator			450K	8M	
	Frequency	Crystal			1M	8M	

6.2 Internal RC Oscillator

T_A = 25°C, V_{DD} = 3.0V, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
HAO	High Speed Oscillator frequency	ENHAO[0]=1	1.6	2.0	2.4	MHz
LPO	Low Power Oscillator frequency	V _{DD} supply voltage be enable LPO	22	28	35	KHz

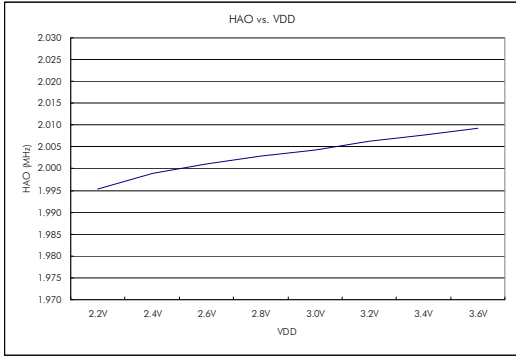


Figure 6.2-1 HAO vs. VDD

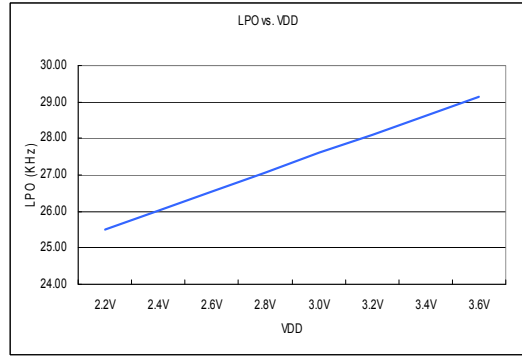


Figure 6.2-2 LPO vs. VDD

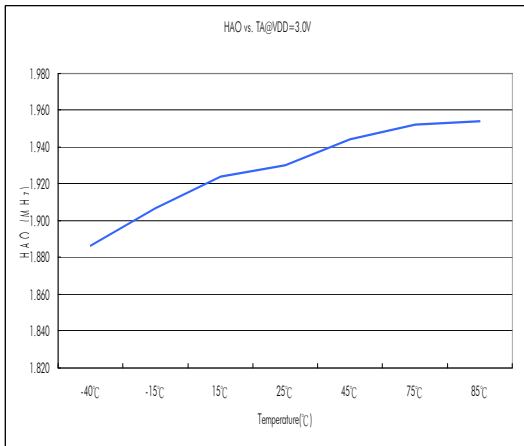


Figure 6.2-3 HAO vs. Temperature

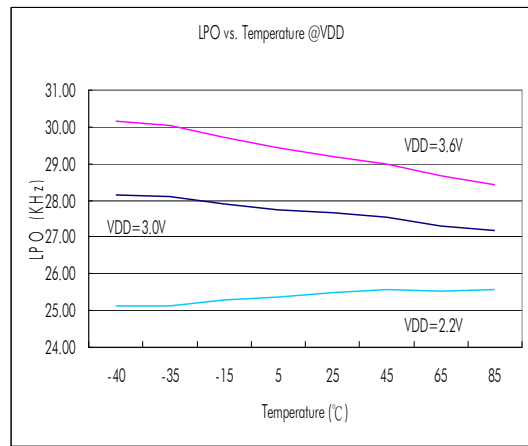


Figure 6.2-4 LPO vs. Temperature

6.3 Supply current into VDD excluding peripherals current

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, \text{OSC_LPO} = 28\text{KHz}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
I_{AM1}	Active mode 1	OSC_CY = 8MHz, OSC_HAO = off, CPU_CK = 8MHz		1.34	2	mA
I_{AM2}	Active mode 2	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 2MHz		0.36	0.55	mA
I_{AM3}	Active mode 3	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 1MHz		0.2	0.3	mA
I_{LP1}	Low Power 1	OSC_CY = 32768Hz, OSC_HAO = off, CPU_CK = 16384Hz		7	12	uA
I_{LP2}	Low Power 2	OSC_CY = off, OSC_HAO = off, CPU_CK = LPO, Idle state		1.65	3	uA
I_{LP3}	Low Power 3	OSC_CY = off, OSC_HAO = off, CPU_CK = off, Sleep state		0.65	1.2	uA

OSC_CY : External Oscillator frequency.

OSC_HAO : Internal High Accuracy Oscillator frequency.

CPU_CK : CPU core work frequency.

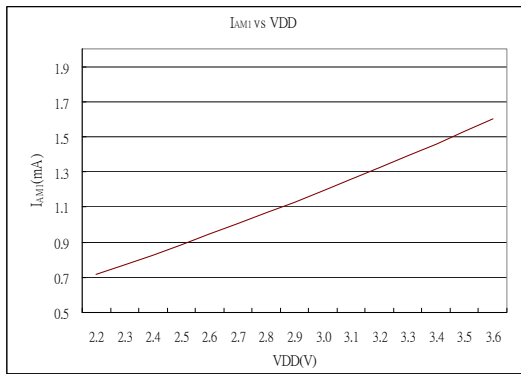


Figure 6.3-1 I_{AM1} vs. VDD

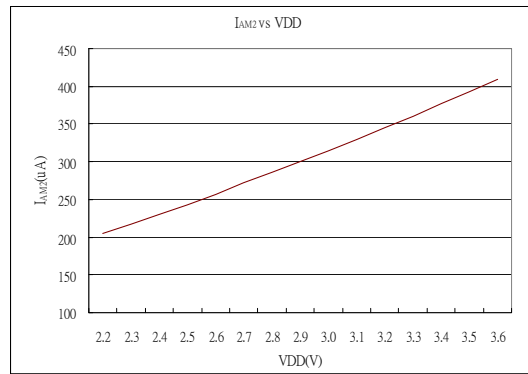


Figure 6.3-2 I_{AM2} vs. VDD

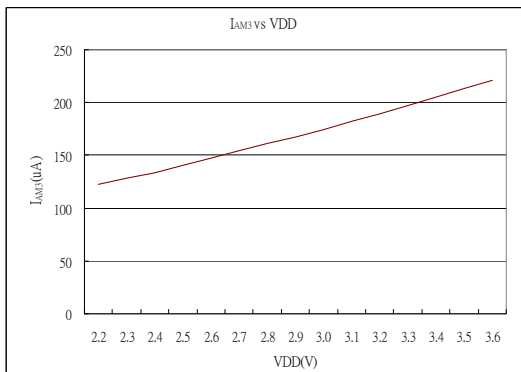


Figure 6.3-3 I_{AM3} vs. VDD

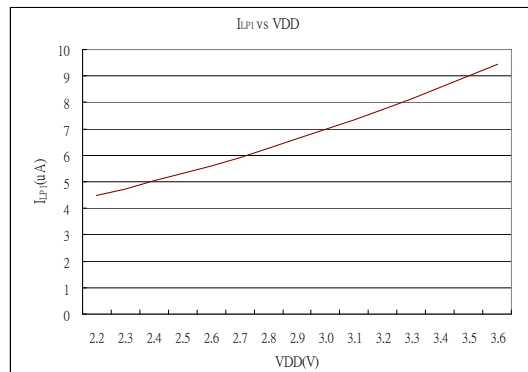


Figure 6.3-4 I_{LP1} vs. VDD

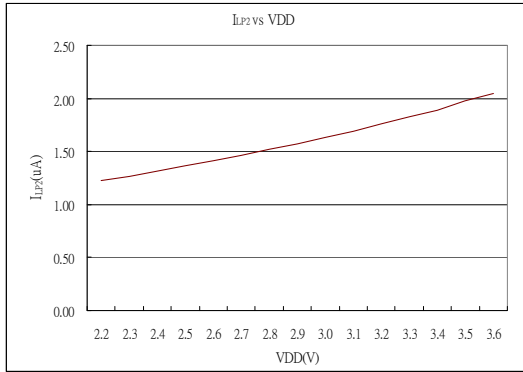


Figure 6.3-5 I_{LP2} vs. VDD

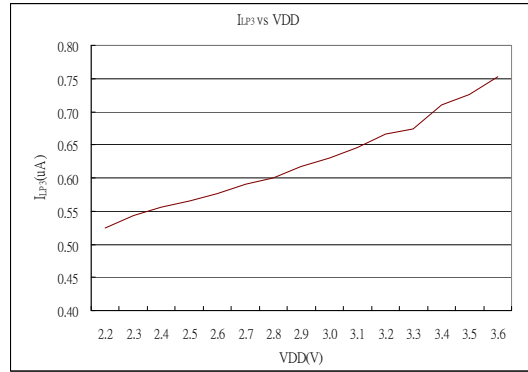


Figure 6.3-6 I_{LP3} vs. VDD

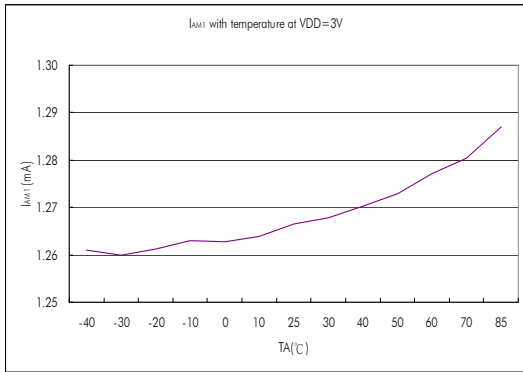


Figure 6.3-7 I_{AM1} vs. Temperature

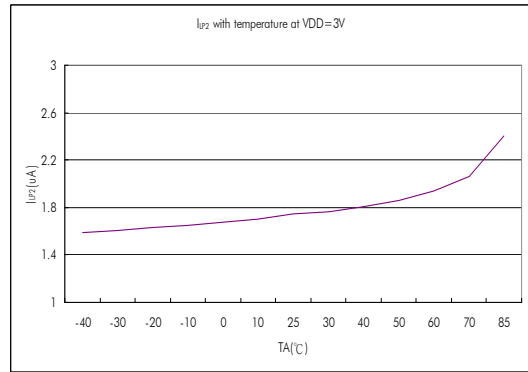


Figure 6.3-8 I_{LP2} vs. Temperature

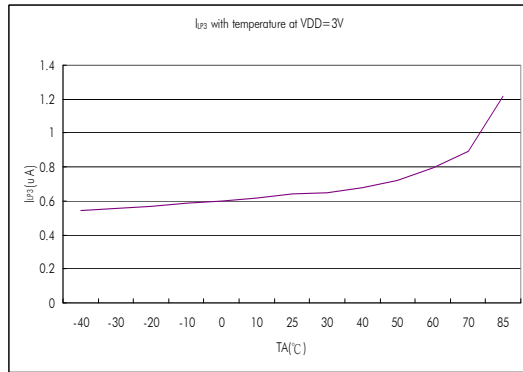


Figure 6.3-9 I_{LP3} vs. Temperature

6.4 Port1~2

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
Input voltage and Schmitt trigger and leakage current and timing						
V_{IH}	High-Level input voltage				2.1	V
V_{IL}	Low-Level input voltage		0.9			
V_{hys}	Input Voltage hysteresis($V_{IH} - V_{IL}$)			0.8		V
I_{LKG}	Leakage Current				0.1	μA
R_{PU}	Port pull high resistance			180		$\text{k}\Omega$
Output voltage and current and frequency						
V_{OH}	High-level output voltage	$I_{OH}=10\text{mA}$	$V_{DD} - 0.3$			V
V_{OL}	Low-level output voltage	$I_{OL}=-10\text{mA}$			$V_{SS} + 0.3$	

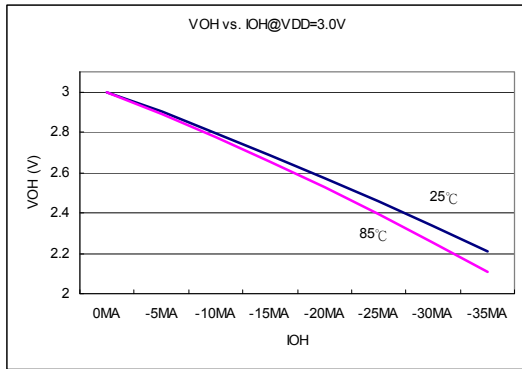


Figure 6.4-1 V_{OH} vs. I_{OH} @VDD=3.0V

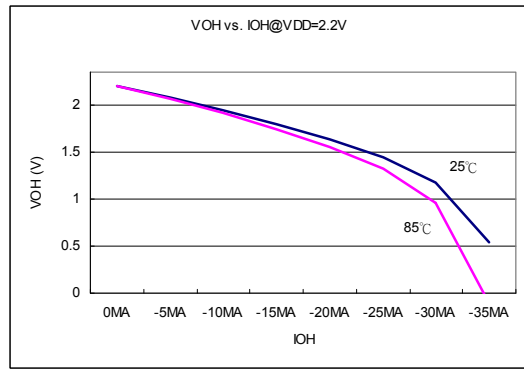


Figure 6.4-2 V_{OH} vs. I_{OH} @VDD=2.2V

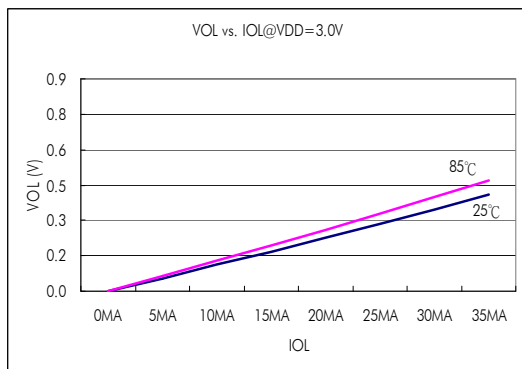


Figure 6.4-3 V_{OL} vs. I_{OL} @VDD=3.0V

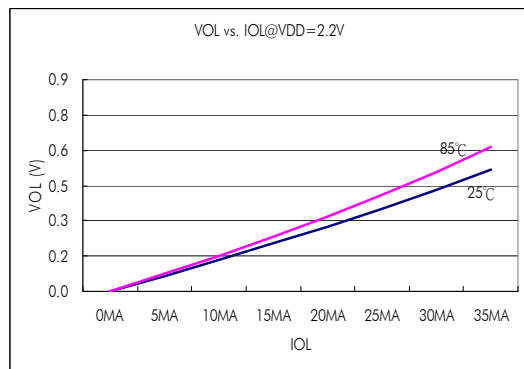


Figure 6.4-4 V_{OL} vs. I_{OL} @VDD=2.2V

6.5 Reset(Brownout, External RST pin, Low Voltage Detect)

$T_A = 25^{\circ}\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit	
BOR	Pulse length needed to accepted reset internally, t_{d-LVR}		2			us	
	V_{DD} Start Voltage to accepted reset internally (L→H), V_{LVR}		1.6	1.85	2.1	V	
	Hysteresis, $V_{HYS-LVR}$			70		mV	
RST	Pulse length needed as RST/VPP pin to accepted reset internally, t_{d-RST}		2			us	
	Input Voltage to accepted reset internally		0.9			V	
	Hysteresis, $V_{HYS-RST}$			0.8		V	
LVD	Operation current, I_{LVD}			10	15	uA	
	External input voltage to compare reference voltage			1.2		V	
	Compare reference voltage temperature drift	$T_A = -40^{\circ}\text{C} \sim 85^{\circ}\text{C}$		100		ppm/°C	
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1110b$			3.3		V	
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1101b$			3.2			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1100b$			3.1			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1011b$			3.0			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1010b$			2.9			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1001b$			2.8			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1000b$			2.7			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0111b$			2.6			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0110b$			2.5			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0101b$			2.4			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0100b$			2.3			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0011b$			2.2			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0010b$			2.1			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0001b$			2.0			
BOR : Brownout Reset LVR : Low Voltage Reset of BOR LVD : Low Voltage Detect RST : External Reset pin							

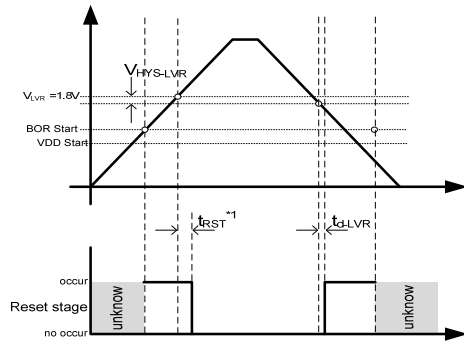


Figure 6.5-1 BOR reset diagram

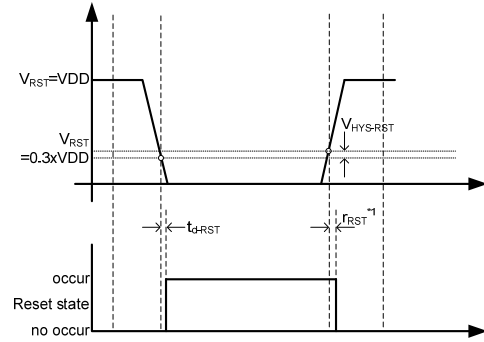


Figure 6.5-2 RST reset diagram

*1 t_{RST} : Please see BOR Introduce of HY11Pxx series User's Guide (UG-HY11S14-Vxx).

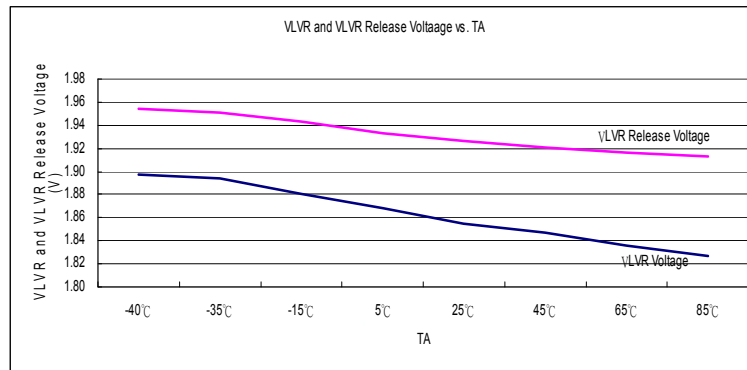


Figure 6.5-3 LVR vs. Temperature

6.6 Power System

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
VDDA	VDDA operation current, I_{VDDA}	$I_L = 0\text{mA}$	VDDAX[1:0]=00b	22			μA
	Select VDDA output voltage	$I_L = 0.1\text{mA}$, $V_{DD} \geq V_{DDA} + 0.25\text{V}$	VDDAX [1:0]=11b	2.4			V
	Dropout voltage	$I_L = 10\text{mA}$	VDDAX [1:0]=11b	250			mV
	Temperature drift		VDDAX [1:0]=11b	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$	50		ppm/ $^\circ\text{C}$
	V_{DD} Voltage drift	$I_L = 0.1\text{mA}$		$V_{DD} = 2.5\text{V} \sim 3.6\text{V}$	± 0.2		%/V
ACM	ACM operation current, I_{ACM}	$I_L = 0\text{mA}$		20			μA
	Output voltage, V_{ACM}	ENACM[0]=1	$I_L = 0\mu\text{A}$	1.0			V
	Output voltage with Load		$I_L = \pm 200\mu\text{A}$	0.98	1.02		V_{ACM}
	Temperature drift	ENACM[0]=1,	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$	50			ppm/ $^\circ\text{C}$
	VDDA Voltage drift	$I_L = 10\mu\text{A}$		100			$\mu\text{V}/\text{V}$

VDDA : Adjust Voltage Regulator
ACM : Analog Common Mode Voltage

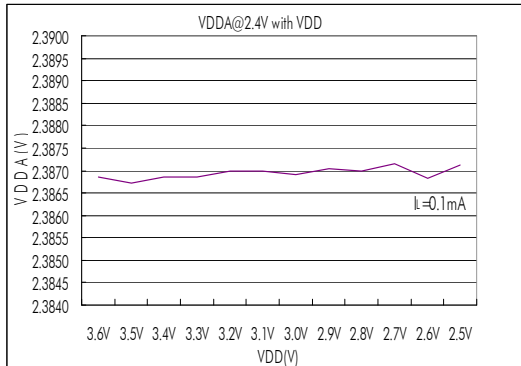


Figure 6.6-1 VDDA $I_L=0.1\text{mA}$ vs. VDD

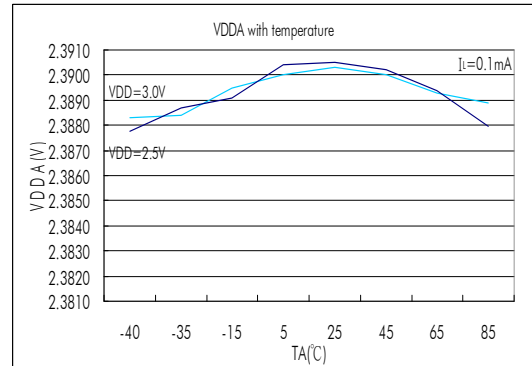


Figure 6.6-2 VDDA $I_L=0.1\text{mA}$ vs. Temperature

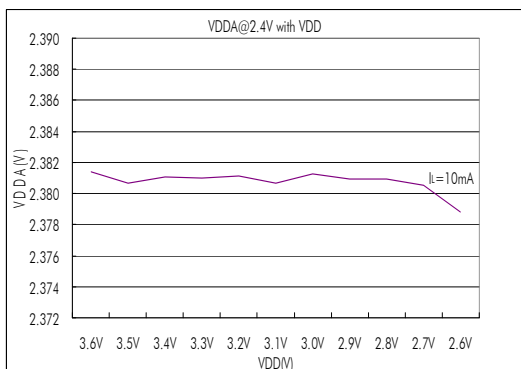


Figure 6.6-3 VDDA $I_L=10\text{mA}$ vs. VDD

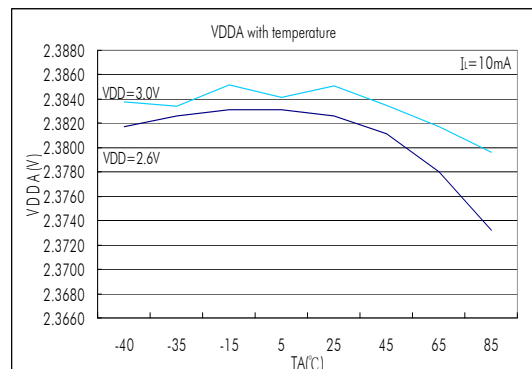


Figure 6.6-4 VDDA $I_L=10\text{mA}$ vs. Temperature

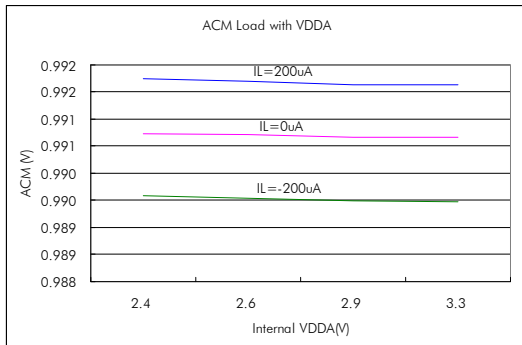


Figure6.6-5 ACM Load vs. VDDA

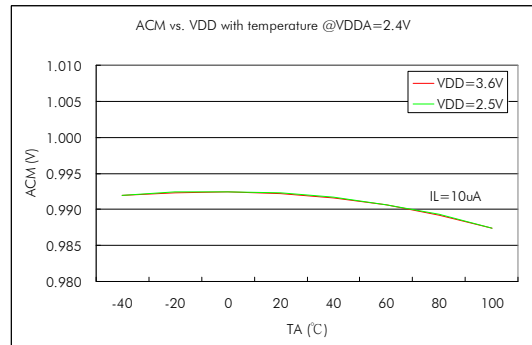


Figure6.6-6 ACM vs. Temperature

6.7 LCD

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, $C_{VLCD} = 4.7\mu\text{F}$, unless otherwise noted.

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit	
I_{LCD}	Operation supply current without output buffer.(all segment turn on)	LCDPR[0]=1	$V_{DD} = 2.2\text{V}$	10		uA	
			$V_{DD} = 3.0\text{V}$				
VLCD	Supply Voltage at VLCD pin	LCDPR[0]=0	2.2		3.6	V	
	Embedded Charge Pump output voltage at VLCD pin	$V_{DD} = 2.2\text{V}$, LCDPR[0]=1, $C_{VLCD} = 4.7\mu\text{F}$	VLCDX[1:0]=11b	2.295	2.55	2.805	V
			VLCDX[1:0]=10b	2.52	2.8	3.08	
			VLCDX[1:0]=01b	2.745	3.05	3.355	
VLCDX[1:0]=00b	2.97	3.3	3.63				
Z_{LCD}	Output impedance with LCD buffer	$f_{LCD} = 128\text{Hz}$, VLCD=3.05V		10		k Ω	

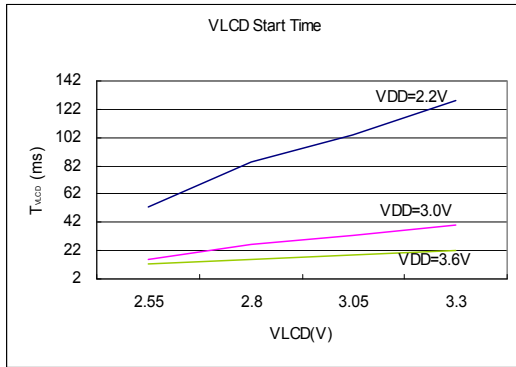


Figure6.7-1 LCD start time

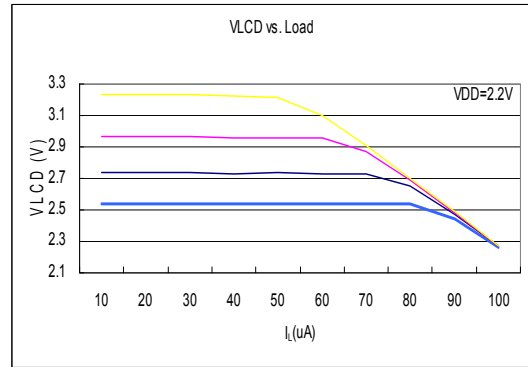


Figure6.7-2 VLCD vs. I_L @VDD=2.2V

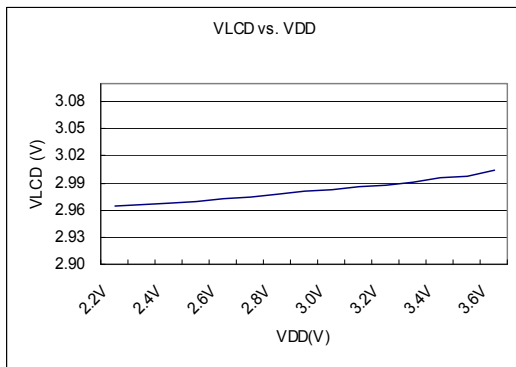


Figure6.7-3 VLCD vs. VDD

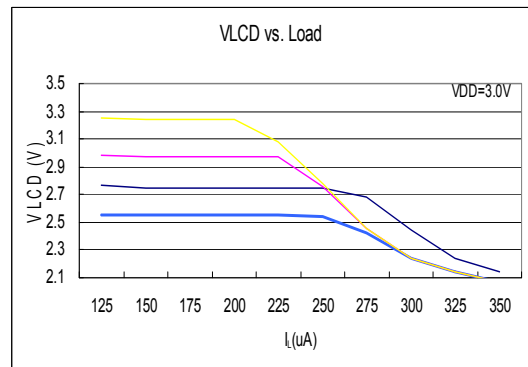


Figure6.7-4 VLCD vs. I_L @VDD=3.0V

6.8 Low Noise OPAMP 2

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=2.4\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{LNOP2}	Supply voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
I_{LNOP2}	Operation supply current		OPM2[1:0]=xxb		200		uA
V_{OS-OP}	Input offset voltage without chopper.		OPM2[1:0]=1xb	-2		2	mV
	Input offset voltage with chopper		OPM2[1:0]=0xb		20	100	uV
	Input offset voltage temperature drift.	OPM2[1:0]=00b	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$		0.1		
OPM2[1:0]=10b				2			°C
V_{OLR}	Unit gain load regulation	$V_O=1.2\text{V},$ $V_{DDA}=2.4\text{V}$	$I_L=+1\text{mA}$		0.1		% V_O
			$I_L=-1\text{mA}$				
CMVR	Common-mode voltage input range		OPM2[1:0]=xxb	0.1		$V_{DDA}-1.1$	V
CMRR	Common-mode rejection ratio		OPM2[1:0]=xxb		90		dB

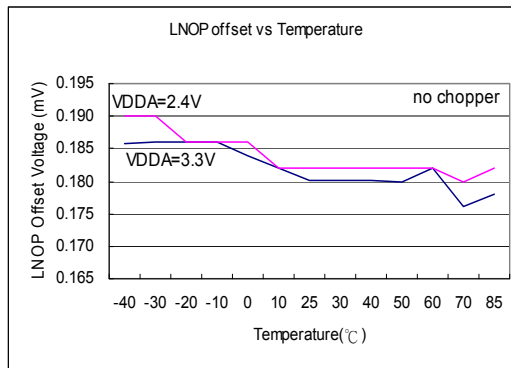


Figure 6.8-1 LNOP2 Offset Temperature

6.9 SD18, Power Supply and recommended operating conditions

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$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=2.4\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{SD18}	Supply Voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
f_{SD18}	Modulator sample frequency, ADC_CK			25	250	300	KHz
	Over Sample Ratio, OSR			128 ^{*1}		32768	
I_{SD18}	Operation supply current without PGA	ENADC[0]=1 INBUF[0]=0, VRBUF[0]=0	GAIN =4, ADC_CK=250KHz	120			μA

*1, OSR=128, setting by ADCCN3[OSR3] bit.
OSR[3:0]=1010b, OSR=128; OSR[3:0]=0xxx, OSR=256 ~ 32768
OSR[3:0]=1xxx b can't set by user

6.9.1 PGA, Power Supply and recommended operating conditions

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=2.4\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{PGA}	Supply Voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
I_{PGA}	Operation supply current	PGAGN[1:0]=<11>		320			μA
G_{PGA}	Gain temperature drift	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$	GAIN=128	15			ppm/ $^\circ\text{C}$

6.9.2 SD18, performance

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=2.4\text{V}, V_{VR}=1.0\text{V}, \text{GAIN}=1$ without PGA, $f_{SD18}=250\text{KHz}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
INL	Integral Nonlinearity(INL)	$V_{DDA}=2.4\text{V}, V_{VR}=1.0\text{V}, \Delta\text{SI}=\pm 200\text{mV}$		± 0.003		± 0.01	%FSR
		$V_{DDA}=2.4\text{V}, V_{VR}=1.0\text{V}, \Delta\text{SI}=\pm 450\text{mV}$					
	No Missing Codes ³	ADC_CK=250KHz, OSR[2:0]=010b		19			Bits
G_{SD18}	Temperature drift Gain 1~x16 (INBUF[0]=0b,)	INBUF[0]=0b, VRBUF[0]=0b	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$	10			ppm/ $^\circ\text{C}$
E_{OS}	Offset error of Full Scale Rang input voltage range with Chopper without PGA	$\Delta\text{AI}=0\text{V}$ $\Delta\text{VR}=0.9\text{V}$	Gain=2	1			%FSR
				GAIN=1	2		$\mu\text{V}/^\circ\text{C}$
	GAIN=2	1					
	GAIN=4	0.5					
	Offset error temperature drift with chopper without PGA		$\text{DCSET}[2:0]=\langle 000 \rangle$ * ΔAI is external short	GAIN=16	0.15		

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=2.4\text{V}, V_{VR}=1.0\text{V}, \text{GAIN}=1$ without PGA, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
------	-----------	-----------------	--	------	------	------	------

CM _{SD18}	Common-mode rejection	V _{CM} =0.7V to 1.7V, V _{VR} =1.0V, without PGA	V _{SI} =0V, GAIN=1	90	dB
		V _{CM} =0.7V to 1.7V, V _{VR} =1.0V, without PGA	V _{SI} =0V, GAIN=16	75	
PSRR	DC power supply rejection	V _D DA=3.0V, Δ V _D DA=±100mV, V _{VR} =1.0V, V _{SI} =1.2V, V _{SI} =1.2V,	GAIN=1 PGA=off	75	dB
			GAIN=16 PGA=8		

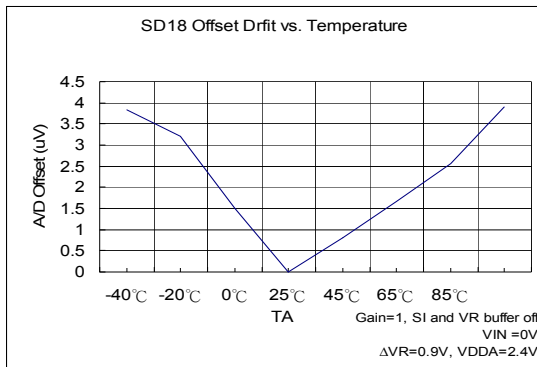


Figure 6.10-1(a) SD18 Offset Temperature drift

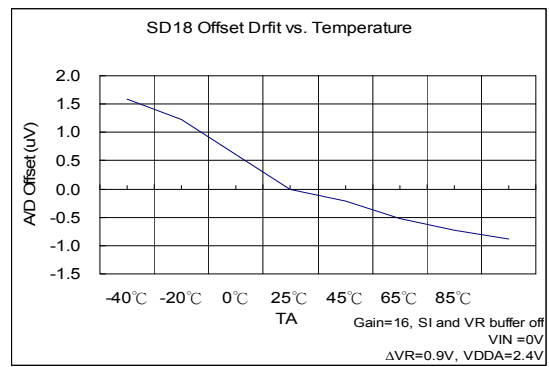


Figure 6.10-1(b) SD18 Offset Temperature drift

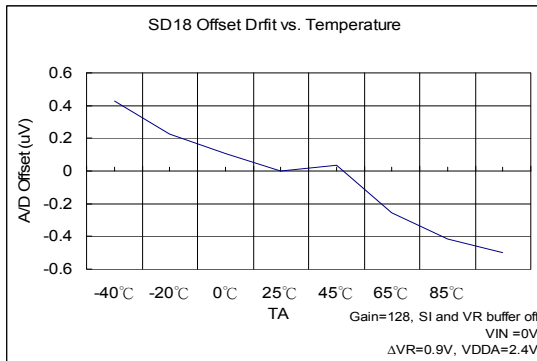


Figure 6.10-1(c) SD18 Offset Temperature drift

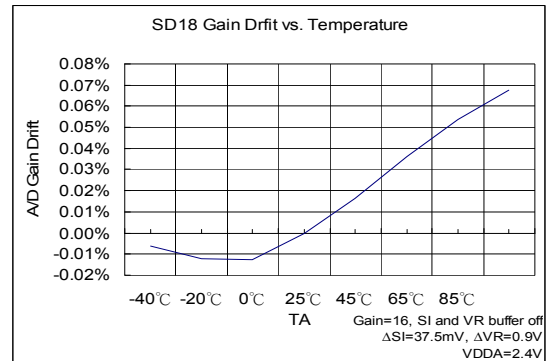


Figure 6.10-2(a) SD18 Gain drift with temperature

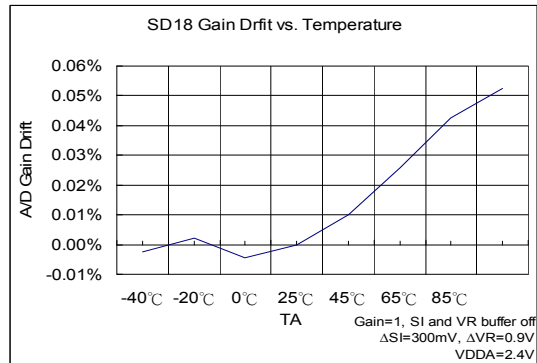


Figure 6.10-2(b) SD18 Gain drift with temperature

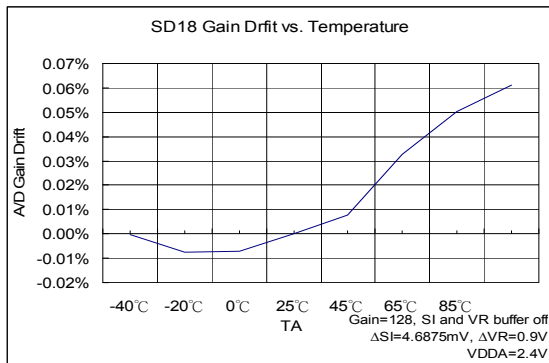


Figure 6.10-2(c) SD18 Gain drift with temperature

6.9.3 SD18 Noise Performance

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, $V_{DDA} = 2.4\text{V}$, unless otherwise noted

HY11P54 針對 SD18 提供了重要的輸入雜訊規格。Table6.8-3(a), Table6.8-3(b) 列出典型的雜訊規格表與 Gain, Output rate, 及單端最大輸入電壓等關係。測試條件設定在外部輸入訊號短路，參考電壓為 1.2V，取樣 1024 筆資料。

ENOB(RMS) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V														
Max. Vin(mV) =0.9*VREF ⁽¹⁾	OSR				128	256	512	1024	2048	4096	8192	16384	32768	
	Output rate(HZ)				1953	977	488	244	122	61	31	15	8	
	Gain	=	PGA	x										ADGN
±2400	0.25	=	1	x	0.25	14.43	16.07	17.20	17.86	18.29	18.66	18.98	19.13	19.30
±2160	0.5	=	1	x	0.5	14.34	16.05	17.13	17.84	18.26	18.62	18.90	19.13	19.27
±1080	1	=	1	x	1	14.38	16.06	17.11	17.72	18.13	18.53	18.88	19.05	19.22
±540	2	=	1	x	2	14.40	15.98	16.96	17.59	18.01	18.45	18.79	19.01	19.17
±270	4	=	1	x	4	14.39	15.88	16.82	17.39	17.85	18.28	18.65	18.95	19.13
±135	8	=	1	x	8	14.27	15.75	16.58	17.15	17.60	18.04	18.45	18.78	19.02
±68	16	=	1	x	16	14.14	15.51	16.18	16.73	17.21	17.70	18.15	18.52	18.83
±8	128	=	8	x	16	13.04	13.83	14.32	14.87	15.38	15.86	16.36	16.84	17.28

(1) Max.Vin (mV) is the max. input voltage of single end to ground (VSS).

Table6.10-3(a) SD18 ENOB Table

RMS Noise(uV) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V														
Max. Vin(mV) =0.9*VREF	OSR				128	256	512	1024	2048	4096	8192	16384	32768	
	Output rate(HZ)				1953	977	488	244	122	61	31	15	8	
	Gain	=	PGA	x										ADGN
±2400	0.25	=	1	x	0.25	362.92	139.77	64.33	40.65	30.04	23.35	18.70	16.75	14.92
±2160	0.5	=	1	x	0.5	193.22	70.82	33.83	20.60	15.37	12.00	9.86	8.38	7.61
±1080	1	=	1	x	1	94.14	35.38	17.16	11.17	8.40	6.34	5.01	4.44	3.92
±540	2	=	1	x	2	46.23	18.59	9.48	6.13	4.57	3.35	2.66	2.28	2.05
±270	4	=	1	x	4	23.37	9.98	5.20	3.51	2.54	1.89	1.46	1.18	1.05
±135	8	=	1	x	8	12.66	5.47	3.06	2.06	1.51	1.11	0.84	0.67	0.56
±68	16	=	1	x	16	6.93	3.23	2.02	1.38	0.99	0.70	0.51	0.40	0.32
±8	128	=	8	x	16	1.86	1.29	0.91	0.63	0.44	0.32	0.22	0.16	0.12

Table6.10-3(b) SD18 RMS Noise Table

The RMS noise are referred to the input. The Effective Number of Bits (ENOB(RMS Bit)) is defined as:

$$\text{ENOB(RMS)} = \frac{\ln\left(\frac{\text{FSR}}{\text{RMS Noise}}\right)}{\ln(2)}$$

$$\text{RMS Noise} = \frac{\left(2 \times \text{VREF} \times \sqrt{\sum_{k=1}^{1024} (\text{ADO}[k] - \text{Average})^2}\right)}{2^{23}}$$

Where FSR (Full - Scale Range) = $2 \times \text{VREF}/\text{Gain}$.

$$\text{Average} = \frac{\sum_{k=1}^{1024} (\text{ADO}[k])}{1024}$$

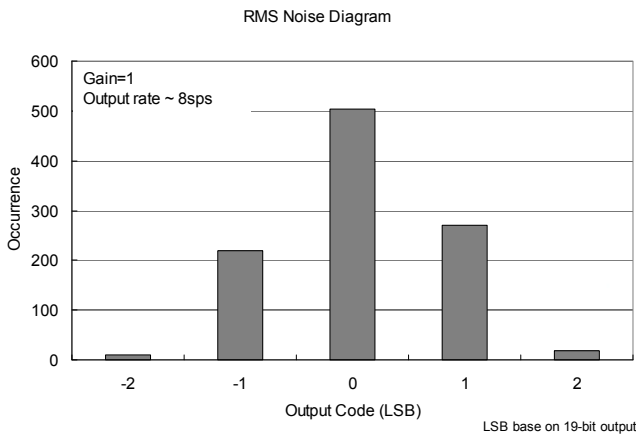


Figure6.10-3(a) RMS Noise Diagram

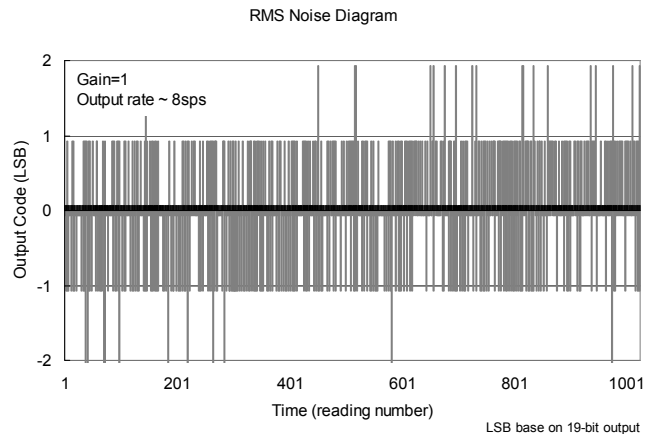


Figure6.10-3(b) Output Code Diagram

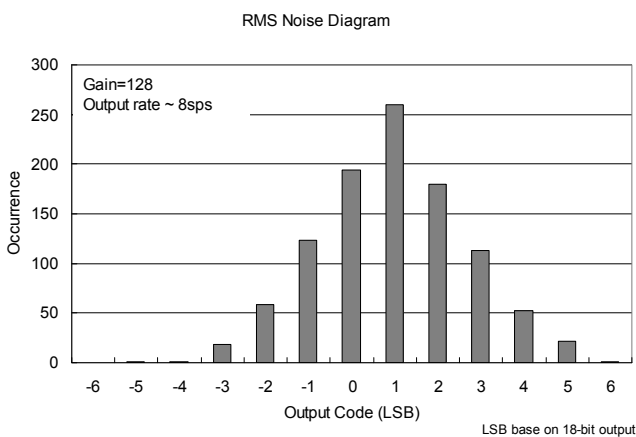


Figure6.10-3(c) RMS Noise Diagram

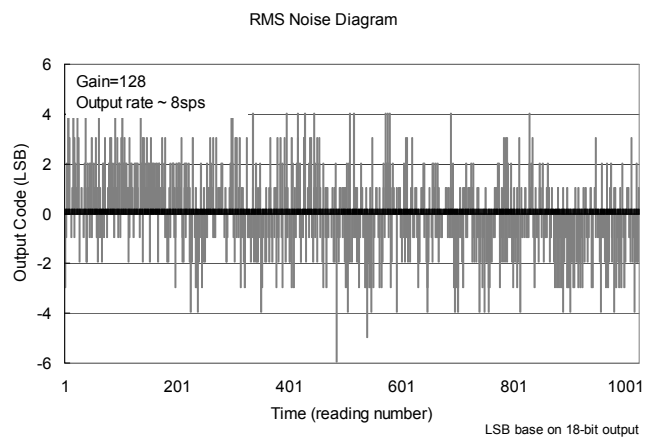


Figure6.10-3(d) Output Code Diagram

6.10 Build-In EPROM(BIE)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
V_{BIE}	Supply Voltage			6.0	6.5	V
I_{BIE}	Operation supply current			5		mA
V_{SS}	Supply Voltage			0		V

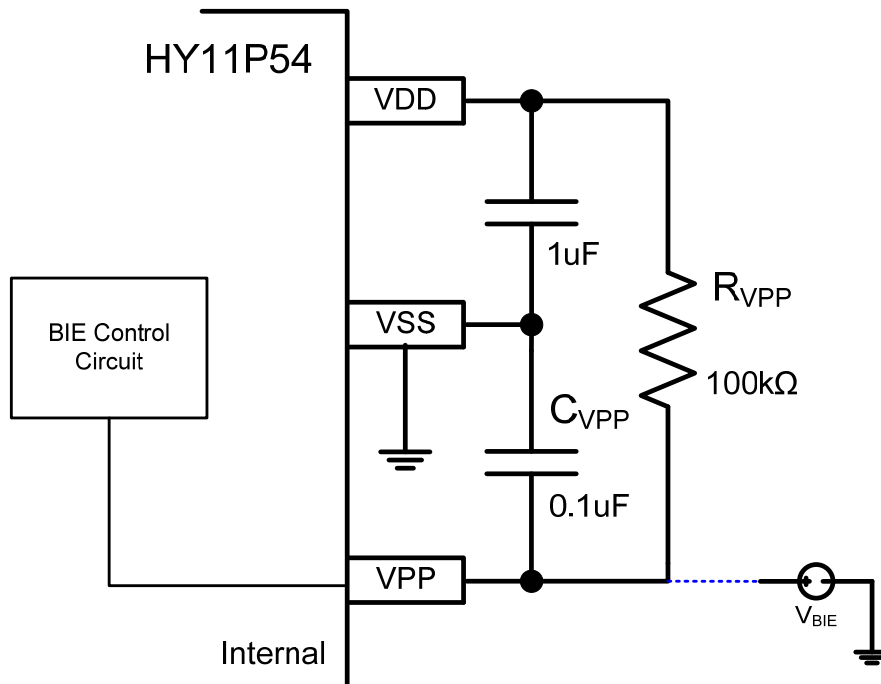
當使用外部 V_{BIE} 電源燒錄 BIE 區塊時，可以透過指令一次燒錄一個字節(word)資料於 BIE 區塊內;

6.11 Build-In EPROM(BIE) Low voltage control circuit

$T_A = 25^\circ\text{C}, V_{DD} = 3.05\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
T_O	Operation temperature range		0	25	40	$^\circ\text{C}$
V_{DD}	Operation supply Voltage		3.05		3.4	V
V_{SS}	Supply Voltage			0		V

啟動 3.05V 低壓燒錄控制電路時，則不需外接 V_{BIE} 電源仍可燒錄 BIE 區塊



BIE typical application

7. 訂貨資訊

下單品名 ¹	封裝型式	引腳數	封裝型式 描述方式		程式碼 編號 ²	出貨包裝 形式	個裝 數量	材料 組成	MSL ³
			D	000					
HY11P54-D000	Die	-	D	000	000	-	100	Green ⁴	-
HY11P54-L064	LQFP	64	L	064	000	Tray	250	Green ⁴	MSL-3
HY11P54-L100	LQFP	100	L	100	000	Tray	90	Green ⁴	MSL-3
HY11P54-NS48	QFN	48	N	S48	000	Tray	490	Green ⁴	MSL-3

¹ 產品名稱 - 封裝型式描述方式 - 程式碼編號 (空白片 / 標準品 / 代客燒錄碼)

例如：您的需求是不帶程式碼的空白片且需要的產品是裸片出貨，晶片型號為 HY11P54。則下單品名為 HY11P54-D000

例如：您的代客燒錄服務申請的程式碼編號為 008，晶片型號為 HY11P54，且需要的產品是裸片出貨。則下單品名為 HY11P54-D000-008

例如：您的需求是晶片型號為 HY11P54，不帶程式碼的空白片且需要的產品是封裝片 LQFP100 出貨，則下單品名為 HY11P54-L100，且需以 Tray 出貨，則除下單品名外，請特別註明出貨包裝形式為 Tray

例如：您的需求是晶片型號為 HY11P54，代客燒錄服務申請的程式碼編號為 009，而需求的產品是封裝片 LQFP100 出貨，則下單品名為 HY11P54-L100-009，且需以 Tray 出貨，則除下單品名外，請特別註明出貨包裝形式為 Tray

² 程式碼編號

“001”~“999” 為標準品或代客燒錄申請的程式碼編號，而空白晶片不帶此碼。

³ MSL:

濕度敏感性等級係依據 IPC/JEDEC J-STD-020 的規範加以試驗分級，並參考 IPC/JEDEC J-STD-033 的標準處理、包裝、運輸與使用。

⁴ Green (RoHS & no Cl/Br):

HYCON 產品皆為 Green Product，符合 RoHS 指令以及無鹵素規定(Br/Cl<0.1%)

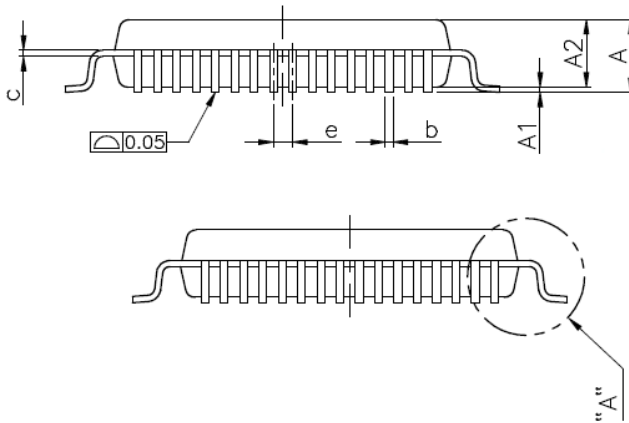
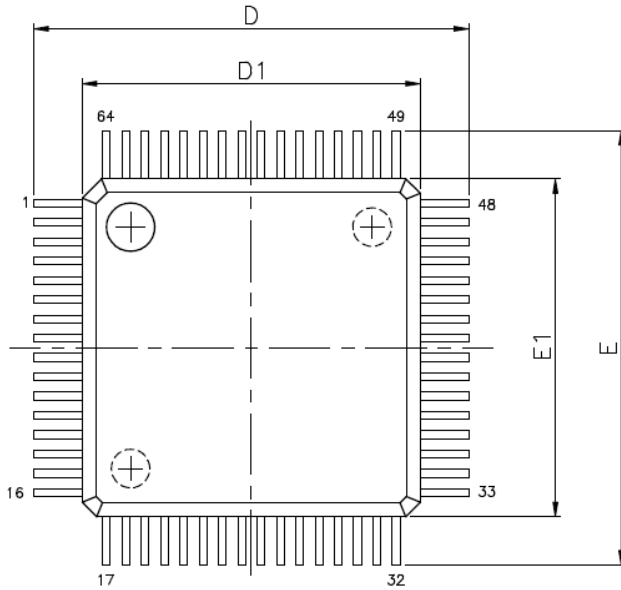
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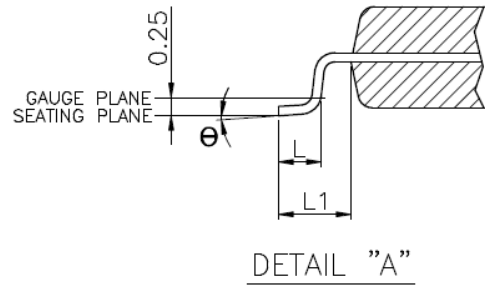
8. 封裝型式資訊

8.1 LQFP64(L064)



VARIATIONS (ALL DIMENSIONS SHOWN IN MM)

SYMBOLS	MIN.	NOM.	MAX.
A	—	—	1.60
A1	0.05	—	0.15
A2	1.35	1.40	1.45
b	0.13	0.18	0.23
c	0.09	—	0.20
D	9.00 BSC		
D1	7.00 BSC		
e	0.40 BSC		
E	9.00 BSC		
E1	7.00 BSC		
L	0.45	0.60	0.75
L1	1.00 REF		
θ	0°	3.5°	7°

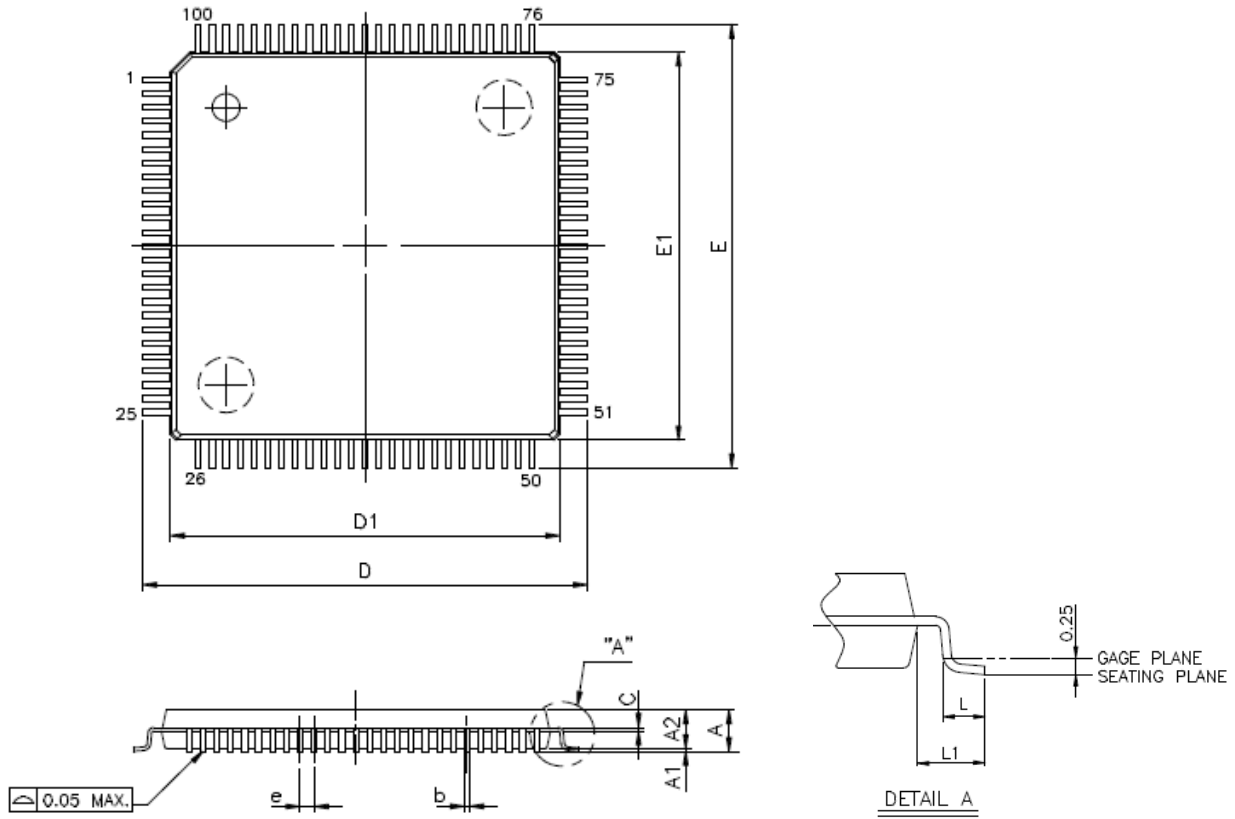


JEDEC MS-026 compliant

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Embedded 18-Bit $\Sigma\Delta$ ADC
8-Bit RISC-like Mixed Signal Microcontroller

8.2 LQFP100(L100)



SYMBOLS	MIN.	NOM.	MAX.
A	--	--	1.60
A1	0.05	--	0.15
A2	1.35	1.40	1.45
b	0.17	0.20	0.27
c	0.09	0.127	0.20
D	16.00 BSC		
D1	14.00 BSC		
E	16.00 BSC		
E1	14.00 BSC		
e	0.50 BSC		
L	0.45	0.60	0.75
L1	1.00 REF		

Note:

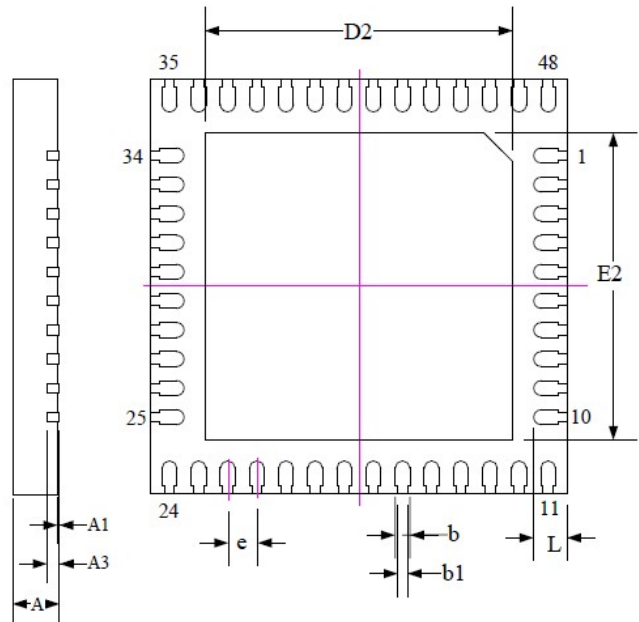
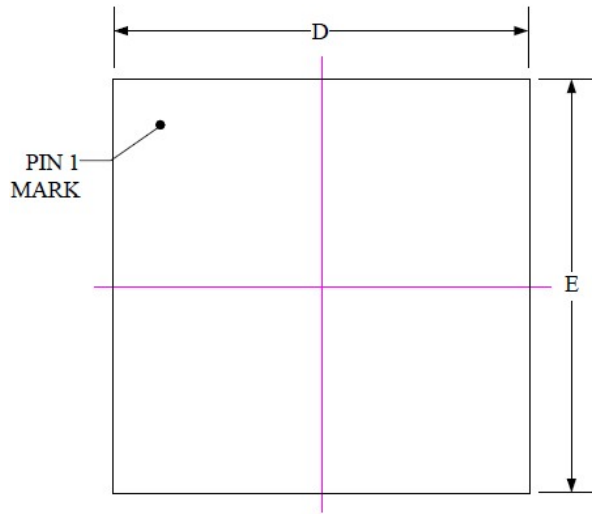
1. All dimensions refer to JEDEC OUTLINE MS-026.
2. Do not include Mold Flash or Protrusions.

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Embedded 18-Bit $\Sigma\Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

8.3 QFN48(NS48)



SYMBOLS	MIN	NOM	MAX
A	0.50	0.55	0.60
A1	0.00	0.02	0.05
A3	0.15 REF.		
b	0.13	0.18	0.23
b1	0.07	0.12	0.17
D	5.00 BSC		
E	5.00 BSC		
D2	3.65	3.70	3.75
E2	3.65	3.70	3.75
L	0.35	0.40	0.45
e	0.35 BSC		

9. 修訂記錄

以下描述本文件差異較大的地方，而標點符號與字形的改變不在此描述範圍。

版本	頁次	變更摘要
V01	ALL	初版發行
V02	ALL	調整 LQFP100 封裝引腳與增加 LQFP64 封裝型號
V03	ALL	調整規格內容
V04	15 27	暫存器列表新增 INTE2[7:6]=TXIE, RCIE, INTF2[7:6]=TXIF, RCIF。 新增 Low Noise OPAMP 2 規格。
V05	4 7 13 34 37	新增 HY11P54-NS48 說明，修正 HY11P54-L100、HY11P54-L064 ADC Channel 數。 新增 HY11P54 QFN48 引腳圖。 於內部方塊圖內新增 Interface(EUART)。 新增 HY11P54-NS48 訂貨資訊。 新增 QFN48 封裝型式資訊。
V06	34	修改訂貨資訊，HY11P54-D000 的各裝數量為 100。
V07	3,4,34,37	QFN 系列封裝代碼變更，N048 更改為 NS48。